

SCS5107 Computational Intelligence Unit V

Fuzzy Systems

CLASSICAL PROPOSITION LOGIC

As in our ordinary informal language, a **sentence** is used in the logic. Especially, a sentence having only ^atrue (1)^o or ^afalse (0)^o as its truth value is called **proposition**.

$2 + 4 = 7$ (false)

For every x , if $f(x) = \sin x$, then $f'(x) = \cos x$. (true) .It rains now. (true or false depending whether it rains or not)

Connectives - combine propositional variables .

Negation, Conjunction, Disjunction ,Implication

What does it mean if p implies q ? Example: p = sky is overcast, q = sun not visible, $p \rightarrow q$

p	q	$\neg p$	$p \vee q$	$p \wedge q$	$p \rightarrow q$
T	T	F	T	T	T
T	F	F	T	F	F
F	T	T	T	F	T
F	F	T	F	F	T

<i>p</i>	<i>q</i>	<i>p</i> \rightarrow <i>q</i>
<i>T</i>	<i>T</i>	<i>T</i>
<i>T</i>	<i>F</i>	<i>F</i>
<i>F</i>	<i>T</i>	<i>T</i>
<i>F</i>	<i>F</i>	<i>T</i>

LOGIC FUNCTIONS

Logic function : a combination of propositional variables by using connectives

Logic formula : Truth values 0 and 1 are logic formulas

- If *v* is a logic variable, *v* and *v'* are a logic formulas
- If *a* and *b* represent a logic formulas,

TAUTOLOGY AND INFERENCE RULE

Tautology : A ^atautology^o is a logic formula whose value is always true regardless of its logic variables. A ^acontradiction^o is one which is always false.

a	b	$a \rightarrow b$	$\overline{(a \rightarrow b)}$	\bar{b}	$\overline{(a \rightarrow b)} \rightarrow \bar{b}$
1	1	1	0	0	1
1	0	0	1	1	1
0	1	1	0	0	1
0	0	1	0	1	1

TAUTOLOGY AND INFERENCE RULE

a	b	$(a \rightarrow b)$	$(a \wedge (a \rightarrow b))$	$(a \wedge (a \rightarrow b)) \rightarrow b$
1	1	1	1	1
1	0	0	0	1
0	1	1	0	1
0	0	1	0	1

Predicate logic :

“Predicate logic” is a logic which represents a proposition with the predicate and an individual (object)

“Socrates is a man”

“Socrates” – object

“is a man” – predicate

“Two is less than four”

“Two”, “four” – objects

“is less than” - predicate

Objects in predicate logic can be represented by variables. Then a predicate proposition can be evaluated for truth if an element of a universal set is instantiated to the variable.

“x is a man”

x=“Tom”, the proposition becomes “Tom is a man”

“x satisfies P” can be denoted P(x)
is_a_man(Tom)

FUZZY SETS

Definition: let X be a non-empty set and be called the universe of discourse. A fuzzy set $A \subset X$ is characterized by the membership function

where $\mu_A(x)$ is a grade (degree) of membership of x in set A .

$$\mu_A : X \rightarrow [0,1]$$

FUZZY SETS

Definition of fuzzy sets:

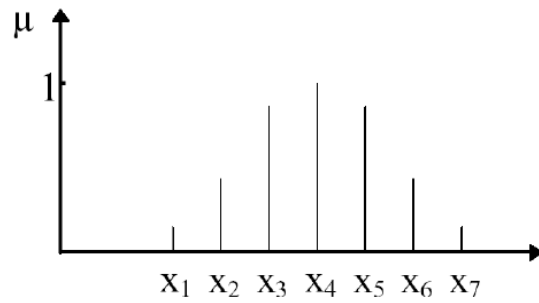
Fuzzy set A can be represented as a set of ordered pairs

$$A = \{(x, \mu_A(x)) \mid x \in X\}$$

FUZZY SETS

Discrete example:

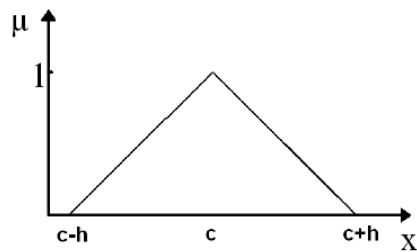
$$\mu_A = 0.1/x_1 + 0.4/x_2 + 0.8/x_3 + 1.0/x_4 + 0.8/x_5 + 0.4/x_6 + 0.1/x_7$$



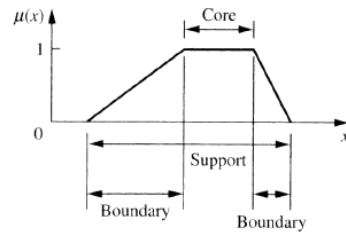
FUZZY SETS

Continuous example:

$$\mu_A(x) = \begin{cases} 1 + \frac{x-c}{h}, & x \in [c-h, c] \\ 1 - \frac{x-c}{h}, & x \in [c, c+h] \\ 0, & \text{otherwise} \end{cases}$$



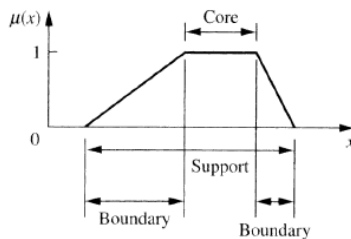
PROPERTIES OF FUZZY SETS



Support : support of a fuzzy set A is a crisp set that contains all elements of A with non-zero membership grade:

$$\text{supp}(A) = \{x \in X | \mu_A(x) > 0\}$$

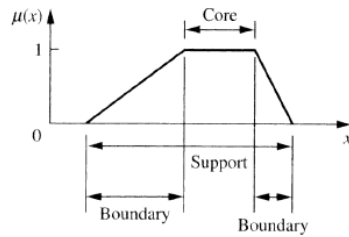
PROPERTIES OF FUZZY SETS



Core: comprises those elements x of the universe such that $\mu_A(x) = 1$.

$$\text{core}(A) = \{x \in X | \mu_A(x) = 1\}$$

PROPERTIES OF FUZZY SETS



Boundary : boundaries comprise those elements x of the universe such that $0 < \mu_A(x) < 1$

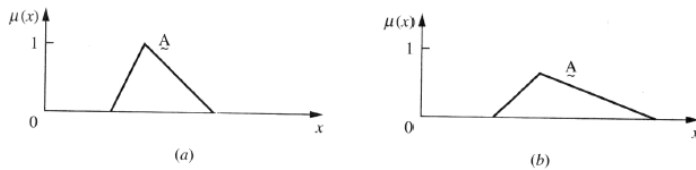
$$\text{bnd}(A) = \{x \in X \mid 0 < \mu_A(x) < 1\}$$

PROPERTIES OF FUZZY SETS

Height : the height of a fuzzy set A is defined

$$\text{hgt}(A) = \sup_{x \in X} \mu_A(x)$$

Set A is called normal if $\text{hgt}(A)=1$
and subnormal if $\text{hgt}(A)<1$



Fuzzy sets that are normal (a) and subnormal (b).

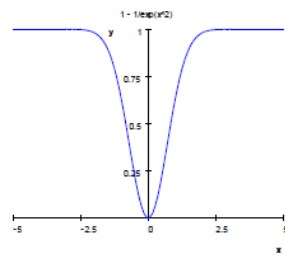
PROPERTIES OF FUZZY SETS

Question?

Is the fuzzy set defined as

$$\mu_A(x) = 1 - 1/e^{-x^2}$$

Normal or subnormal?

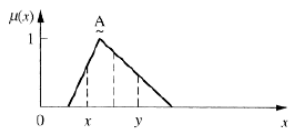


PROPERTIES OF FUZZY SETS

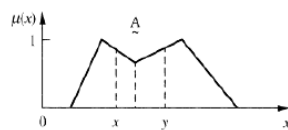
Convex Fuzzy set: a fuzzy set A is convex iff

$$\forall x, y \in X \text{ and } \forall \lambda \in [0,1]$$

$$\mu_A(\lambda x + (1-\lambda)y) \geq \min(\mu_A(x), \mu_A(y))$$



Convex, normal fuzzy set



Non convex, normal fuzzy set

OPERATIONS ON FUZZY SETS

1. Empty set

$$\mu_{\emptyset} \equiv 0$$

2. Basic set (universe)

$$\mu_X \equiv 1$$

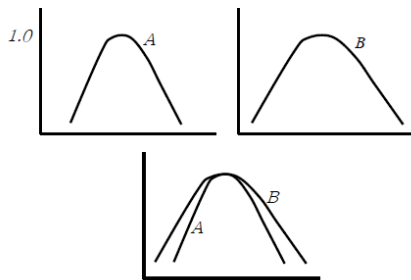
3. Identity

$$A = B \Leftrightarrow \mu_A(x) = \mu_B(x) \quad \forall x \in X$$

OPERATIONS ON FUZZY SETS

4. Subset

$$A \subset B \Leftrightarrow \mu_A(x) \leq \mu_B(x) \quad \forall x \in X$$

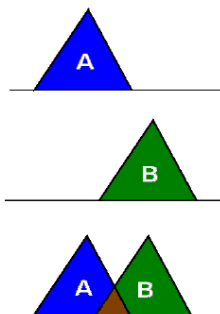


OPERATIONS ON FUZZY SETS

5. Union

$$U[\mu_A, \mu_B] = \max[\mu_A, \mu_B],$$

$$\forall x \in X : \mu_{A \cup B}(x) = \max(\mu_A(x), \mu_B(x))$$



OPERATIONS ON FUZZY SETS

6. Intersection

Axioms for intersection function

$$I: [0,1] \times [0,1] \rightarrow [0,1] \quad \mu_{A \cap B}(x) = I[\mu_A(x), \mu_B(x)]$$

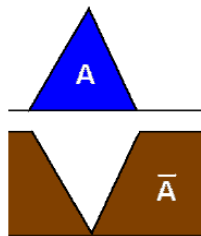
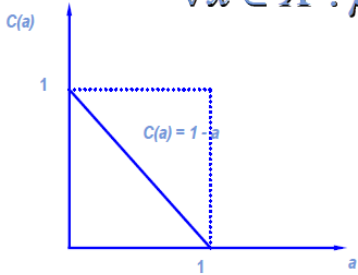
- $I(1, 1) = 1, I(1, 0) = 0, I(0, 1) = 0, I(0, 0) = 0$
- $I(a, b) = I(b, a)$, Commutativity.
- If $a \leq a'$ and $b \leq b'$, $I(a, b) \leq I(a', b')$, monotonicity.
- $I(I(a, b), c) = I(a, I(b, c))$, Associativity.
- I is a continuous function.
- $I(a, a) = a$, idempotency.

7. Complement

Standard complement function:

$$C(a) = 1 - a$$

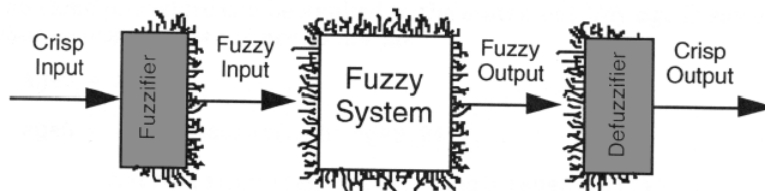
$$\forall x \in X : \mu_{\bar{A}}(x) = 1 - \mu_A(x)$$



Properties of fuzzy operations:

- (1) Involution $\overline{\overline{A}} = A$
- (2) Commutativity $A \cup B = B \cup A$
 $A \cap B = B \cap A$
- (3) Associativity $(A \cup B) \cup C = A \cup (B \cup C)$
 $(A \cap B) \cap C = A \cap (B \cap C)$
- (4) Distributivity $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$
 $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$
- (5) Idempotency $A \cup A = A$
 $A \cap A = A$
- (6) Absorption $A \cup (A \cap B) = A$
 $A \cap (A \cup B) = A$
- (7) Absorption by X and \emptyset $A \cup X = X$
 $A \cap \emptyset = \emptyset$
- (8) Identity $A \cup \emptyset = A$
 $A \cap X = A$
- (9) De Morgan's law $\overline{A \cap B} = \overline{A} \cup \overline{B}$
 $\overline{A \cup B} = \overline{A} \cap \overline{B}$
- (10) Equivalence formula $(\overline{A} \cup B) \cap (A \cup \overline{B}) = (\overline{A} \cap \overline{B}) \cup (A \cap B)$
- (11) Symmetrical difference formula $(\overline{A} \cap B) \cup (A \cap \overline{B}) = (\overline{A} \cup \overline{B}) \cap (A \cup B)$

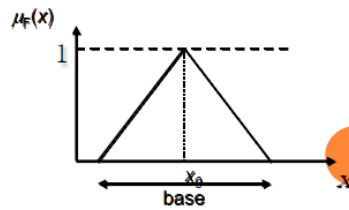
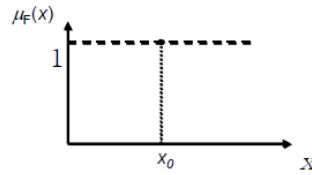
Fuzzy System



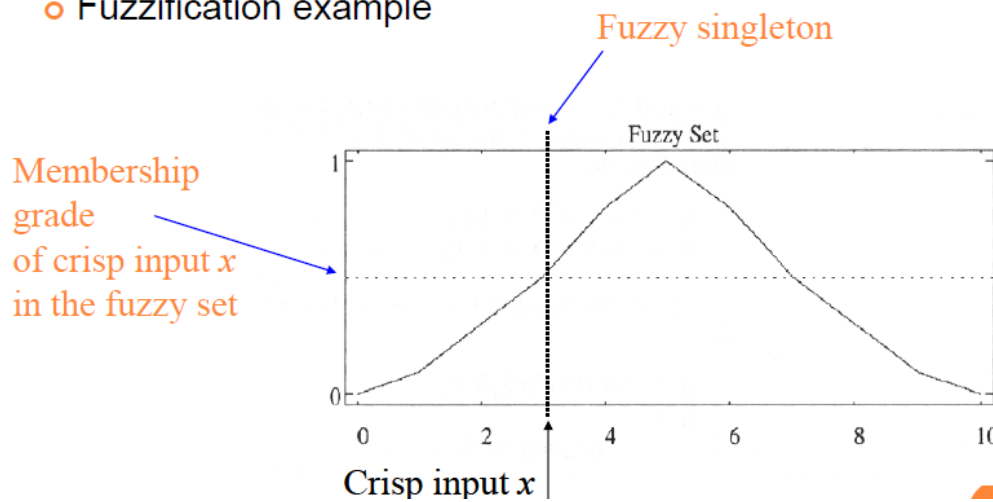
- * Fuzzify crisp inputs to get the fuzzy inputs
- * Defuzzify the fuzzy outputs to get crisp outputs

FUZZIFICATION

- Process of making a crisp quantity fuzzy
- If it is assumed that input data do not contain noise or vagueness, a fuzzy singleton can be used
- If the data are vague or perturbed by noise, they should be converted into a fuzzy number



- Fuzzification example



BUILD A FUZZY CONTROLLER

3 Steps

1. Pick the linguistic variables
 - Example: Let temperature (X) be input and motor speed (Y) be output
2. Pick the fuzzy sets
 - Define fuzzy subsets of the X and Y
3. Pick the fuzzy rules
 - Associate output to the input

EXAMPLE: BUILD A FUZZY CONTROLLER

Goal: Design a motor speed controller for air conditioner

Step 1: assign input and output variables

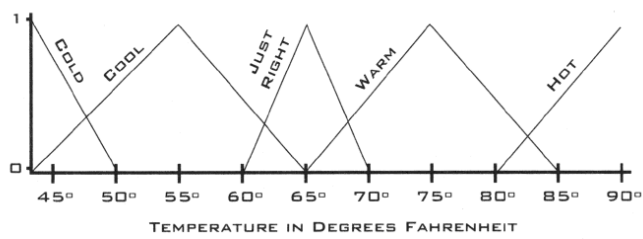
- Let X be the temperature in Fahrenheit
- Let Y be the motor speed of the air conditioner

Step 2: Pick fuzzy sets

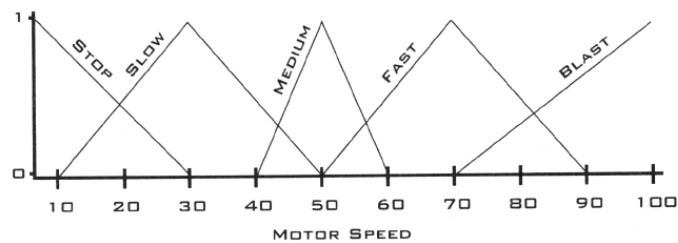
Define linguistic terms of the linguistic variables temperature (X) and motor speed (Y) and associate them with fuzzy sets

- For example, 5 linguistic terms / fuzzy sets on X
 - Cold, Cool, Just Right, Warm, and Hot
- Say 5 linguistic terms / fuzzy sets on Y
 - Stop, Slow, Medium, Fast, and Blast

Input Fuzzy sets



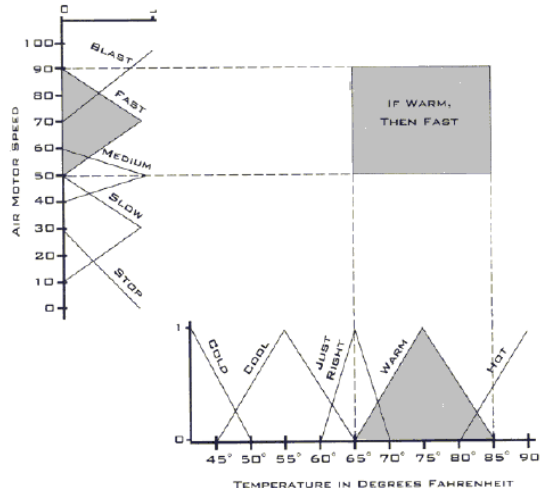
Output Fuzzy sets



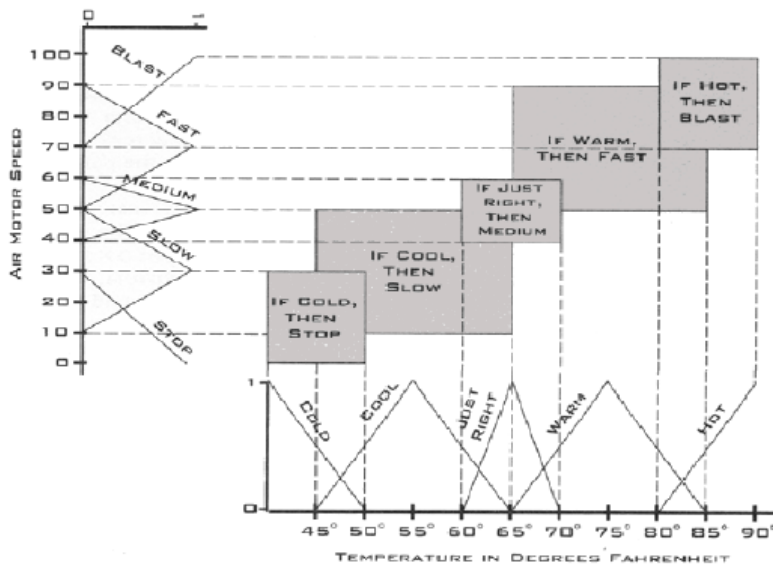
Step 3: Assign a motor speed set to each temperature set

- If temperature is ***cold*** then motor speed is **stop**
- If temperature is ***cool*** then motor speed is **slow**
- If temperature is ***just right*** then motor speed is **medium**
- If temperature is ***warm*** then motor speed is **fast**
- If temperature is ***hot*** then motor speed is **blast**

- › A Fuzzy Relation expressed by a rule



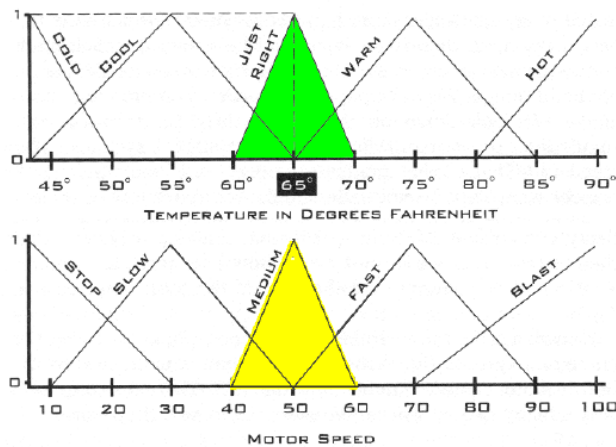
A Fuzzy controller with 5 patches



In Mamdani and Larsen model, which rule “fires” or activates at which time?

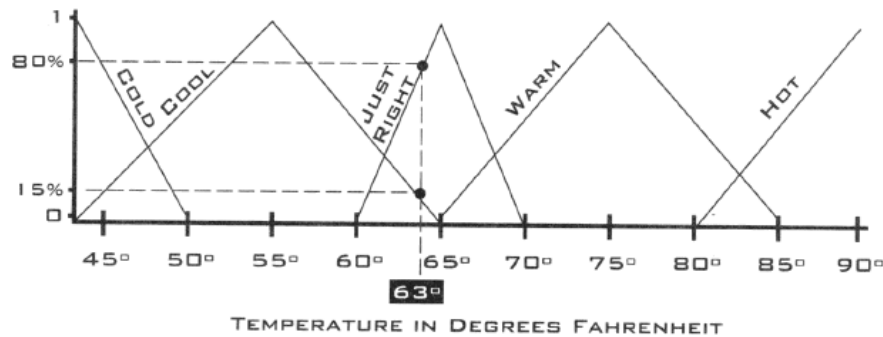
- They all fire all the time
- They fire in parallel
 - All rules fire to some degree
 - Most fire to zero degree
- The result is a union of fuzzy results from each rule

IF TEMPERATURE IS JUST RIGHT THEN MOTOR SPEED IS MEDIUM

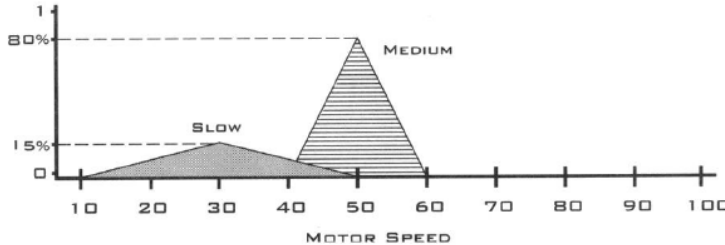
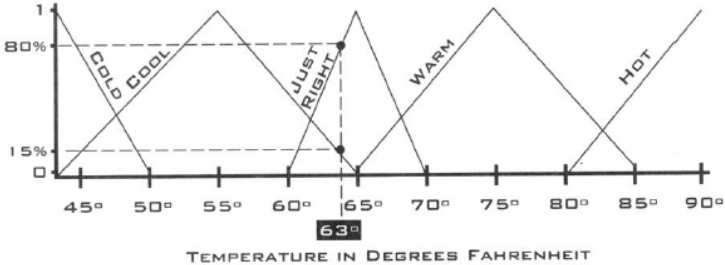


If temperature is cool then motor speed is slow

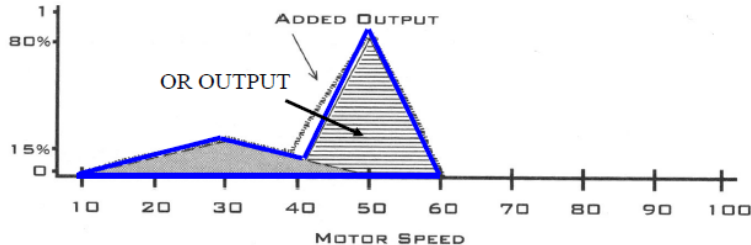
If temperature is just right then motor speed is medium



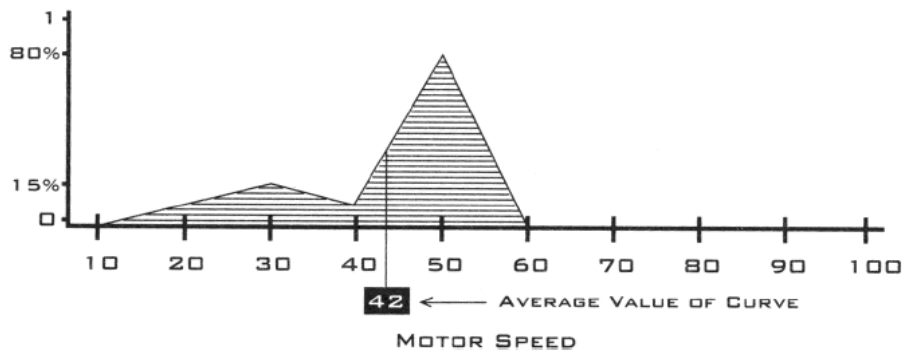
EXAMPLE: T = 63 DEGREE F.



Summed (MAXed) of the partially fired then-part fuzzy sets

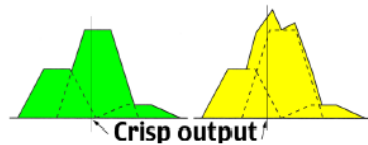


Defuzzify to find the output motor speed



Question: how to convert a fuzzy set into a crisp value?

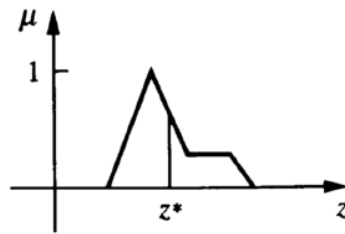
DEFUZZIFICATION



- Converts a fuzzy set into a crisp output.
- Defuzzification is a process to get a non-fuzzy value that best represents the possibility distribution of an inferred fuzzy control action.
- There is no systematic procedure for choosing a good defuzzification strategy.
- Selection of defuzzification procedure depends on the properties of the application.

DEFUZZIFICATION

- Centroid of the Area: the most prevalent and physically appealing of all the defuzzification methods [Sugeno, 1985; Lee, 1990]



- A disadvantage: computationally intensive

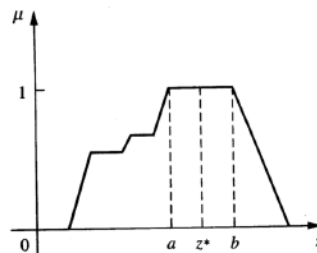
$$z^* = \frac{\int \mu_C(z) \cdot z \, dz}{\int \mu_C(z) \, dz}$$

where \int denotes an algebraic integration.

- Mean of maximum (MOM)

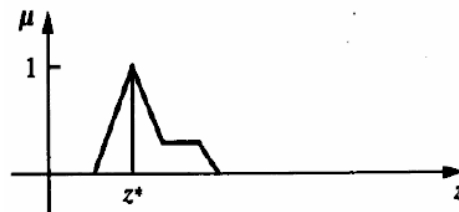
$$z_0 = \sum_{j=1}^k \frac{z_j}{k}$$

The defuzzified result represents the mean value of all actions, whose membership functions reach the maximum



z_j : control action whose membership functions reach the max
 k : number of such control actions.

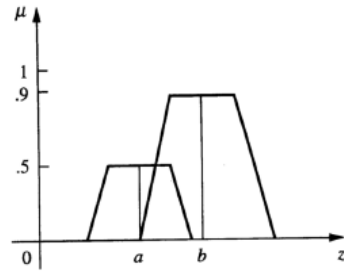
Max-membership principal, also known as height method



$$\mu_C(z^*) \geq \mu_C(z) \quad \text{for all } z \in Z$$

Weighted average method

- Valid for symmetrical output membership functions
- Produces results very close to the COA method
- Less computationally intensive

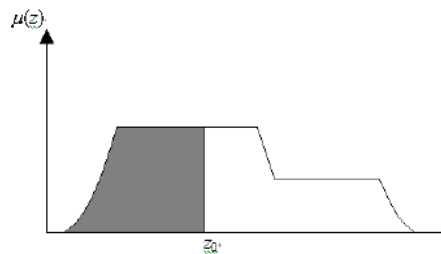


$$z^* = \frac{\sum \mu_C(\bar{z}) \cdot \bar{z}}{\sum \mu_C(\bar{z})} \quad z^* = \frac{a(.5) + b(.9)}{.5 + .9}$$

Formed by weighting each functions in the output by its respective maximum membership value

Bisector of the Area

- The BOA generates the action (z_0) which partitions the area into two regions with the same area



$$\int_{\alpha}^{z_0} \mu_C(z) dz = \int_{z_0}^{\beta} \mu_C(z) dz$$

$$\alpha = \min\{z \mid z \in W\}$$

$$\beta = \max\{z \mid z \in W\}$$

First (or last) of maxima

- Determine the smallest value of the domain with maximized membership degree

