

UNIT II SIGNALS & ERRORS

Analog and digital signals – Encoding and modulation – Parallel and serial transmission – DTE/DCE – Types of errors – Error detection and correction – Data link control – Line discipline – Flow control – Error control.

INTRODUCTION

Computer networks are designed to transfer data from one point to another. During transit data is in the form of electromagnetic signals. Hence it is important to study data and signals before we move to further concepts in data communication.

DATA & SIGNALS

To be transmitted, data must be transformed to electromagnetic signals.

Signals

Information can be in the form of data, voice, picture, and so on. To be transmitted, information must be transformed into electromagnetic signals.

Data can be Analog or Digital.

1. **Analog data** refers to information that is continuous; ex. sounds made by a human voice
2. **Digital data** refers to information that has discrete states. Digital data take on discrete values.

For example, data are stored in computer memory in the form of 0s and 1s

Signals can be of two types:

1. **Analog Signal:** They have infinite values in a range.
2. **Digital Signal:** They have limited number of defined values

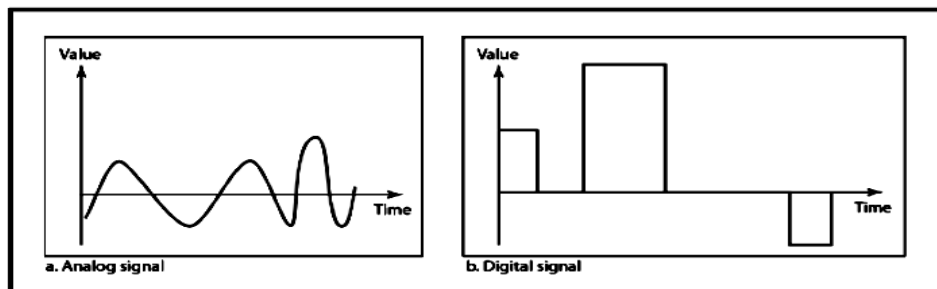


Figure: a. Analog Signal b. Digital Signal*
Periodic & Non Periodic Signals

Signals which repeat itself after a fixed time period are called Periodic Signals. Signals which do not repeat itself after a fixed time period are called Non-Periodic Signals. In data communications, we commonly use periodic analog signals and non-periodic digital signals.

ANALOG SIGNAL

An analog signal has infinitely many levels of intensity over a period of time.

As the wave moves from value A to value B, it passes through and includes an infinite number of values along its path as it can be seen in the figure below.

A simple analog signal is a sine wave that cannot be further decomposed into simpler signals.

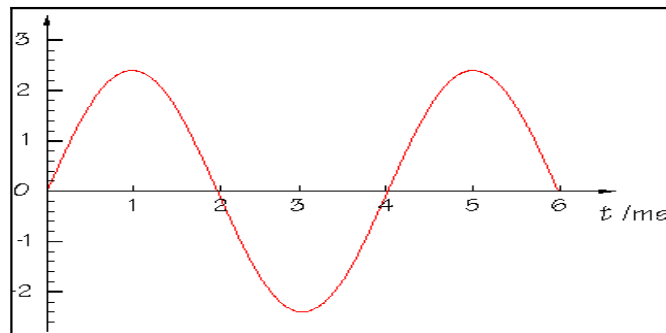


Fig. Sine wave

A sine wave is characterized by three parameters:

1. Peak Amplitude
2. Frequency
3. Phase

Characteristics of an Analog Signal

Peak Amplitude

The amplitude of a signal is the absolute value of its intensity at time t

The peak amplitude of a signal is the absolute value of the highest intensity.

The amplitude of a signal is proportional to the energy carried by the signal

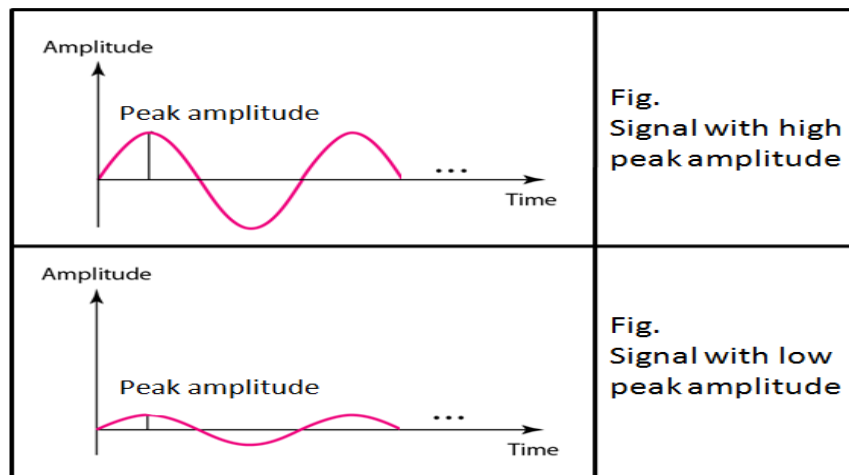


Fig. Amplitude of a sine wave

Frequency

Frequency refers to the number of cycles completed by the wave in one second.

Period refers to the time taken by the wave to complete one second.

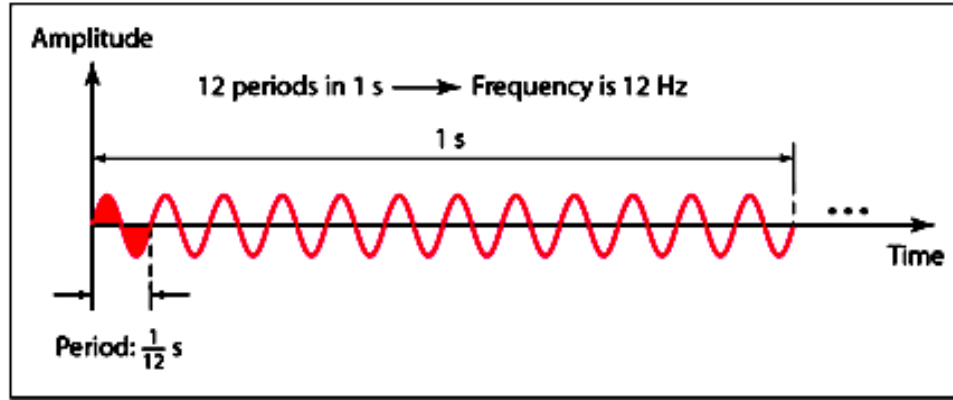


Fig: Frequency & Period of a sine wave

Phase

Phase describes the position of the waveform with respect to time (specifically relative to time 0).

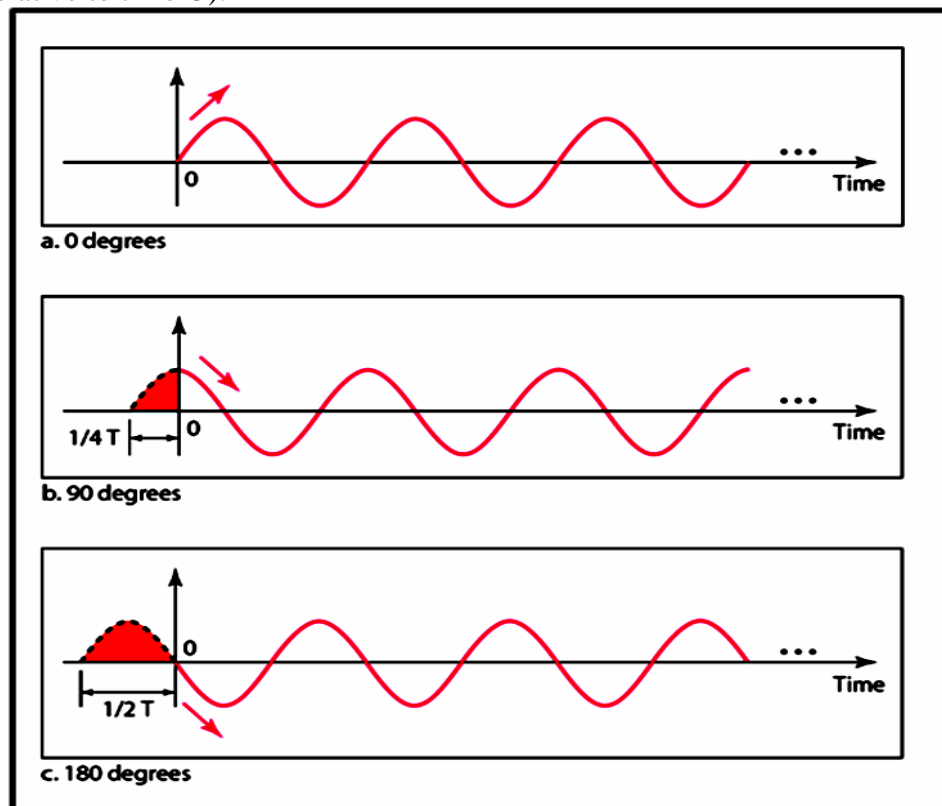
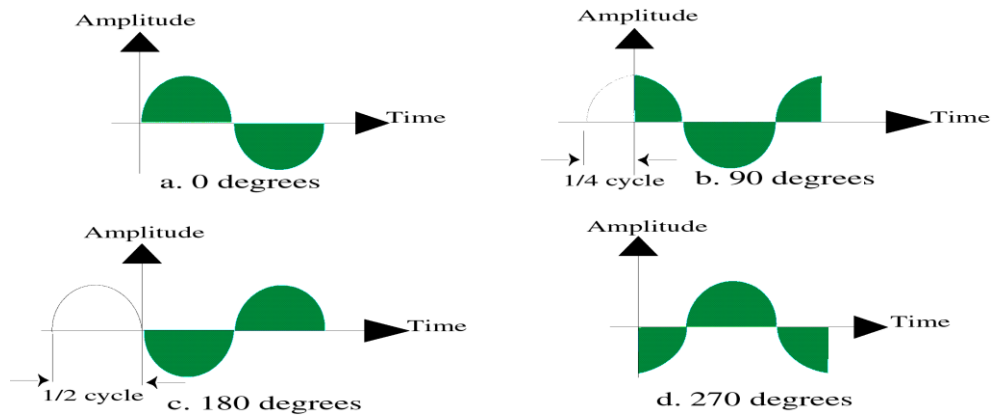
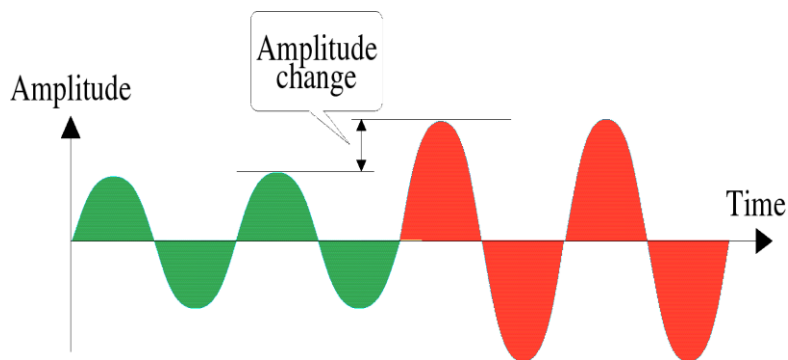


Fig: Phase of a sine wave*

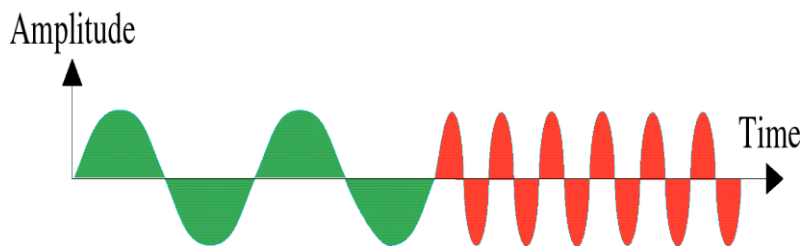
Phase indicates the forward or backward shift of the waveform from the axis. It is measured in degrees or radian. The figure above shows the sine waves with same amplitude and frequency but different phases.



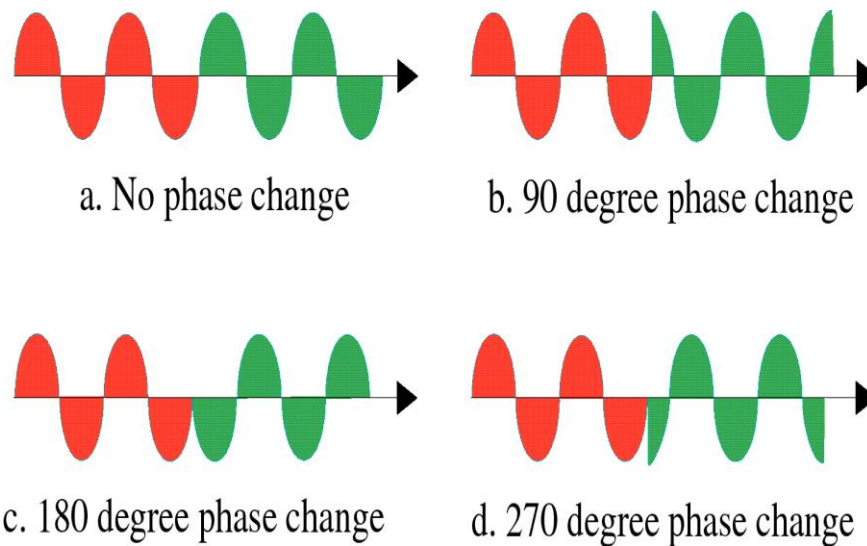
Amplitude Change



Frequency Change



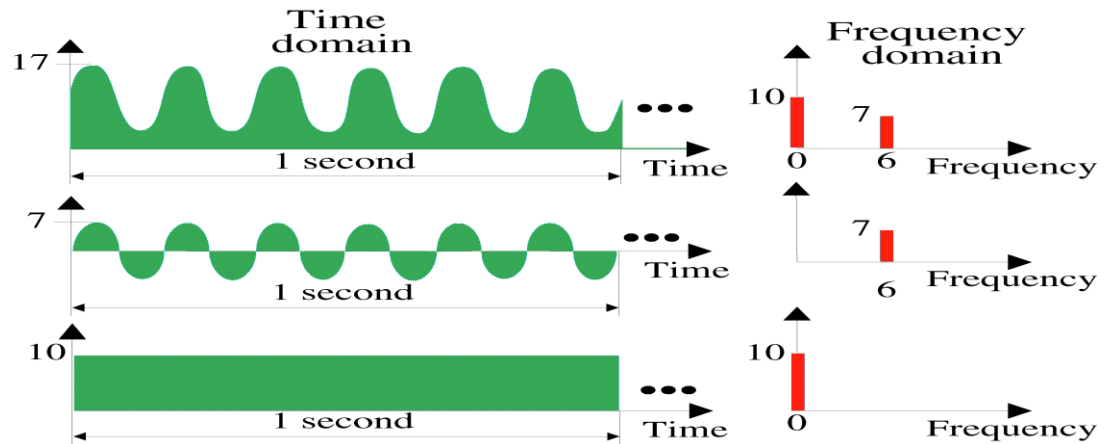
Phase Change



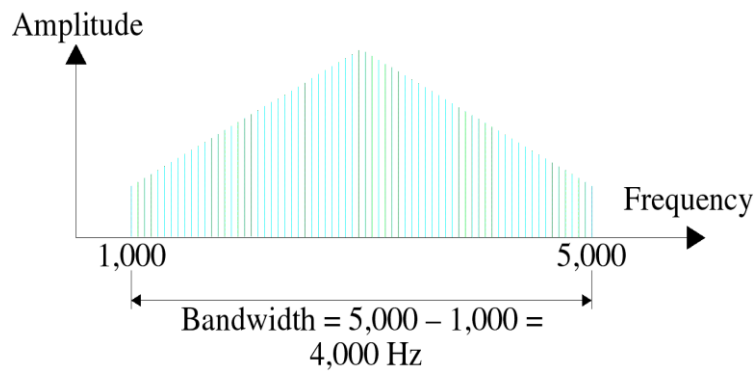
Composite signals

To decompose a composite signal into its components, Fourier analysis is needed.

Signal with DC Component



Bandwidth



Relation between Frequency & Period

Frequency & Period are inverse of each other.

It is indicated by the following formula:

$$T = 1/f$$

Or

$$f = 1/T$$

Example1. A wave has a frequency of 100hz. Its period(T) is given by

$$T = 1/ F = 1/ 100 = 0.01 \text{ sec}$$

Example2. A wave completes its one cycle in 0.25 seconds. Its frequency is given by

$$F = 1 / T = 1 / 0.25 = 4 \text{ Hz}$$

Wavelength

The wavelength of a signal refers to the relationship between frequency (or period) and propagation speed of the wave through a medium.

The wavelength is the distance a signal travels in one period.

It is given by

$$\text{Wavelength} = \text{Propagation Speed} \times \text{Period}$$

OR

$$\text{Wavelength} = \text{Propagation Speed} \times \frac{1}{\text{Frequency}}$$

It is represented by the symbol : λ (pronounced as lamda)

It is measured in micrometers

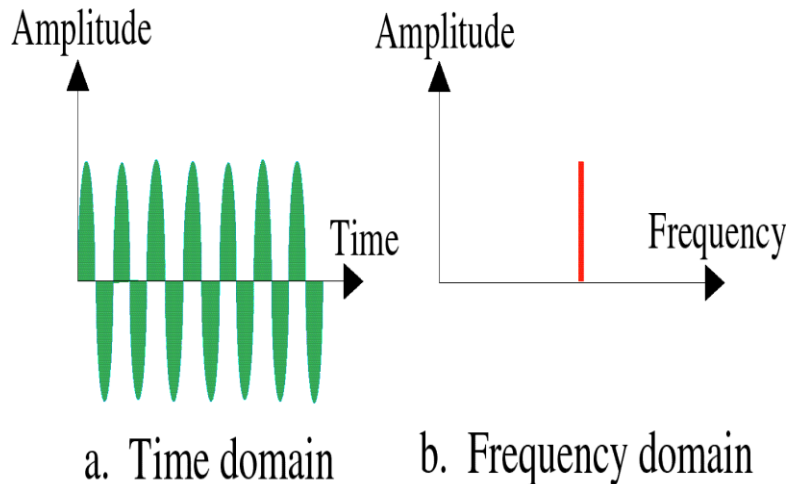
It varies from one medium to another.

Time Domain and Frequency domain representation of signals

A sine wave can be represented either in the time domain or frequency domain. The **time-domain plot** shows changes in signal amplitude with respect to time. It indicates time and amplitude relation of a signal.

The **frequency-domain plot** shows signal frequency and peak amplitude. The figure below show time and frequency domain plots of three sine waves.

Time and Frequency Domain



Time and frequency domains for different signals

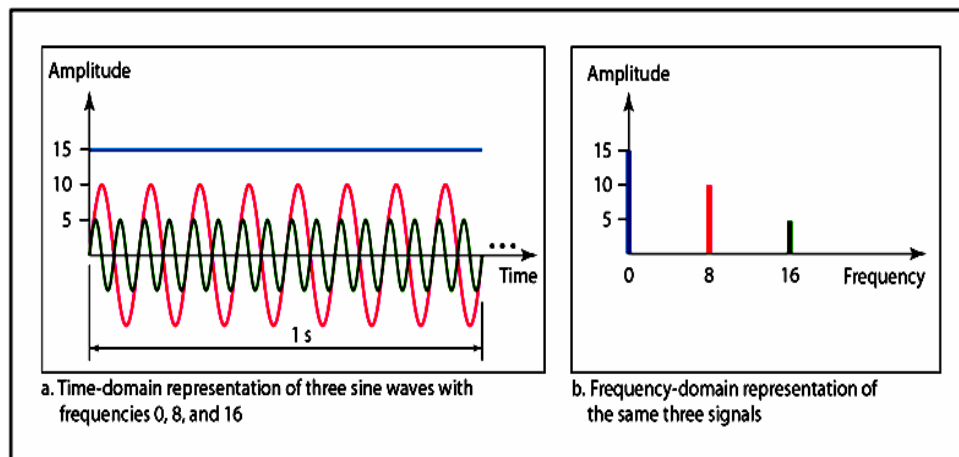
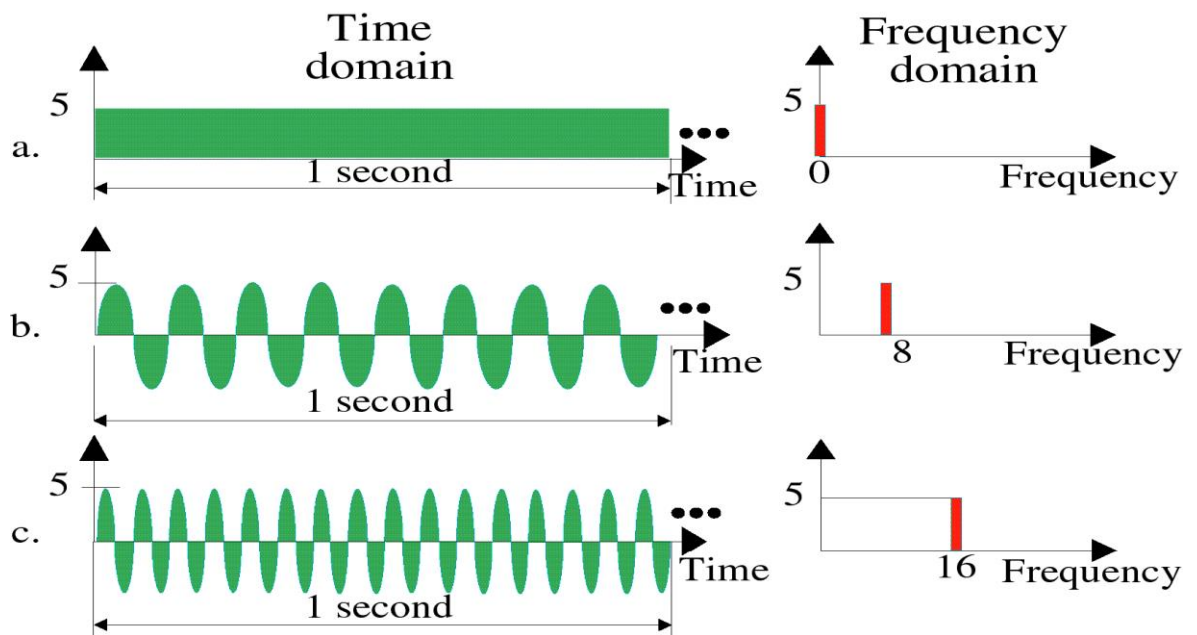


Fig: Time domain and frequency domain plots of three sine waves*

A complete sine wave in the time domain can be represented by one single spike in the frequency domain

Composite Signal

A composite signal is a combination of two or more simple sine waves with different frequency, phase and amplitude.

If the composite signal is periodic, the decomposition gives a series of signals with discrete frequencies; if the composite signal is non-periodic, the decomposition gives a combination of sine waves with continuous frequencies.

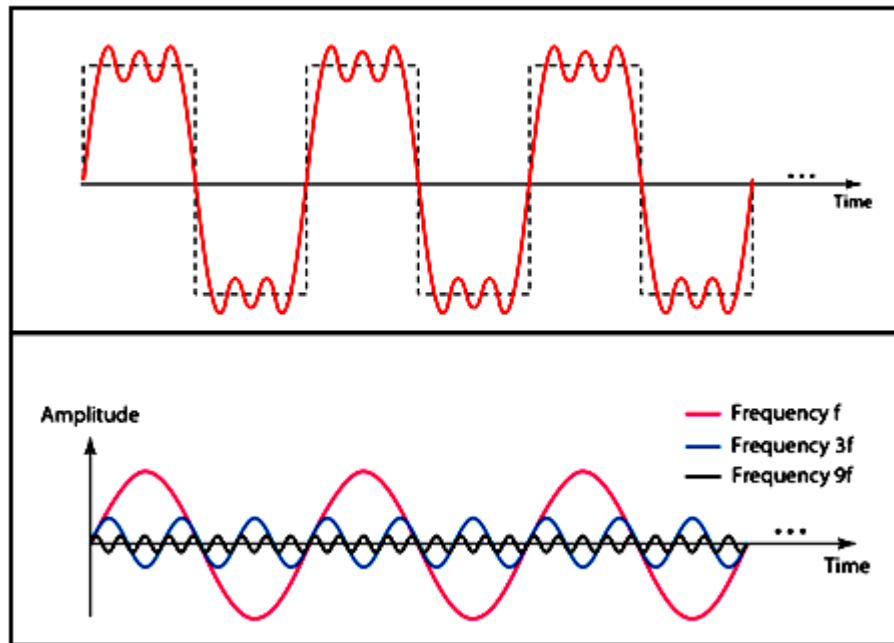


Fig: A Composite signal with three component signals

For data communication a simple sine wave is not useful, what is used is a composite signal which is a combination of many simple sine waves.

According to French Mathematician, Jean Baptist, any composite signal is a combination of simple sine waves with different amplitudes and frequencies and phases.

Composite signals can be periodic or non periodic.

A periodic composite signal can be decomposed into a series of signals with discrete frequencies.

A non-periodic signal when decomposed gives a combination of sine waves with continuous frequencies.

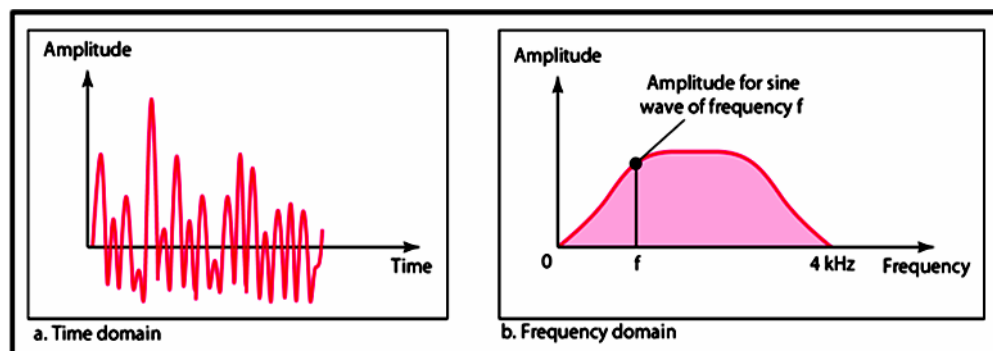
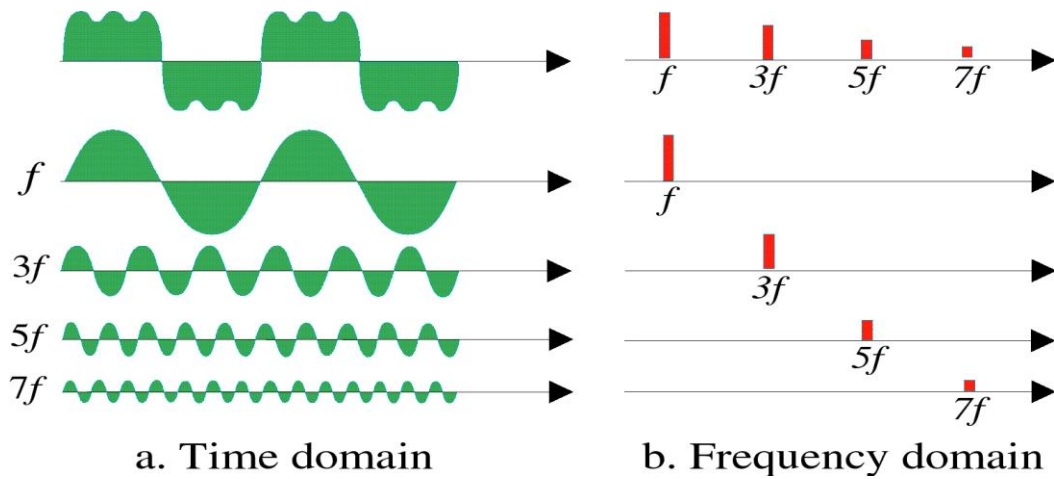


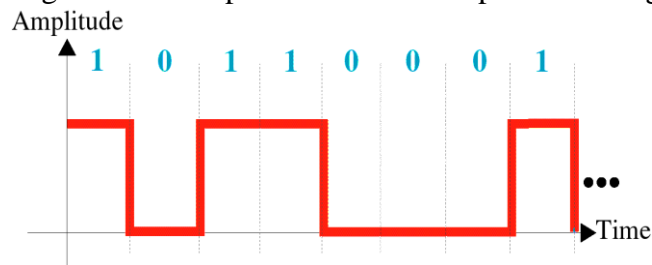
Fig The time and frequency domains of a non-periodic composite analog signal

Composite Waveform



Digital Signal

Information can also be explained in the form of a digital signal.
A digital signal can be explained with the help of following points:



Definition:-

A digital is a signal that has discrete values.
The signal will have value that is not continuous.

LEVEL

Information in a digital signal can be represented in the form of voltage levels.

Ex. In the signal shown below, a '1' is represented by a positive voltage and a '0' is represented by a Zero voltage.

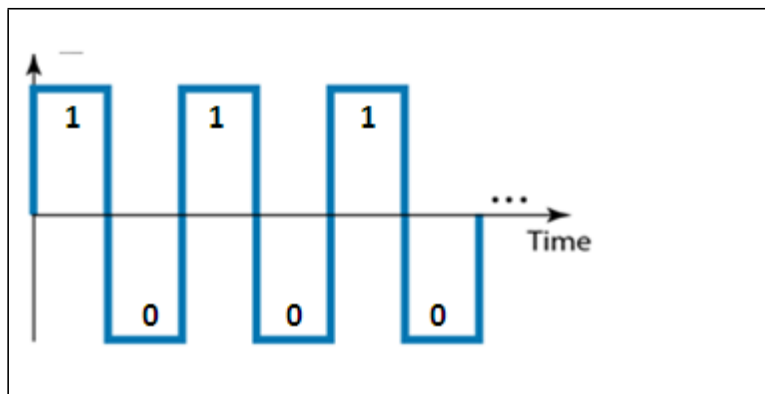


Fig: A digital signal with Two levels. „1“ represented by a positive voltage and „0“ represented by a negative voltage

A Signal can have more than two levels

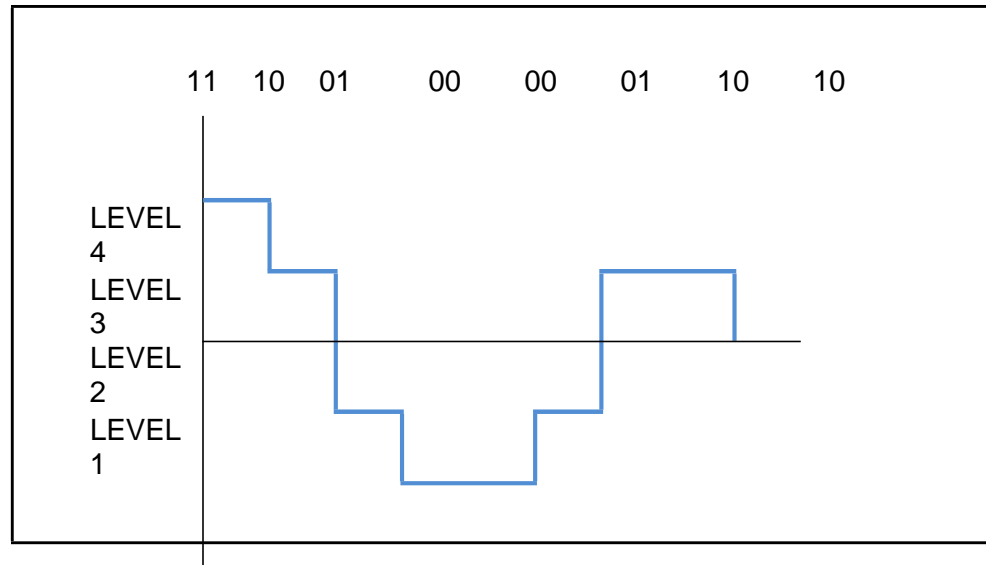


Fig: A digital signal with four levels

In general, if a signal has L levels then, each level need $\log_2 L$ bits

Example: Consider a digital Signal with four levels, how many bits are required per level?

Answer: Number of bits per level = $\log_2 L$
= $\log_2 4$
= 2

Hence, 2 bits are required per level for a signal with four levels.

BIT LENGTH or Bit Interval (T_b)

It is the time required to send one bit. It is measured in seconds.

BIT RATE

It is the number of bits transmitted in one second. It is expressed as bits per second (bps).

Relation between bit rate and bit interval can be as follows

Bit rate = $1 / \text{Bit interval}$

Baud Rate

It is the rate of Signal Speed, i.e the rate at which the signal changes.

A digital signal with two levels $_0$ & $_1$ will have the same baud rate and bit rate.

The diagram below shows three signal of period (T) 1 second

a) Signal with a bit rate of 8 bits/ sec and baud rate of 8 baud/sec

b) Signal with a bit rate of 16 bits/ sec and baud rate of 8 baud/sec

c) Signal with a bit rate of 16 bits/ sec and baud rate of 4 baud/sec

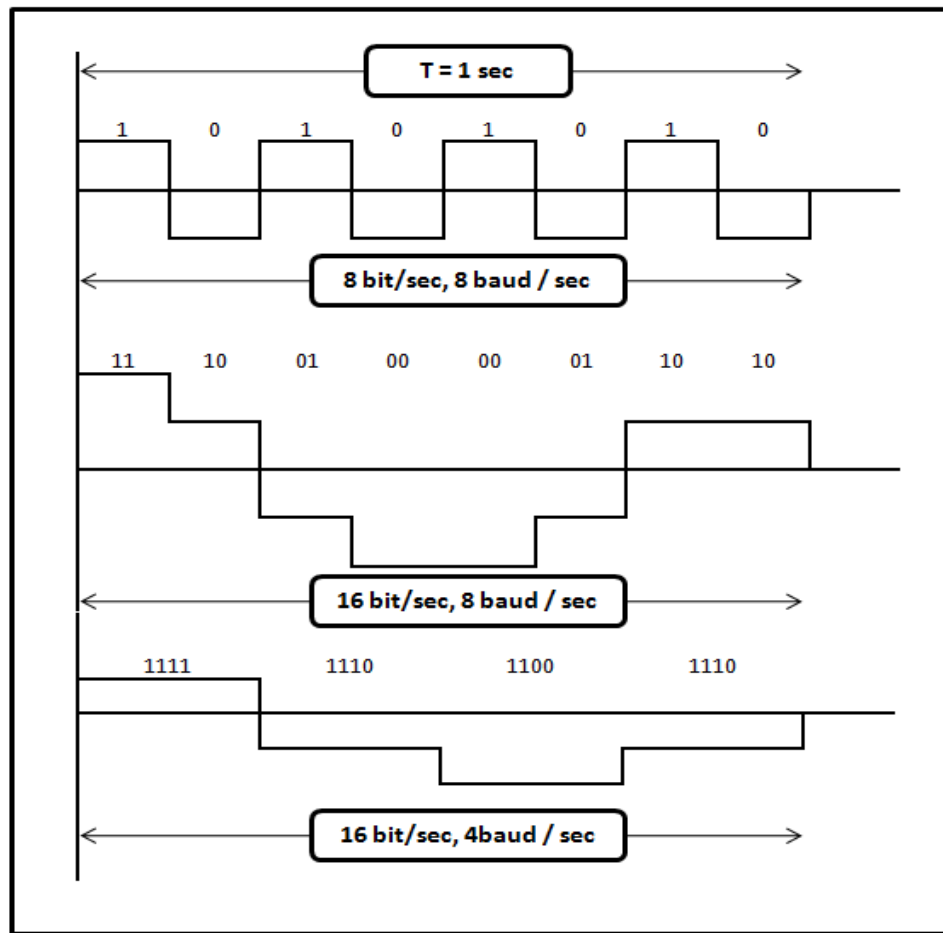
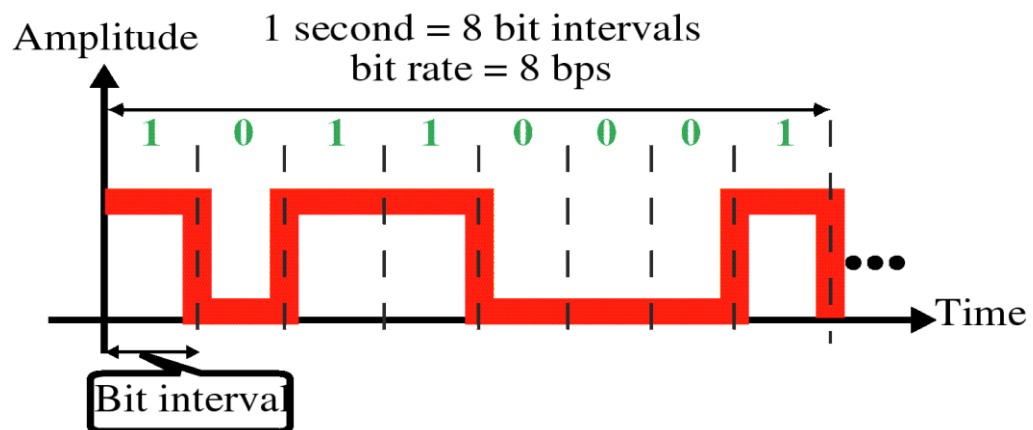


Fig: Three signals with different bit rates and baud rates

Bit Interval and Bit Rate

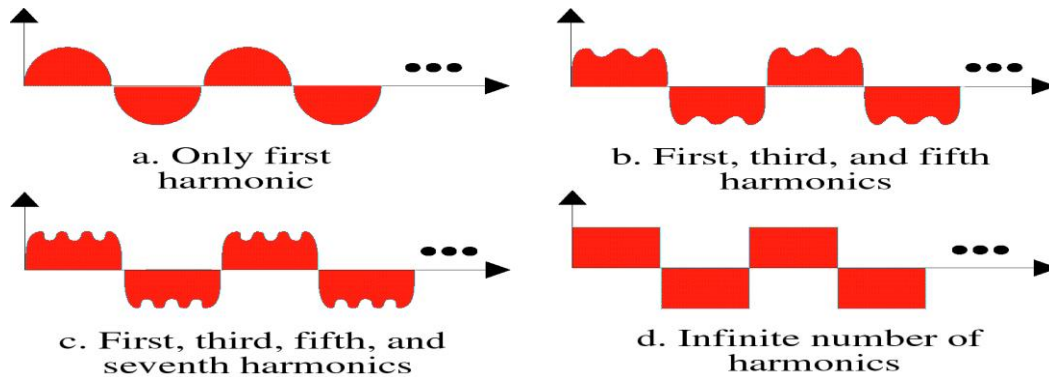
The bit interval is the time required to send one single bit. The bit rate is the number of bit intervals per second.



Decomposition of a Digital Signal

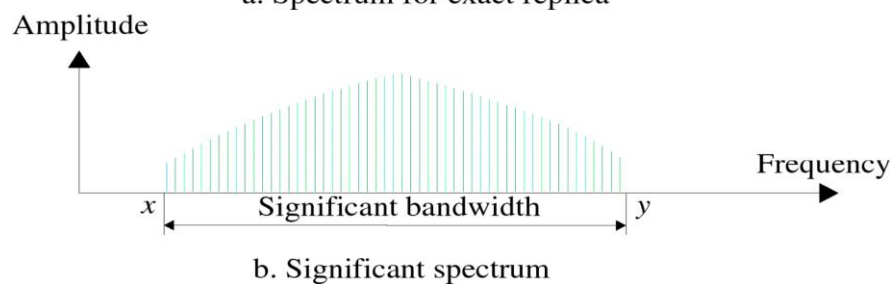
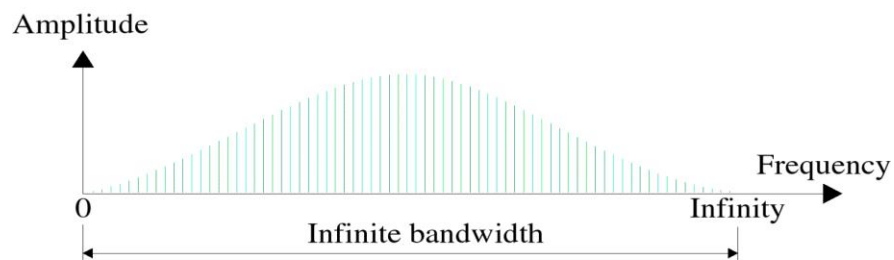
A digital signal can be decomposed into an infinite number of sine waves (harmonics).

Harmonics of a Digital Signal



Exact and Significant Spectrums

The significant spectrum of a digital signal is the portion of the signal's spectrum that can adequately reproduce the original signal.



Analog and Digital

Analog refers to something that is continuous—a set of specific points of data and all possible points between. Digital refers to something that is discrete—a set of specific points of data with no other points in between.

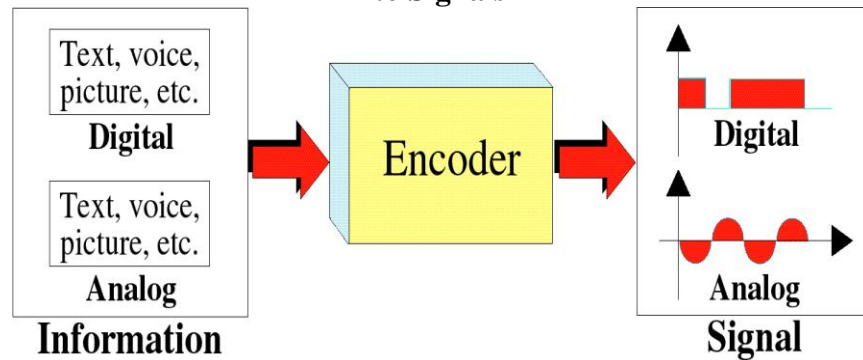
Analog and Digital Data

Data can be analog or digital. An example of analog data is the human voice. An example of digital data is data stored, the memory of a computer in the form of 0s and 1s.

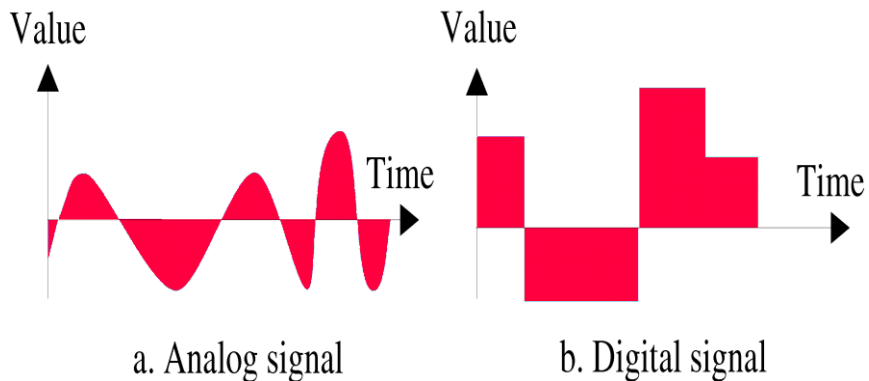
Analog and Digital Signals

Signals can be analog or digital. Analog signals can have any value in a range; digital signals can have only a limited number of values.

Transformation of Information to Signals



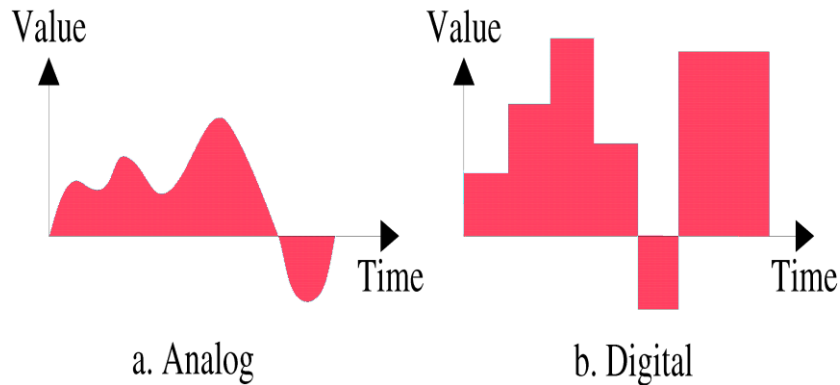
Analog and Digital Signals



Aperiodic and periodic signals

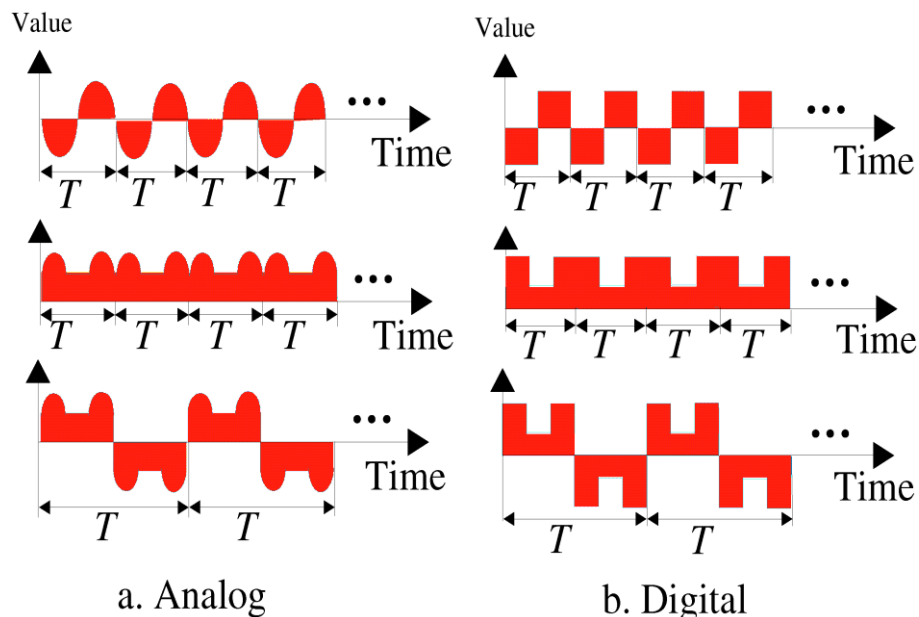
Aperiodic signals

An aperiodic, or nonperiodic, signal changes constantly without exhibiting a pattern or cycle that repeats over time. An aperiodic, or nonperiodic, signal has no repetitive pattern. An aperiodic signal can be decomposed into an infinite number of periodic signals.



Periodic Signals

A signal is a periodic signal if it completes a pattern within a measurable time frame, called a period, and repeats that pattern over identical subsequent periods. The completion of one full pattern is called a cycle. A periodic signal consists of a continuously repeated pattern. The period of a signal (T) is expressed in seconds.



BANDWIDTH OF A SIGNAL

Bandwidth can be defined as the portion of the electromagnetic spectrum occupied by the signal

It may also be defined as the frequency range over which a signal is transmitted.

Different types of signals have different bandwidth. Ex. Voice signal, music signal, etc

Bandwidth of analog and digital signals are calculated in separate ways; analog signal bandwidth is measured in terms of its frequency (hz) but digital signal bandwidth is measured in terms of bit rate (bits per second, bps)

Bandwidth of signal is different from bandwidth of the medium/channel

Bandwidth of an analog signal

Bandwidth of an analog signal is expressed in terms of its frequencies.

It is defined as the range of frequencies that the composite analog signal carries.

It is calculated by the difference between the maximum frequency and the minimum frequency.

Consider the signal shown in the diagram below:

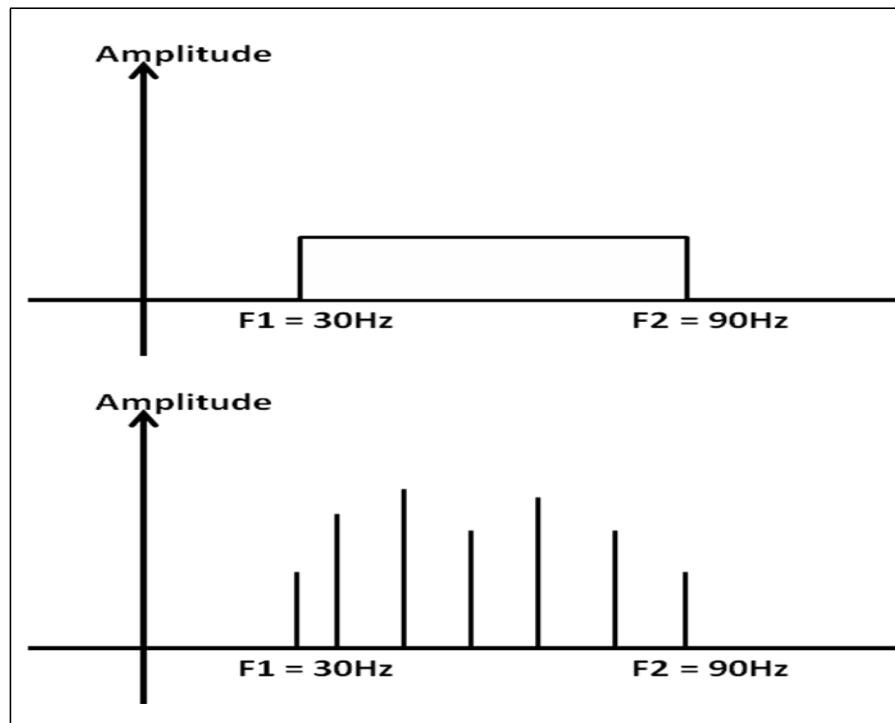


Fig: Bandwidth of a signal in time domain and frequency domain

The signal shown in the diagram is an composite analog signal with many component signals.

It has a minimum frequency of $F1 = 30\text{Hz}$ and maximum frequency of $F2 = 90\text{Hz}$.

Hence the bandwidth is given by $F2 - F1 = 90 - 30 = 60\text{ Hz}$

Bandwidth of a digital signal

It is defined as the maximum bit rate of the signal to be transmitted.

It is measured in bits per second.

BANDWIDTH OF A CHANNEL

A channel is the medium through which the signal carrying information will be passed.

In terms of analog signal, bandwidth of the channel is the range of frequencies that the channel can carry.

In terms of digital signal, bandwidth of the channel is the maximum bit rate supported by the channel. i.e. the maximum amount of data that the channel can carry per second.

The bandwidth of the medium should always be greater than the bandwidth of the signal to be transmitted else the transmitted signal will be either attenuated or distorted or both leading in loss of information.

The channel bandwidth determines the type of signal to be transmitted i.e. analog or digital.

THE MAXIMUM DATA RATE OF A CHANNEL

Data rate depends on three factors:

1. The bandwidth available
2. The level of the signals we use
3. The quality of the channel (the level of noise)

The quality of the channel indicates two types:

a) A Noiseless or Perfect Channel

An ideal channel with no noise.

The Nyquist Bit rate derived by Henry Nyquist gives the bit rate for a Noiseless Channel.

b) A Noisy Channel

A realistic channel that has some noise.

The Shannon Capacity formulated by Claude Shannon gives the bit rate for a Noisy Channel

Nyquist Bit Rate

The Nyquist bit rate formula defines the theoretical maximum bit rate for a noiseless channel

$$\text{Bitrate} = 2 \times \text{Bandwidth} \times \log_2 L$$

Where,

Bitrate is the bitrate of the channel in bits per second

Bandwidth is the bandwidth of the channel

L is the number of signal levels.

Example

What is the maximum bit rate of a noiseless channel with a bandwidth of 5000 Hz transmitting a signal with two signal levels.

Solution:

The bit rate for a noiseless channel according to Nyquist Bit rate can be calculated as follows:

$$\begin{aligned}\text{BitRate} &= 2 \times \text{Bandwidth} \times \log_2 L \\ &= 2 \times 5000 \times \log_2 2 = 10000 \text{ bps}\end{aligned}$$

Shannon Capacity

The Shannon Capacity defines the theoretical maximum bit rate for a noisy channel

$$\text{Capacity} = \text{bandwidth} \times \log_2 (1 + \text{SNR})$$

Where,

Capacity is the capacity of the channel in bits per second

Bandwidth is the bandwidth of the channel

SNR is the Signal to Noise Ratio

Shannon Capacity for calculating the maximum bit rate for a noisy channel does not consider the number of levels of the signals being transmitted as done in the Nyquist bit rate. Example:

Calculate the bit rate for a noisy channel with SNR 300 and bandwidth of 3000Hz

Solution:

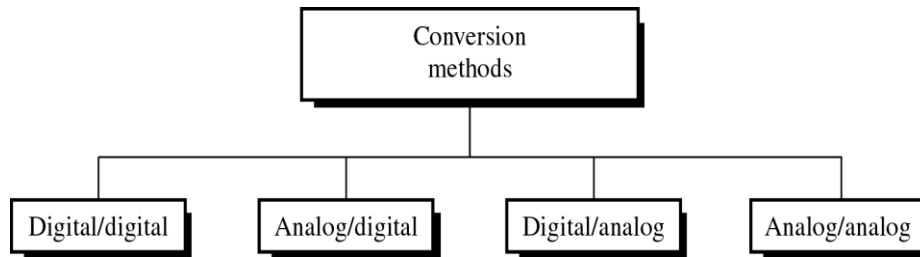
The bit rate for a noisy channel according to Shannon Capacity can be calculated as follows:

$$\begin{aligned}&= 3000 \times \log_2 (1 + 300) \\ &= 3000 \times \log_2 (301) \\ &= 3000 \times 8.23 \\ &= 24,690 \text{ bps}\end{aligned}$$

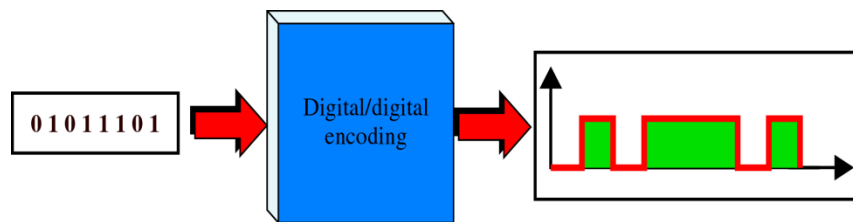
Encoding and Modulating

We must transform data into signals to send them from one place to another.

Different Conversion Schemes



Digital to Digital Conversion



Types of Digital to Digital Encoding

Digital Data to Digital Signal

Coding methods Coding methods are used to convert digital data into digital signals.

There are two types of coding methods:

- 1 Line Coding
- 2 Block Coding

Scrambling is also one of the ways to convert digital data to digital signals but is not used.

8.3.1 Line Encoding

It is the process of converting Digital data into digital signal. In other words, it is converting of binary data(i.e. A sequence of bits) into digital signal (i.e. a sequence of discrete, discontinuous voltage pulses)

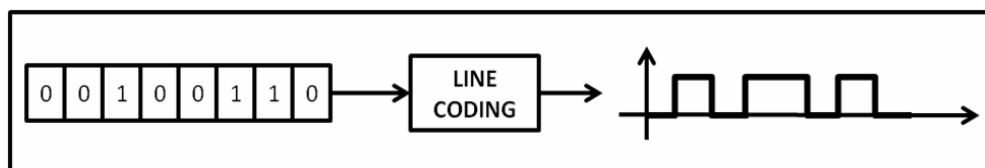


Figure: Line Coding

8.3.2 Classification of Line Codes

The following figure shows the classification of Line coding schemes:

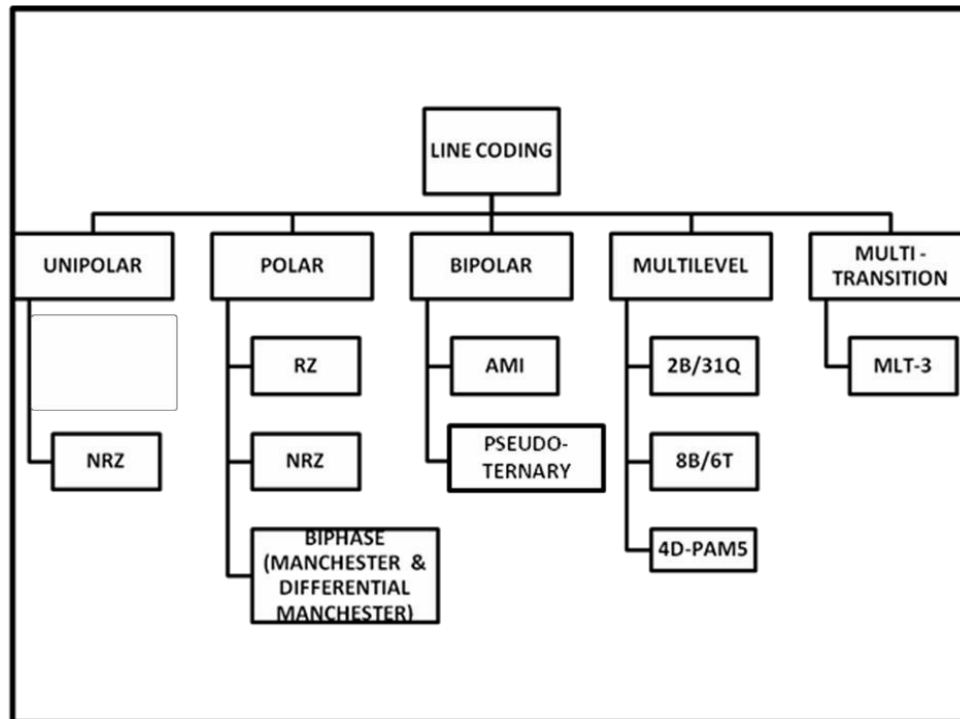
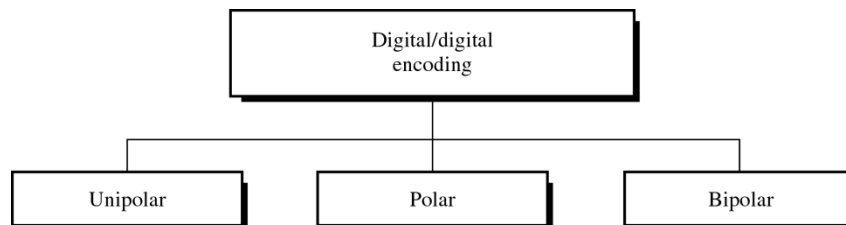
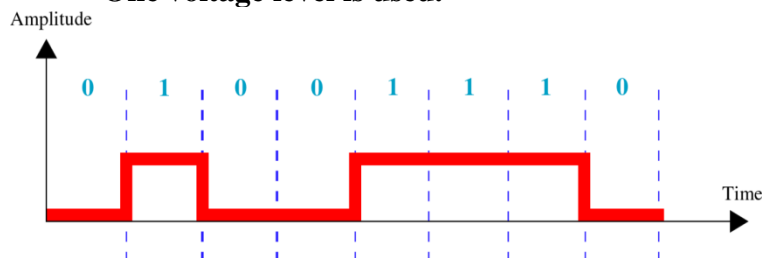


Figure : Classification of line coding schemes



Unipolar Encoding

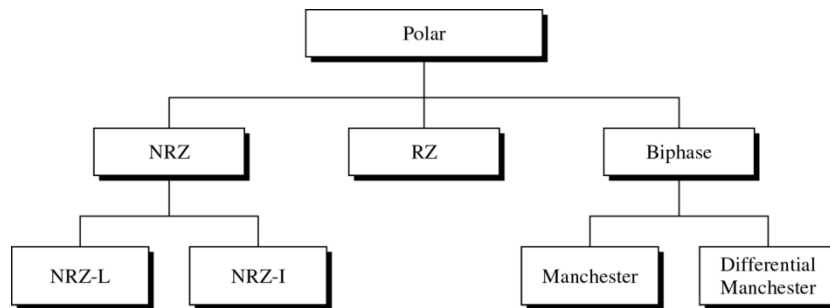
One voltage level is used.



Polar Encoding

Polar encoding uses two levels (positive and negative) of amplitude.

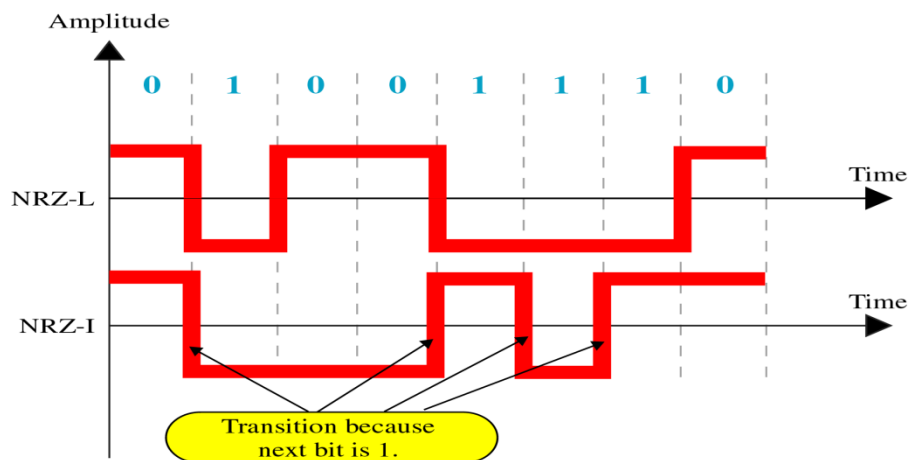
Types of Polar Encoding



NRZ-L and NRZ-I Encoding

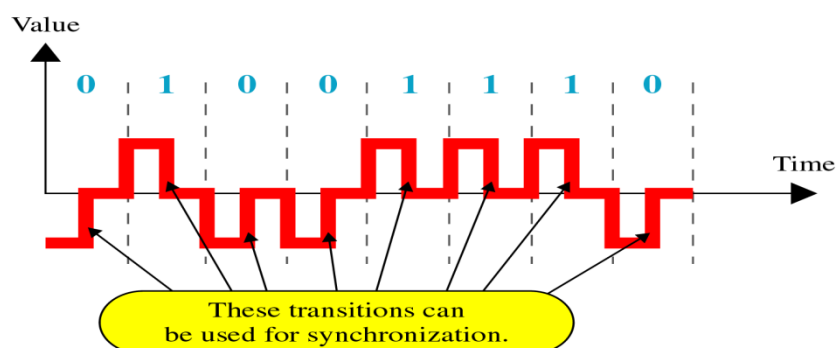
In NRZ-L the level of the signal is dependent upon the state of the bit. A positive voltage usually means the bit is a 0 and a negative voltage means the bit is a 1.

In NRZ-I the signal is inverted if a 1 is encountered. An inversion of the voltage level represents a bit 1. A 0 bit is represented by no change.



RZ Encoding

In RZ, the signal changes not between bits but during each bit. A 1 bit is actually represented by positive-to-zero and a 0 bit by negative-to-zero. The main disadvantage of RZ encoding is that it requires two signal changes to encode one bit and therefore occupies more bandwidth.



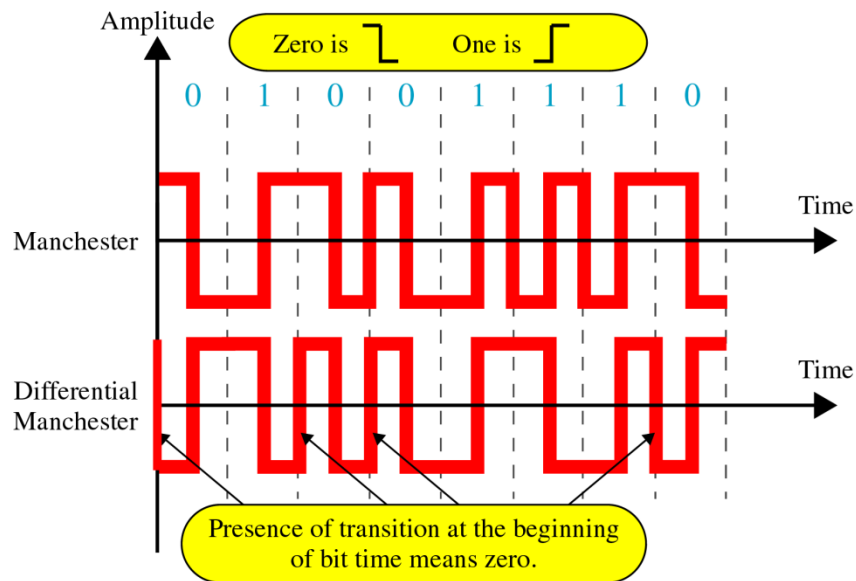
Biphase

Biphase encoding is implemented in two different ways: Manchester and Differential Manchester.

Manchester and Differential Manchester Encoding

In Manchester encoding, the transition at the middle of the bit is used for both synchronization and bit representation.

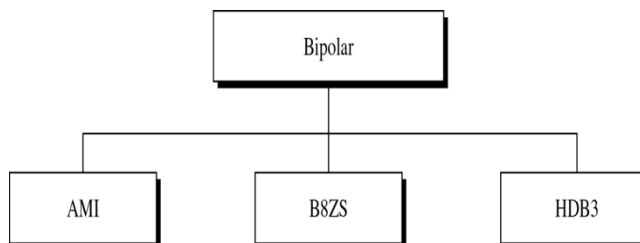
In Differential Manchester encoding, the transition at the middle of the bit is used only for synchronization. The bit representation is shown by the inversion or non inversion at the beginning of the bit.



Bipolar

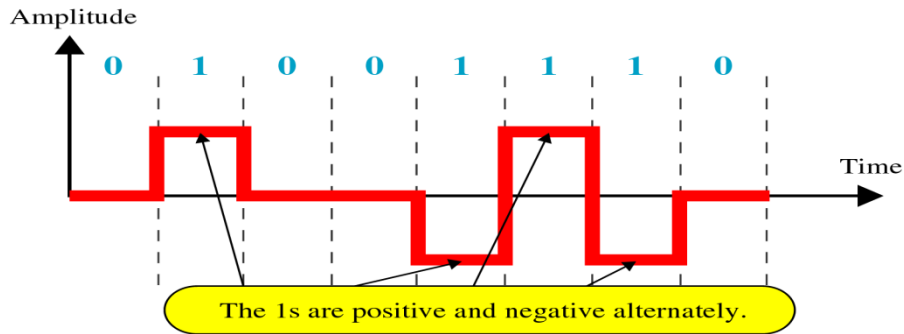
In bipolar encoding, we use three levels: positive, zero and negative.

Types of Bipolar Encoding



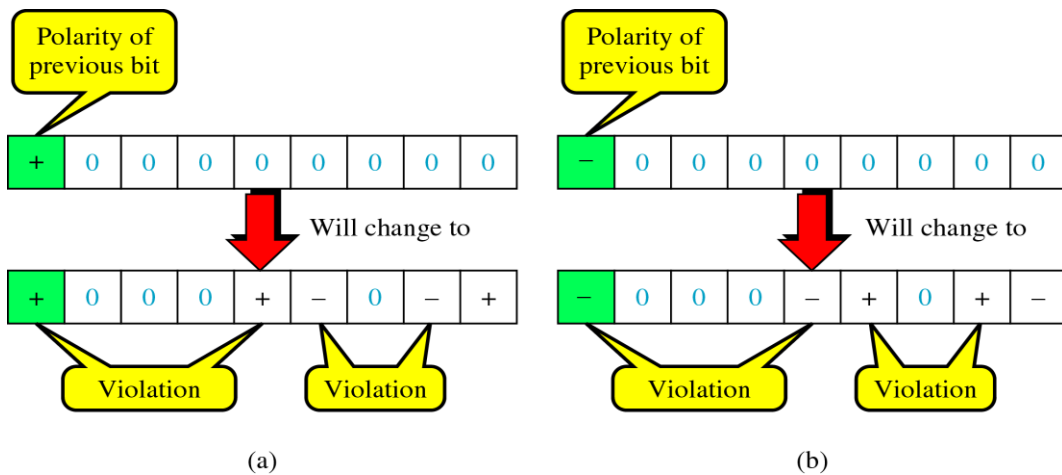
Bipolar AMI (Alternate Mark Inversion) Encoding

A neutral, Zero voltage represents binary 0. Binary 1s are represented by alternating positive and negative voltages.



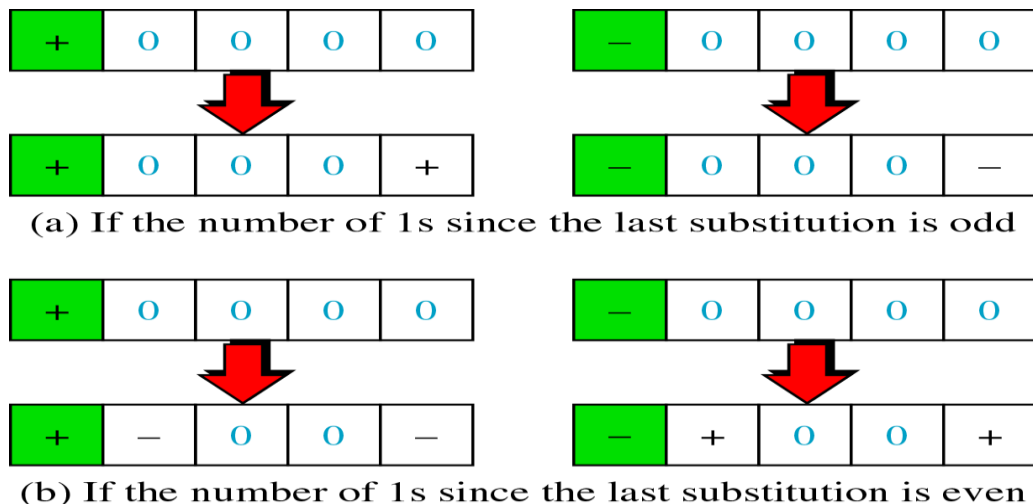
(Bipolar 8-Zero Substitution) B8ZS Encoding

In B8ZS if eight 0s come one after another, we change the pattern in one of two ways based on the polarity of the previous 1.



(High-Density Bipolar 3) HDB3 Encoding

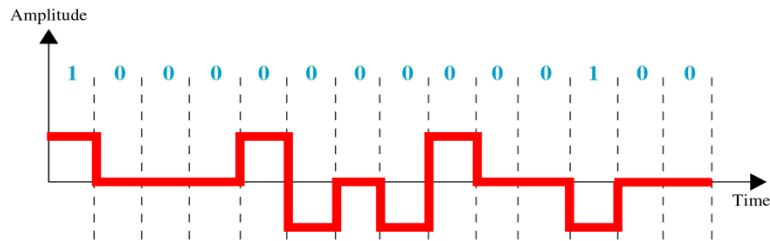
In HDB3 if four 0s come one after another, we change the pattern in one of four ways based on the polarity of the previous 1 and the number of 1s since the last substitution.



Example 5.1

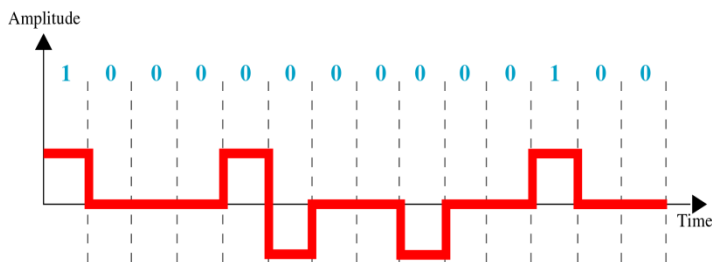
Using B8ZS, encode the bit stream 1000000000100. Assume that the polarity of the first 1 is positive.

Solution to Example 5.1

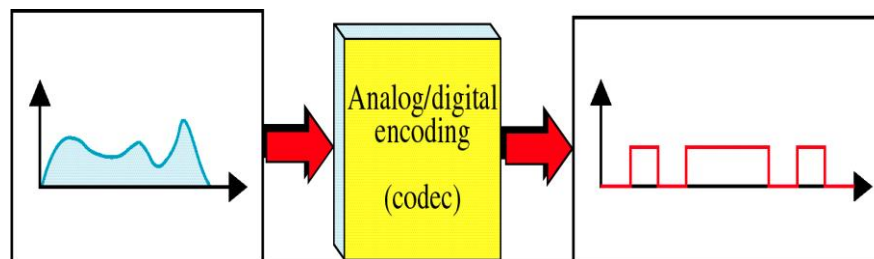


Example 5.2 Using HDB3, encode the bit stream 10000000000100. Assume that the number of 1s so far is odd and the first 1 is positive.

Solution to Example 5.2

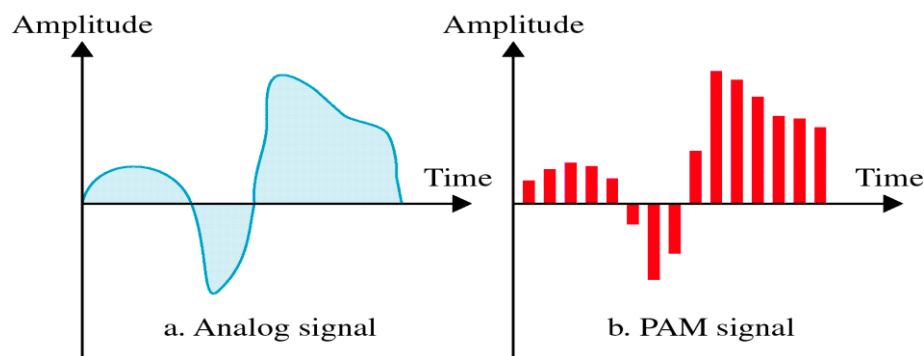


5.2 Analog to Digital Conversion



Pulse Amplitude Modulation (PAM)

The first step in analog to digital conversion is called Pulse Amplitude Modulation (PAM). In PAM, the original signal is sampled at equal intervals.

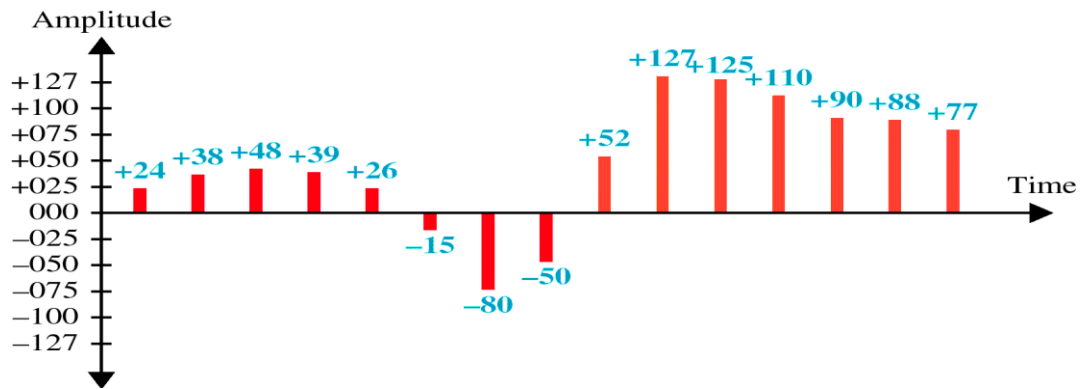


Pulse Code Modulation (PCM)

PCM modifies the pulses created by PAM to create a completely digital signal.

Quantized PAM Signal

Quantization is a method of assigning integral values in a specific range to sampled instances.



Quantizing Using Sign and Magnitude

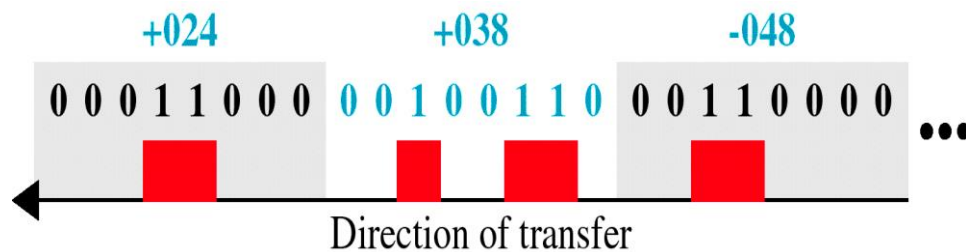
+024	00011000	-015	10001111	+125	01111101
+038	00100110	-080	11010000	+110	01101110
+048	00110000	-050	10110010	+090	01011010
+039	00100111	+052	00110110	+088	01011000
+026	00011010	+127	01111111	+077	01001101

Sign bit
+ is 0 - is 1

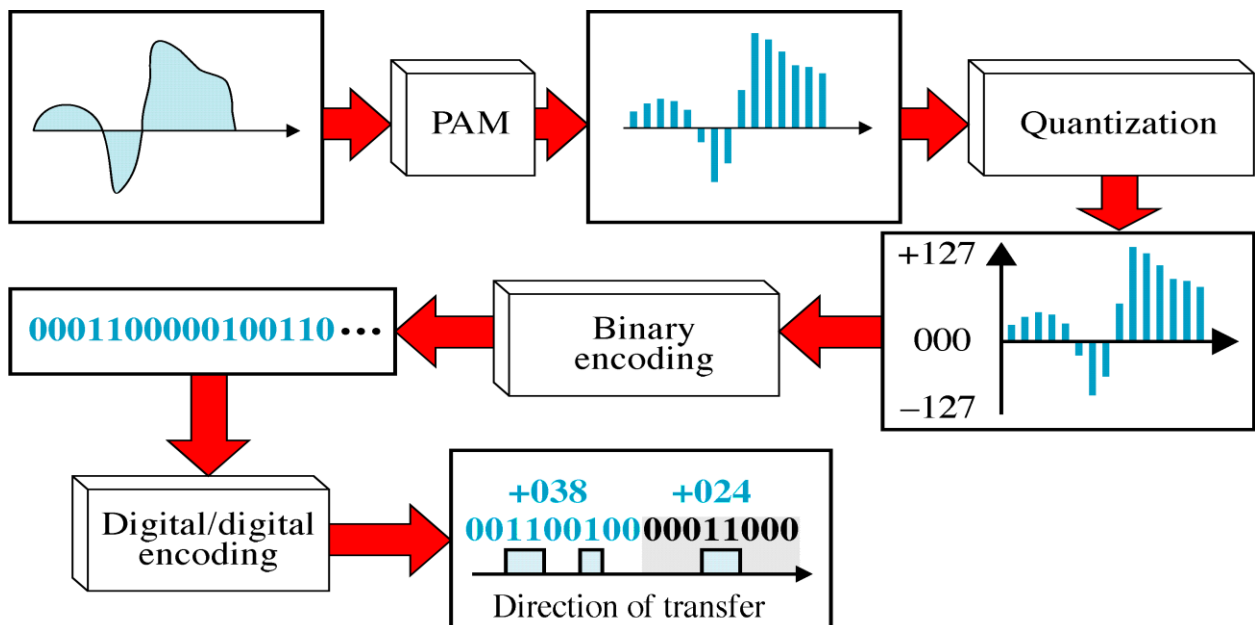
Sampling Rate

According to the Nyquist theorem, the sampling rate must be at least two times the highest frequency.

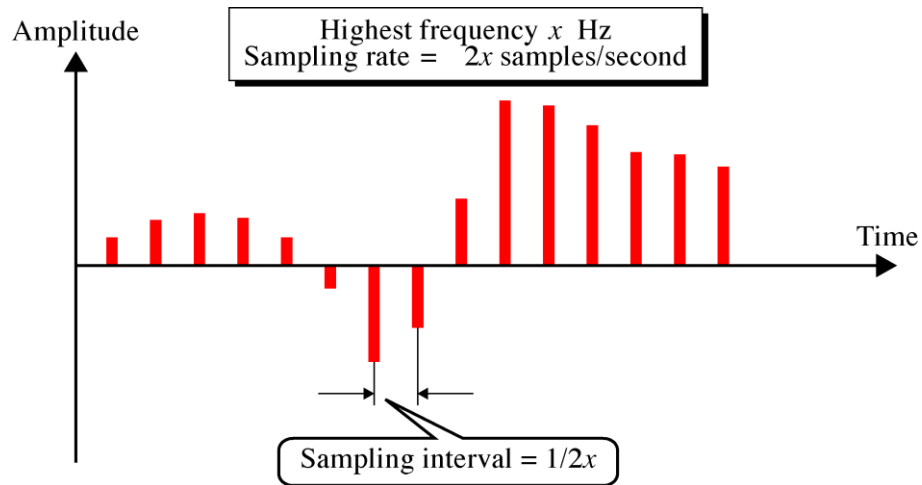
PCM



From Analog signal to PCM digital code

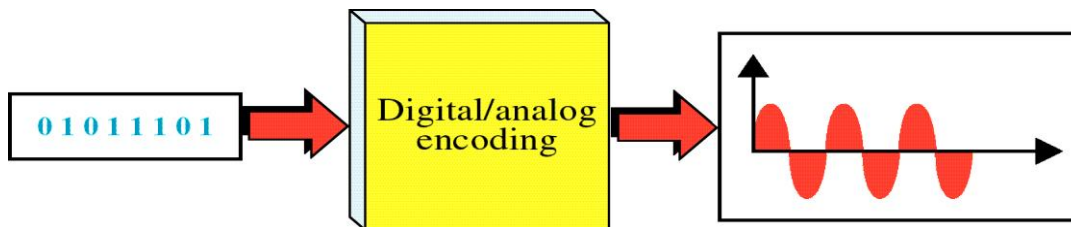


Nyquist Theorem

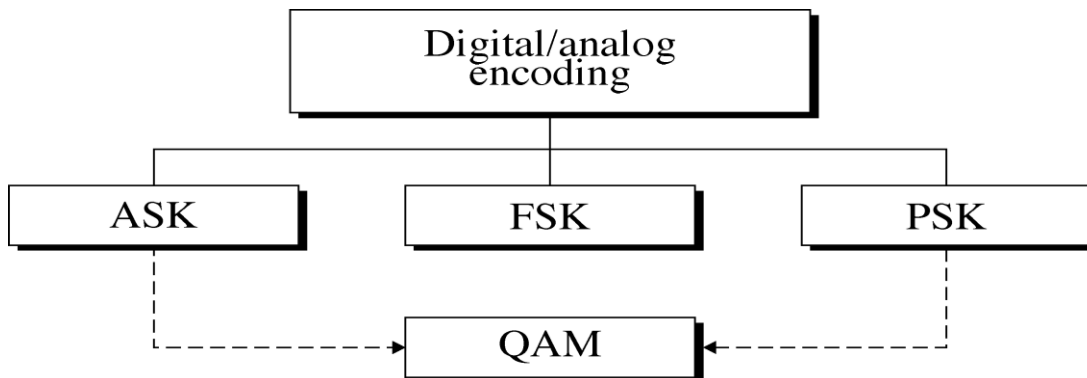


5.3 Digital to Analog Conversion

This is the process of changing one of the characteristics of an Analog signal based on the information in a digital signal (0s and 1s).



Type of Digital to Analog modulation



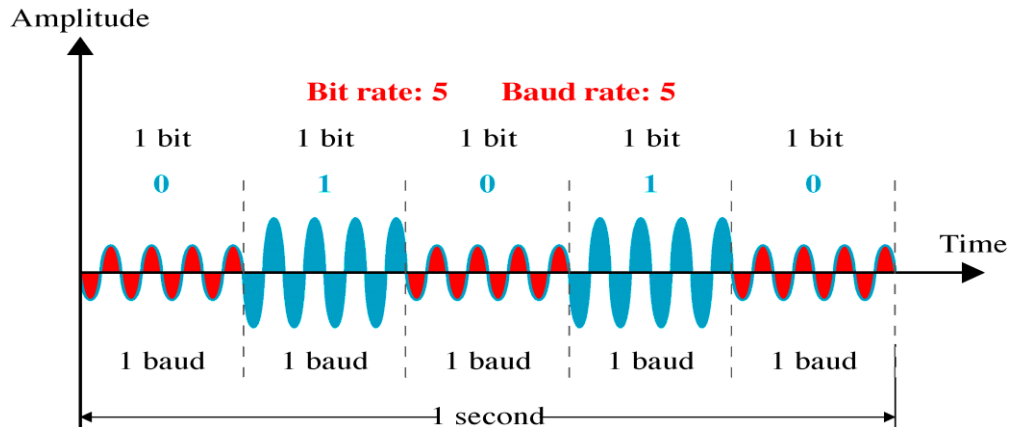
Aspect of Digital to Analog conversion

Two basic issues must be defined: bit/ baud rate and carrier signal

Bitrate is the number of bits per second. Baud rate is the number of signal units per second. baud rate is less than or equal to bit rate.

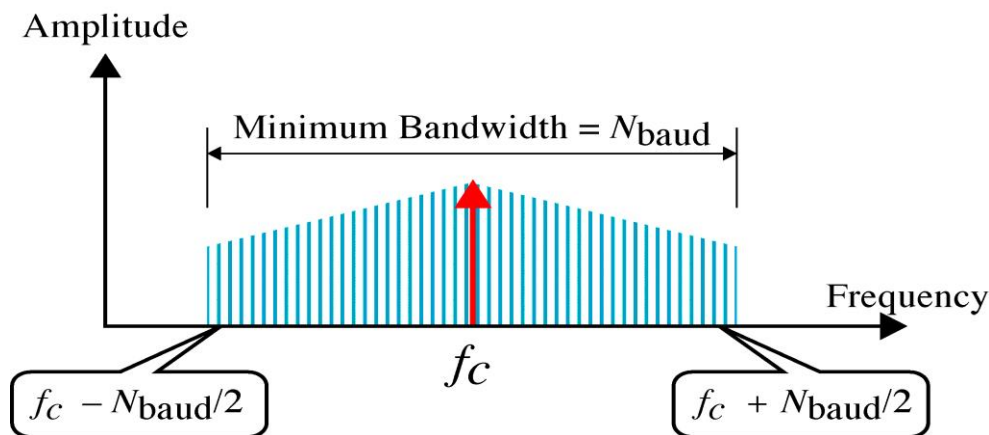
Amplitude Shift Keying (ASK)

In ASK the strength of the carrier signal is varied to represent the binary 1 or 0. Both frequency and phase remain constant, while the amplitude changes



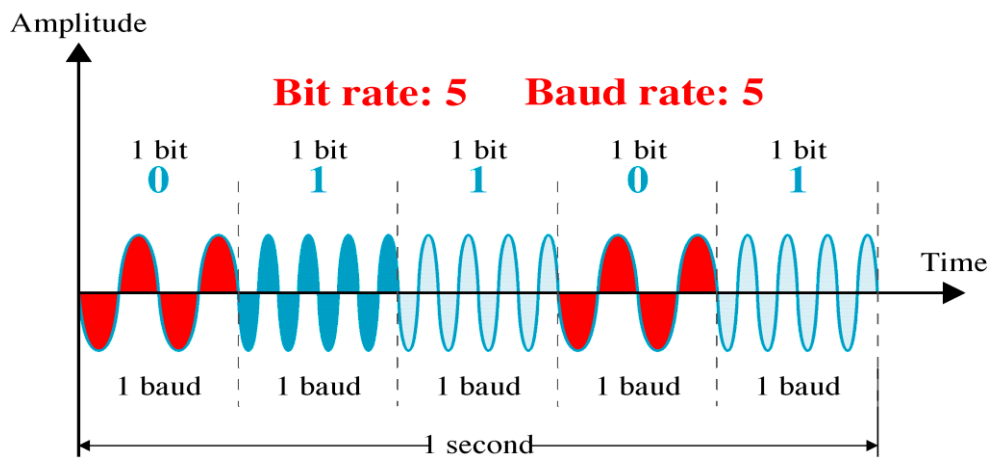
A popular ASK technique is called on-off Keying (**OOK**). In OOK one of the bit values is represented by no voltage. Advantage is a reduction in the amount of energy required to transmit information.

Bandwidth for ASK

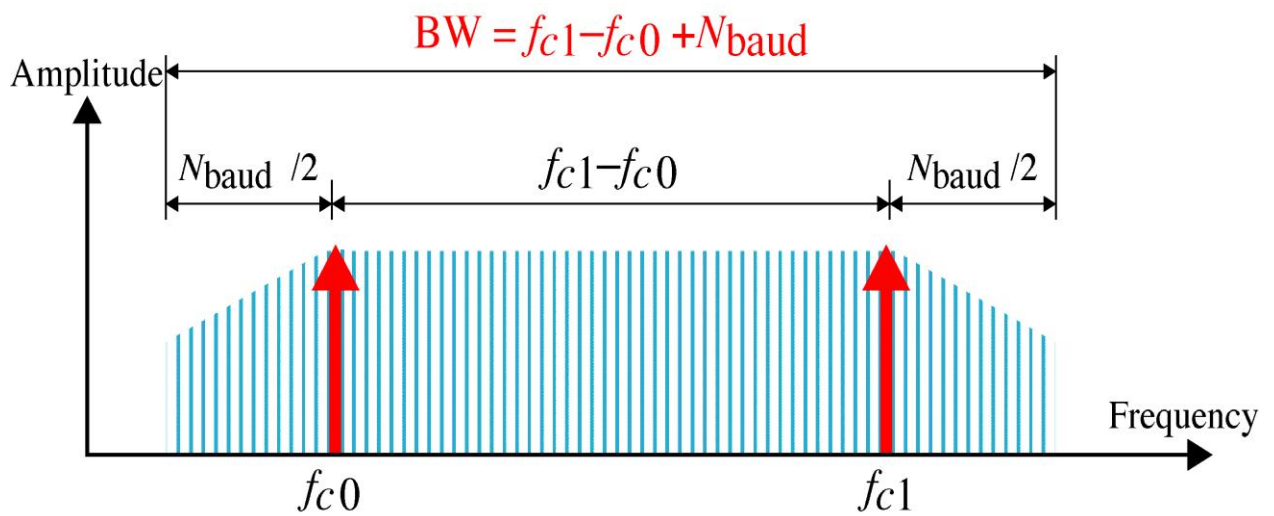


Frequency Shift Keying (FSK)

In FSK the frequency of the carrier signal is varied to represent the binary 1 or 0. Both Amplitude and phase remain constant, while the frequency changes. FSK avoids most of the noise problems of PSK.

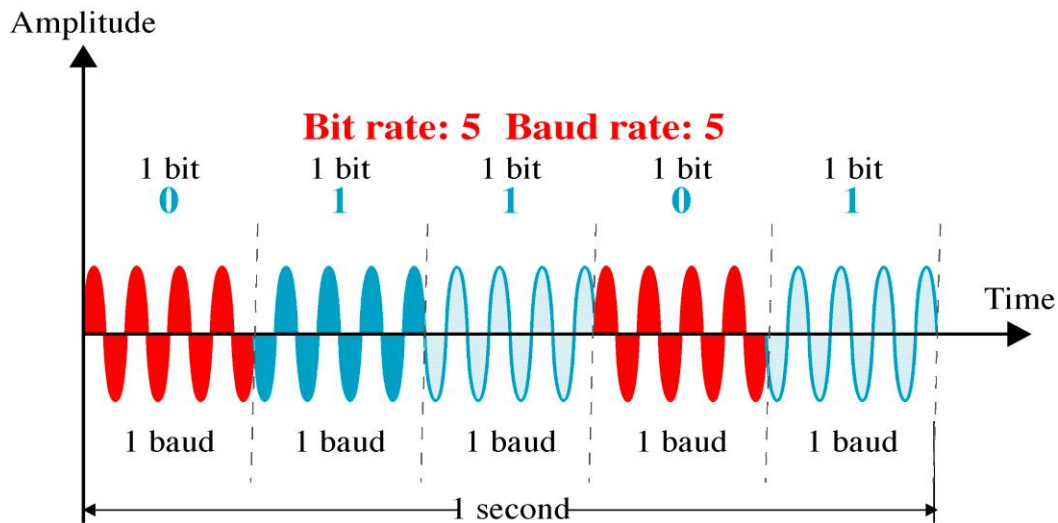


Bandwidth for FSK



Phase Shift Keying (PSK)

In PSK the phase of the carrier is varied to represent binary 1 or 0. Both peak amplitude and frequency remains constant as the phase changes

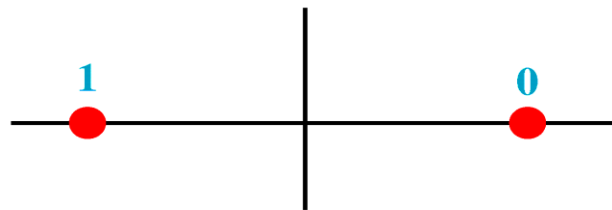


The above method is often called 2-PSK or binary PSK, because two different phases (0 and 180 Degrees) are used

PSK Constellation

Bit	Phase
0	0
1	180

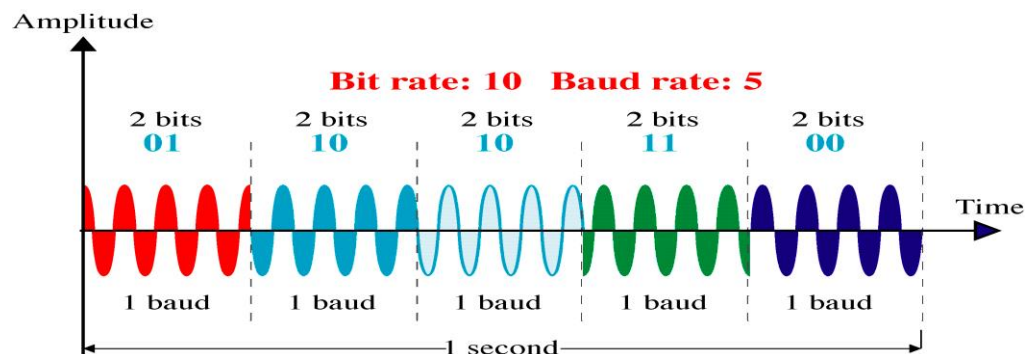
Bits



Constellation diagram

4-PSK

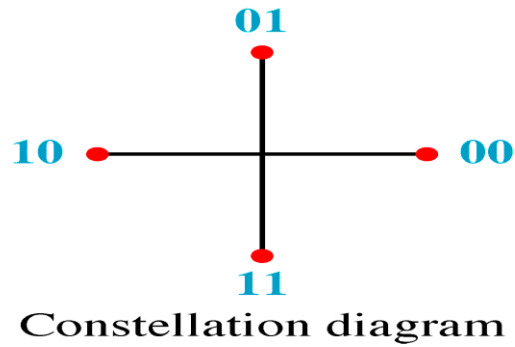
This Technique is also called Q-PSK . The pair of bits represented by each phase is called a di bit. We can also extend this idea to 8-PSK. The constellation diagram for the signal is shown in following figures:



4-PSK Characteristics

Dibit	Phase
00	0
01	90
10	180
11	270

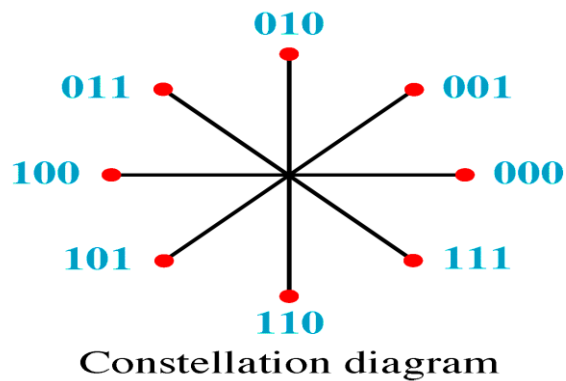
Dibit
(2 bits)



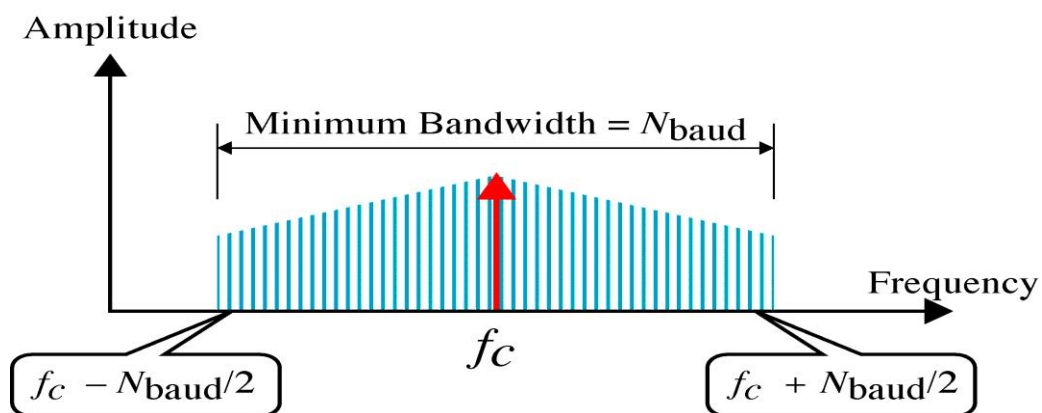
8-PSK Characteristics

Tribit	Phase
000	0
001	45
010	90
011	135
100	180
101	225
110	270
111	315

Tribits
(3 bits)



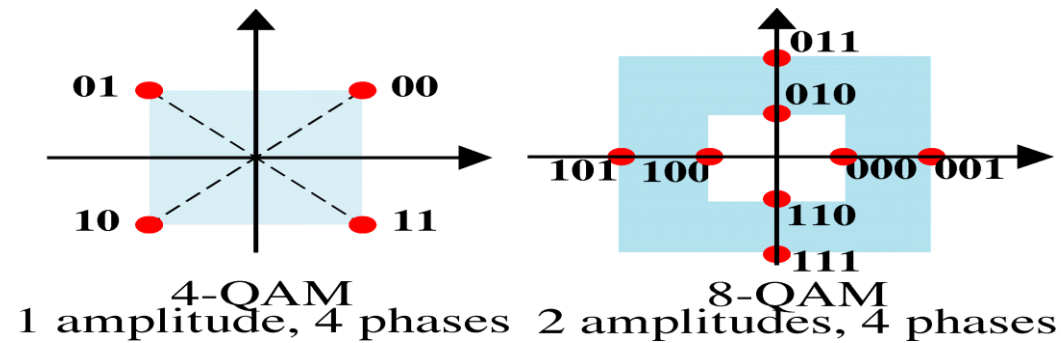
PSK Bandwidth



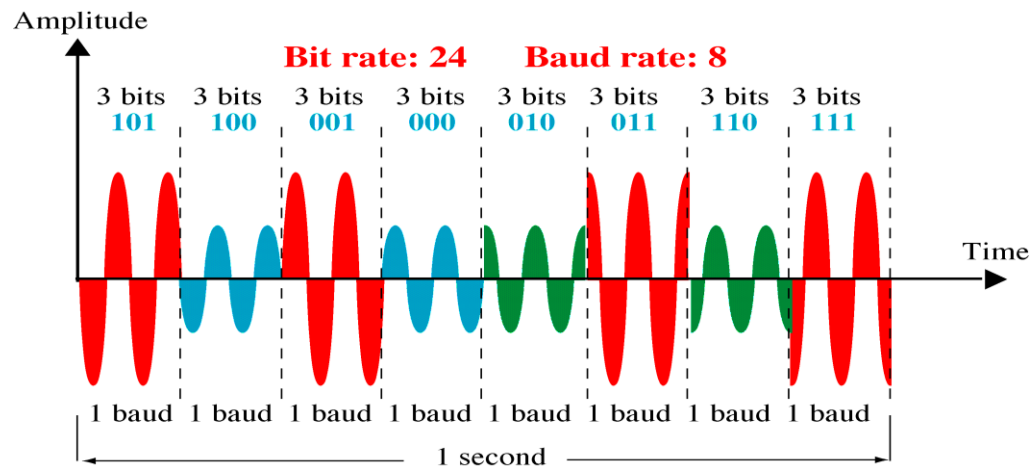
Quadrature Amplitude Modulation (QAM)

QAM means combining ASK and PSK in such a way that we have maximum contrast between each bit, dibit, tribit, quadbit and so on. the following are the two possible configuration :

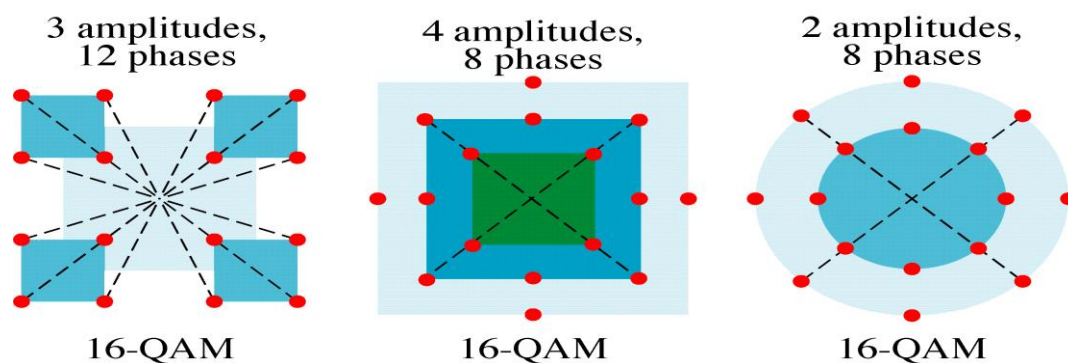
4-QAM and 8-QAM Constellations



8-QAM Signal



16-QAM Constellation



Bit Rate and Baud Rate

Bit

Baud rate = N

Bit rate = N

0	0	1	0	1	0	0	0	1	0	1	0	1	0	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Dibit

Baud rate = N

Bit rate = $2N$

0	0	1	0	1	0	0	0	1	0	1	0	1	1	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Tribit

Baud rate = N

Bit rate = $3N$

0	0	1	0	1	0	0	0	1	0	1	0	1	1	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Quadbit

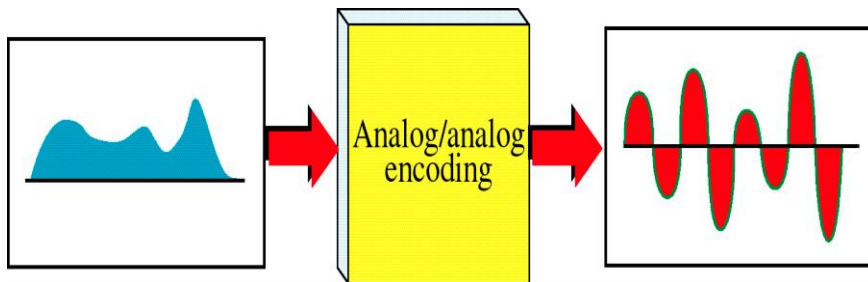
Baud rate = N

Bit rate = $4N$

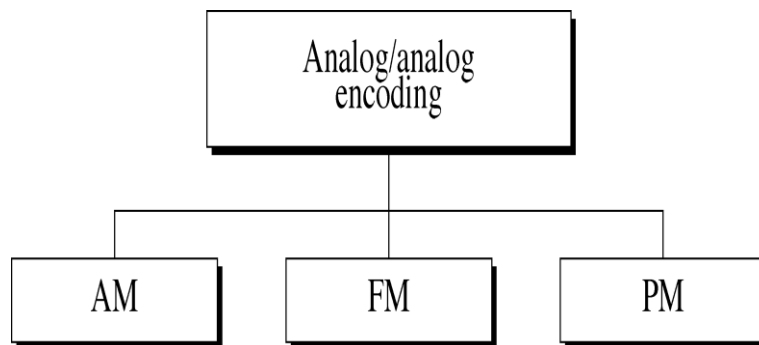
0	0	1	0	1	0	0	0	1	0	1	0	1	1	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Analog to Analog Conversion

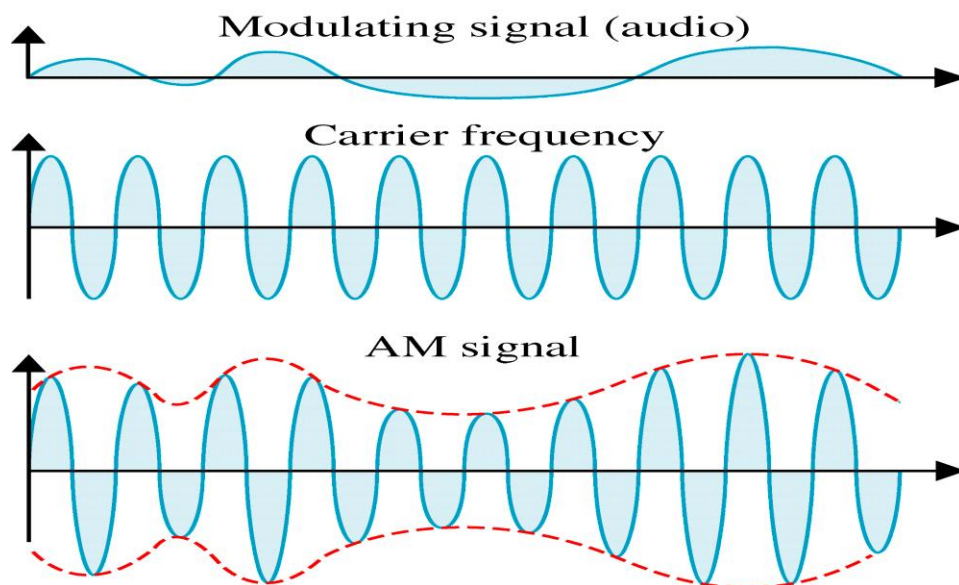
Is the representation of analog information by an analog signal.



Types of Analog-to-analog modulation

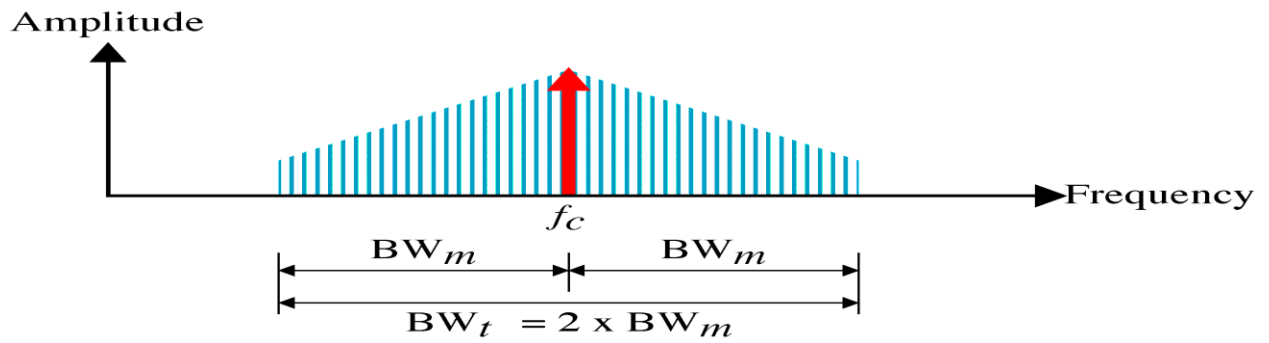


Amplitude Modulation(AM)



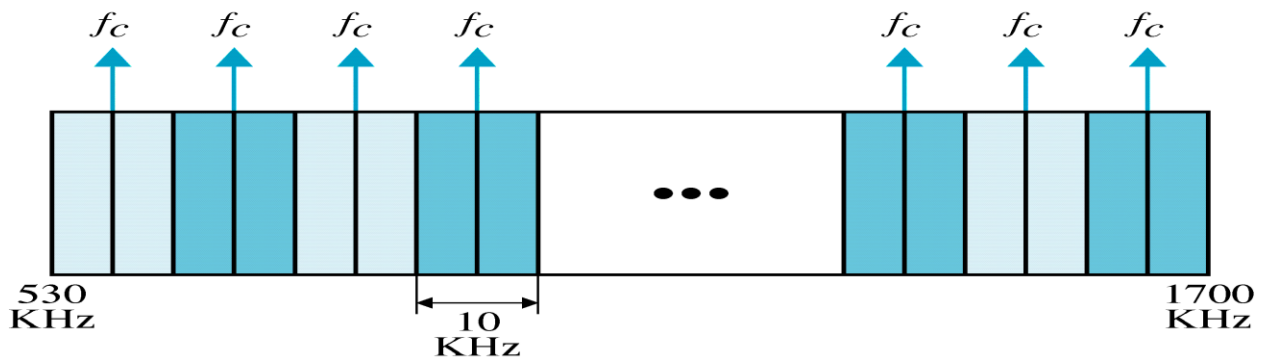
AM Bandwidth

BW_m = Bandwidth of the modulating signal (audio)
 BW_t = Total bandwidth (radio)
 f_c = Frequency of the carrier

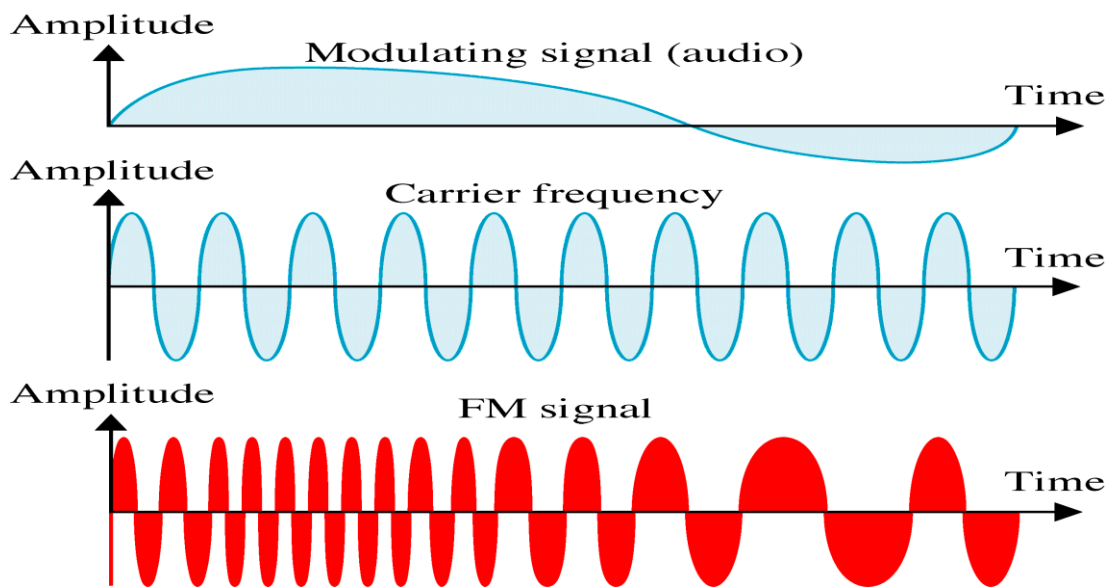


AM Band Allocation

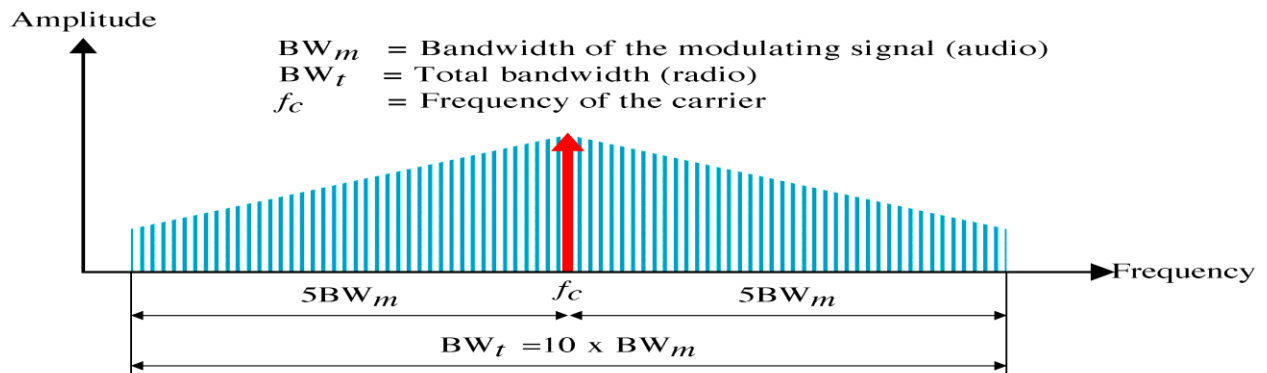
f_c = Carrier frequency of the station



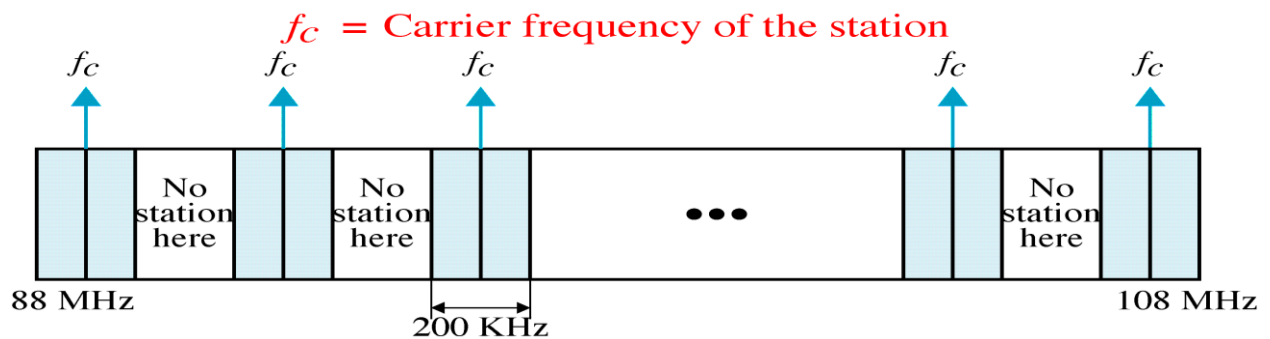
Frequency Modulation(FM)



FM Bandwidth



FM Band Allocation



Phase Modulation(PM)

Due to simpler hardware requirements, phase modulation(PM) is used in some systems as an alternative to frequency modulation.

Digital Data Transmission

Data transmission

- Data needs to be transmitted between devices in a computer system.
- Data is transmitted in the form of bits.
- Data transmission refers to the movement of data in form of bits between two or more digital devices.

DATA TRANSMISSION TYPES

1. Parallel
2. Serial
 - (i) Synchronous
 - (ii) Asynchronous

PARALLEL TRANSMISSION

- In parallel transmission, all the bits of data are transmitted simultaneously on separate communication lines.
- Parallel transmission is used for short distance communication.
- In order to transmit n bit , n wires or lines are used.

- **More costly.**
- **Faster than serial transmission.**
- **Data can be transmitted in less time.**

SERIAL TRANSMISSION

- **In serial transmission , the various bits of data are transmitted serially one after the other.**
- **It requires only one communication line rather than n lines to transmit data from sender to receiver.**
- **Thus all the bits of data are transmitted**
- **on single lines in serial fashion.**
- **Less costly.**
- **Long distance transmission.**

SYNCHRONOUS TRANSMISSION

- **Data sent at one time multiple bytes.**
- **Start and stop bit not used.**
- **Gap between data units not present.**
- **Data transmission speed fast.**
- **Cost high.**
- **Transfer of data between two computer.**
- **Synchronization between sender and receiver required.**

ASYNCHORONOUS TRANSMISSION

- **Sends only one character at a time (one byte of data at a time)**
- **Synchronize two devices using Start Bit and Stop Bit.**
- **Start bit refers to the start of the data. Usually 0 is used for start bit.**
- **Stop bit indicates the end of data. More than one bit can be used for end.**



Data Transmission

	<u>Serial</u>	<u>Parallel</u>
Cost	Cheap	Expensive
Speed	Slow	Fast
Transmission Amount	Single bit	8 bits (8 data lines) Transmitter & Receiver
Transmission Lines	One line to transmit one to receive	8 lines for simultaneous transmission
Transmission Distance	Long distance	Short distance (synchronization)
Example	Modem	Printer Connection

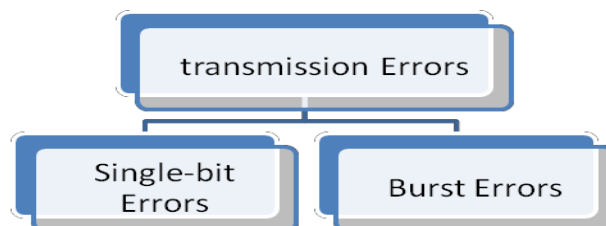
ERRORS, DETECTION & CORRECTION

Errors in the data are basically caused due to the various impairments that occur during the process of transmission. When there is an imperfect medium or environment exists in the transmission it prone to errors in the original data.

Transmission errors are usually detected at the physical layer of the OSI model.

Transmission errors are usually corrected at the data link layer of the OSI model.

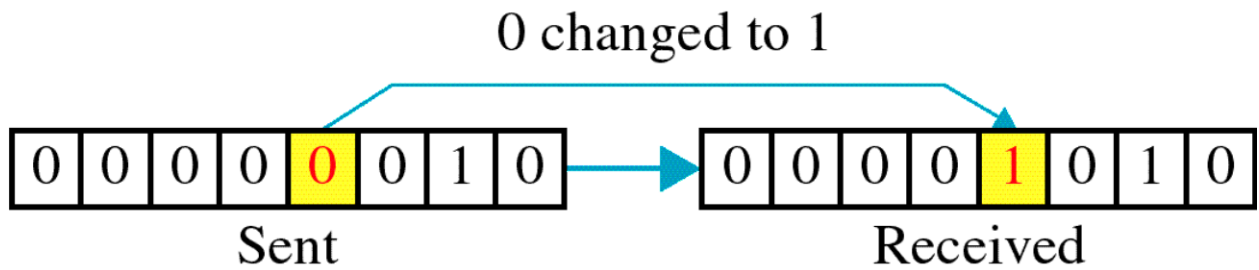
Types of Errors



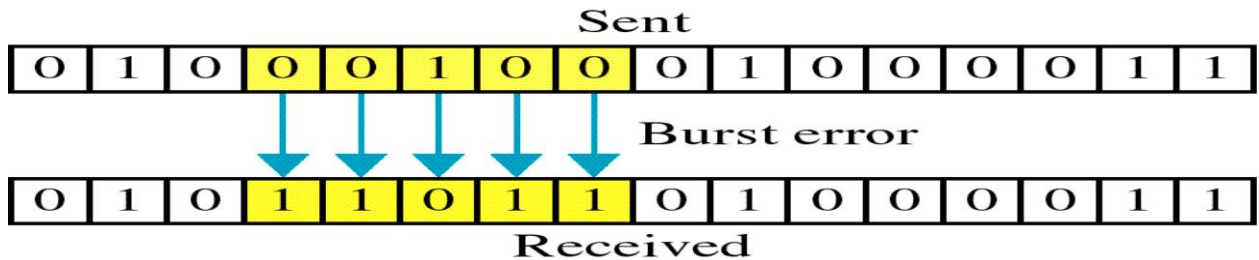
Single-bit: In a single-bit error, only one bit in the data unit has changed.

Burst : A burst error means that two or more bits in the data unit have changed.

Single-bit error



Burst error



DETECTION

Redundancy is one error detection mechanism. Redundancy is the concept of addition of extra bits to a message for error detection. In order to detect and correct the errors in the data communication we add some extra bits to the original data. These extra bits are nothing but the redundant bits which will be removed by the receiver after receiving the data.

Their presence allows the receiver to detect or correct corrupted bits. Instead of repeating the entire data stream, a short group of bits may be attached to the entire data stream. This technique is called redundancy because the extra bits are redundant to the information: they are discarded as soon as the accuracy of the transmission has been determined.

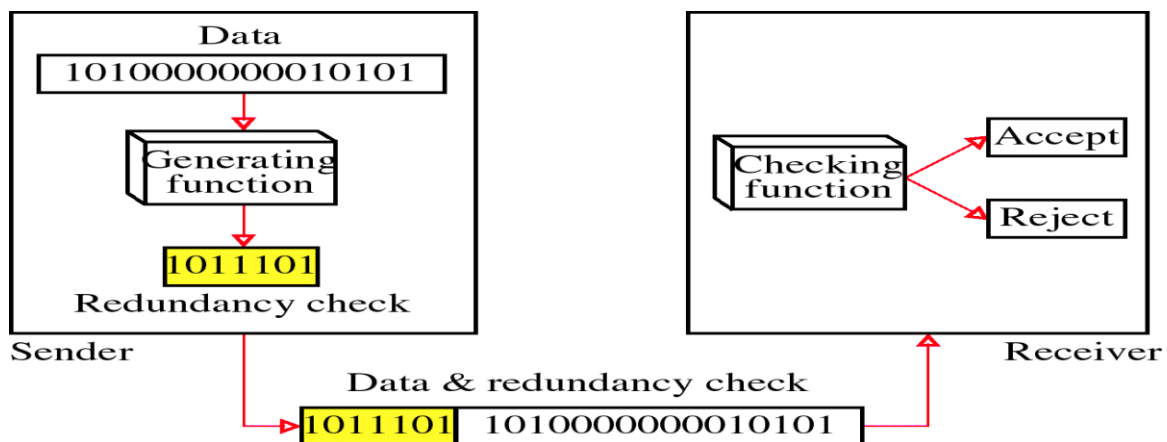


Fig: Redundancy

Four types of redundancy checks follows:

a) Vertical redundancy check (VRC)

- b) Longitudinal redundancy check(LRC)
- c) Cyclic redundancy check(CRC)
- d) Checksum

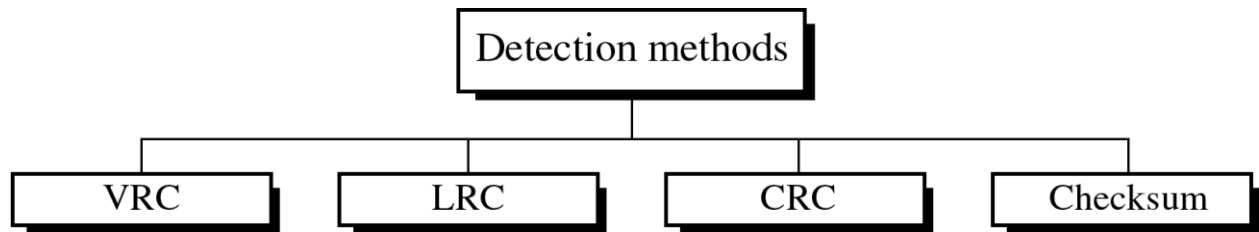
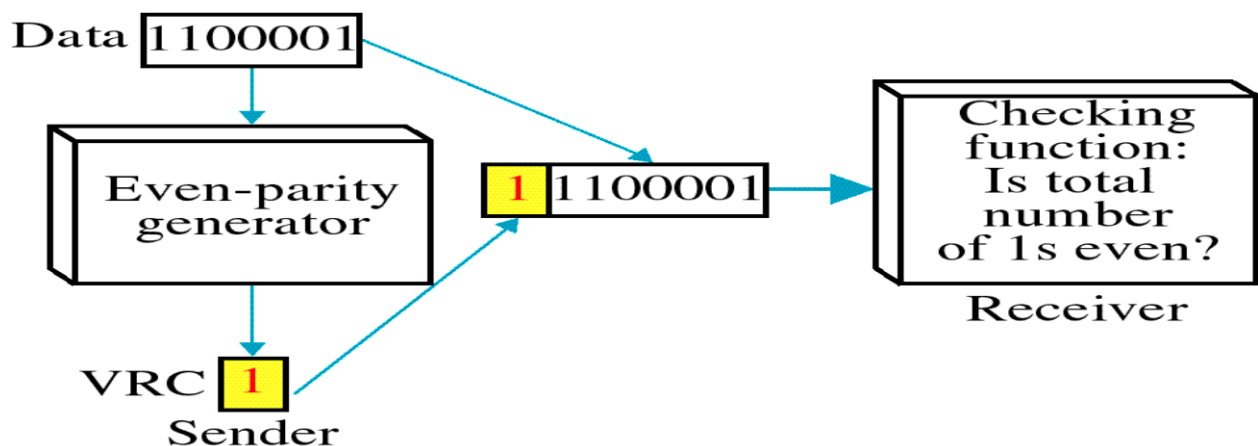


Fig: Redundancy

Vertical redundancy check(VRC)

In this technique, a redundant bit, called a parity bit is added to every data unit so that the total number of 1s becomes even.

Performance: VRC can detect only an odd numbers of errors; it cannot detect an even number of errors.



Example: Imagine the sender wants to send the word "world."

In ASCII the five characters are coded as

```

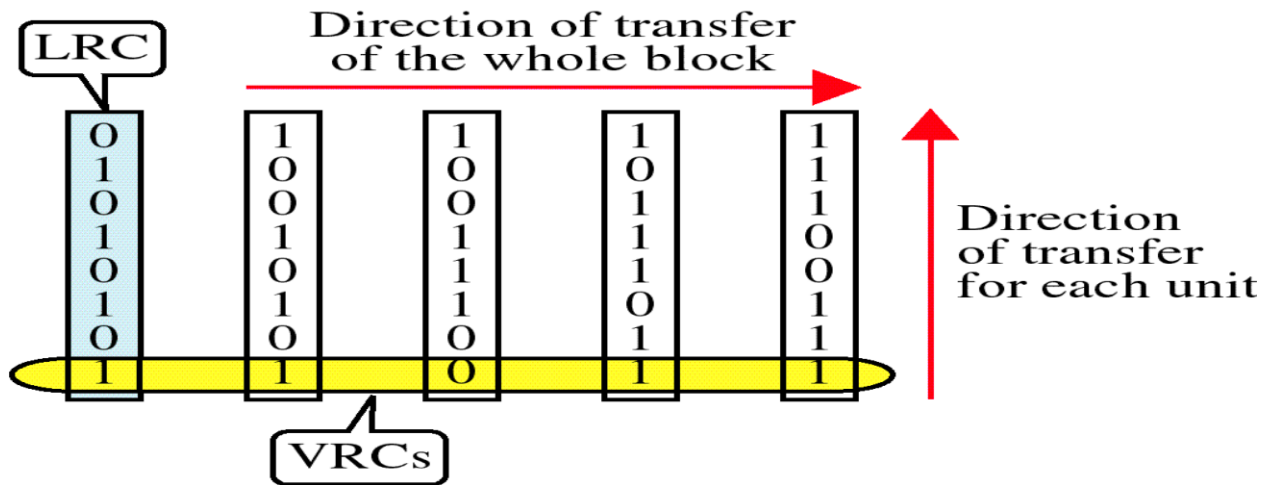
<-----1110111 1101111 1110010 1101100 1100100
          w       o       r       l       d
  
```

Each of the first four characters has an even numbers of 1s, so the parity bit is a 0. The last character("d"), however, has three 1s (an odd number), so the parity bit is a 1 to make the total number of 1s even. The following shows the actual bits sent (the parity bits are underlined)

```

<-----11101110 11011110 11100100 11011000 11001001
          w       o       r       l       d
  
```


VRC and LRC



Cyclic redundancy check(CRC)

CRC, the most powerful of the redundancy checking techniques, is based on binary division. Most powerful of the redundancy checking techniques is the cyclic redundancy check (CRC). This method is based on the binary division. In CRC, the desired sequence of redundant bits are generated and is appended to the end of data unit. It is also called as CRC remainder. So that the resulting data unit becomes exactly divisible by a predetermined binary number.

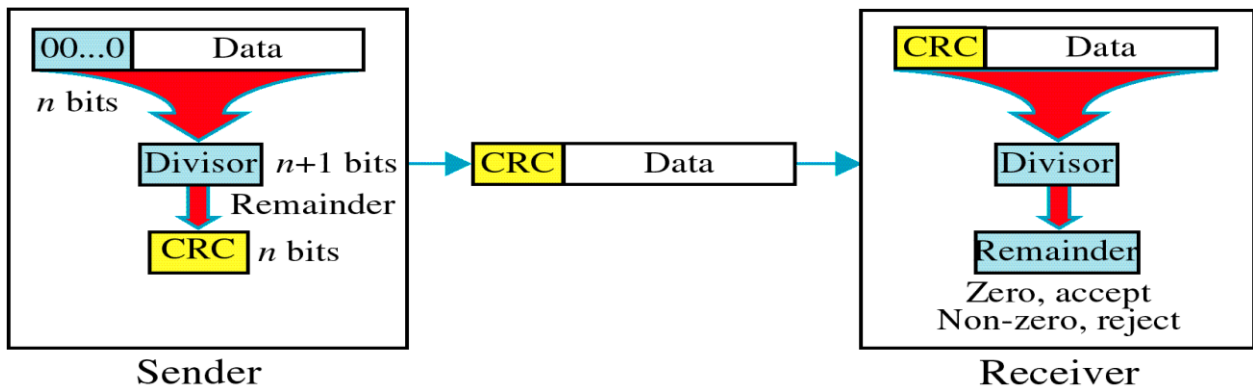
At its destination, the incoming data unit is divided by the same number. If at this step there is no remainder then the data unit

indicates that the data unit has been damaged in transit and therefore must be rejected.

The redundancy bits used by CRC are derived by dividing the data unit by a predetermined divisor; the remainder is the CRC. To be valid, a CRC must have two qualities: It must have exactly one less bit than the divisor, and appending it to the end of the data string must make the resulting bit sequence exactly divisible by the divisor.

The following figure shows the process:

CRC generator and checker

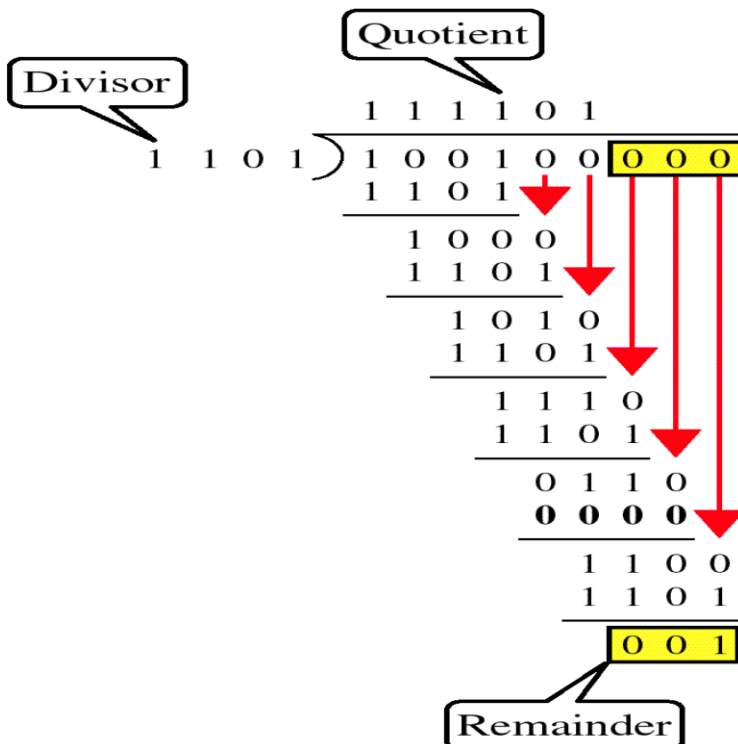


Step1: A string of 0's is appended to the data unit. It is n bits long. The number n is 1 less if-number of bits in the predetermined divisor which is $n + 1$ bits.

Step 2: The newly generated data unit is divided by the divisor, using a process called as binary division. The remainder resulting from this division is the CRC.

Step 3: the CRC of n bits derived in step 2 replaces the appended 0's at the data unit. Note that the CRC may consist of all 0's.

The data unit arrives at the receiver data first, followed by the CRC. The receiver treats the whole string as a unit and divides it by the same divisor that was used the CRC remainder. If the string arrives without error, the CRC checker yields a remainder of zero, the data unit passes. If the string has been changed in transit, the division yields zero remainder and the data unit does not pass.



A CRC checker functions does exactly as the generator does. After receiving the data appended with the CRC, it does the samemodulo-2 division. If the remainder is all 0's, the

CRC is dropped and the data is accepted: otherwise, the received stream of bits is discarded and data is resent.

Performance:

CRC is a very effective error detection method. If the divisor is chosen according to the previously mentioned rules,

1. CRC can detect all burst errors that affect an odd number of bits.
2. CRC can detect all burst errors of length less than or equal to the degree of the polynomial
3. CRC can detect, with a very high probability, burst errors of length greater than the degree of the polynomial.

Checksum

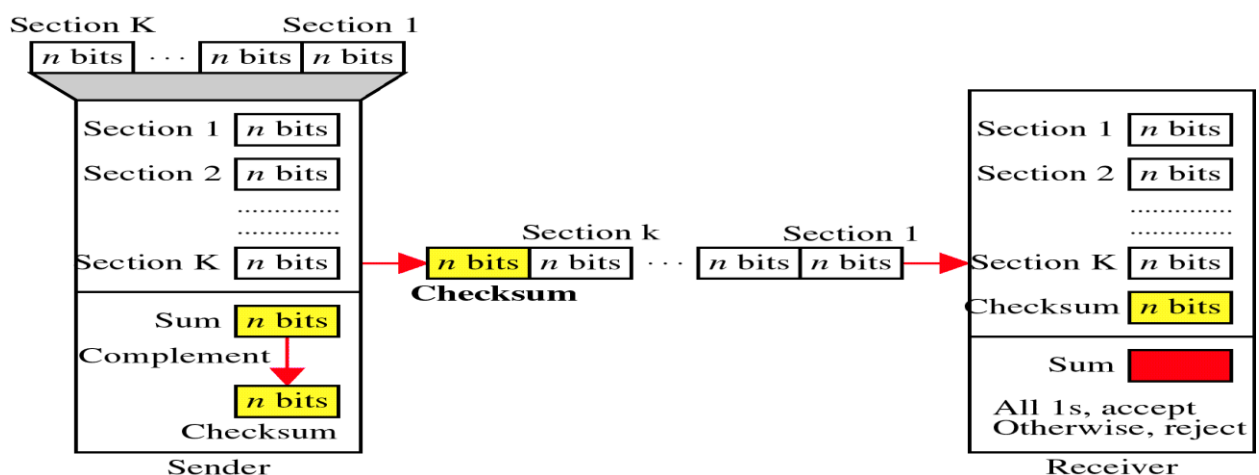
A checksum is fixed length data that is the result of performing certain operations on the data to be sent from sender to the receiver. The sender runs the appropriate checksum algorithm to compute the checksum of the data, appends it as a field in the packet that contains the data to be sent, as well as various headers.

When the receiver receives the data, the receiver runs the same checksum algorithm to compute a fresh checksum. The receiver compares this freshly computed checksum with the checksum that was computed by the sender. If the two checksum matches, the receiver of the data is assured that the data has not changed during the transit.

checksum is used by the higher-layer protocols(TCP/IP) for error detection.

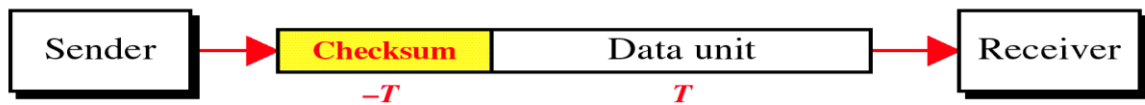
To calculate a checksum:

- a. Divide the data into sections.
- b. Add the sections together using one's complement arithmetic.
- c. Take the complement of the final sum; this is the checksum

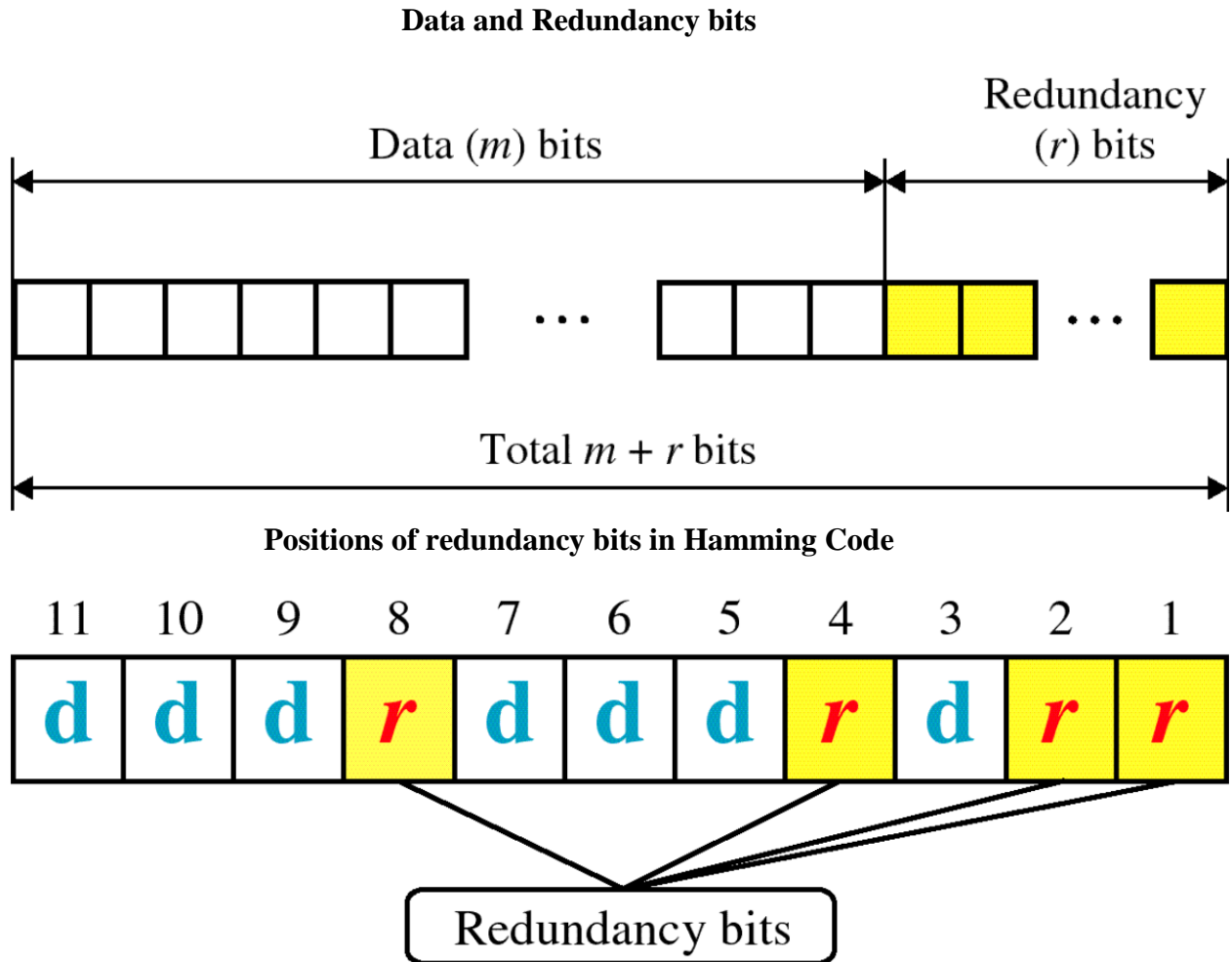


Data Unit and Checksum

The receiver adds the data unit and the checksum field. If the result is all 1s, the data unit is accepted; otherwise it is discarded.



Error Correction



The combinations used to calculate each of the four r values for a seven-bit data sequence are as follows:

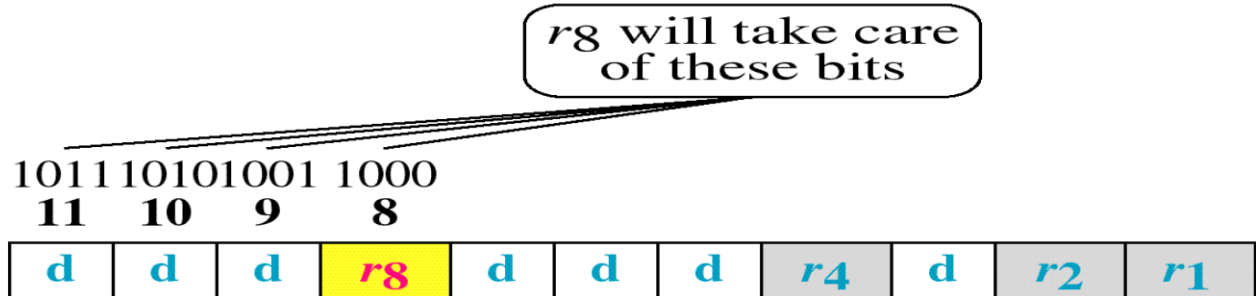
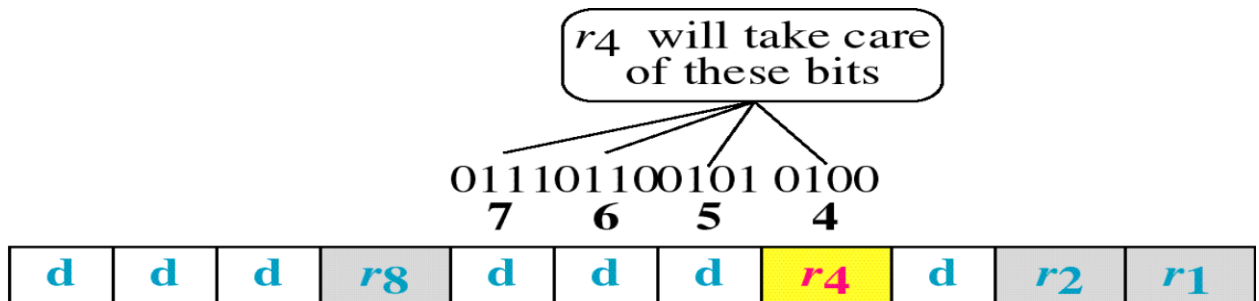
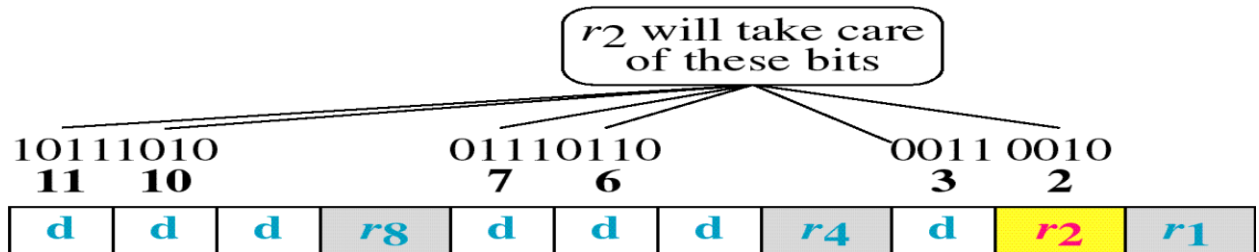
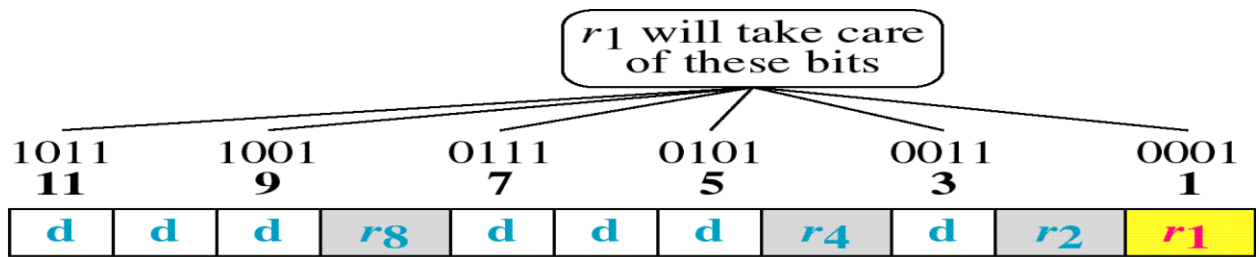
r_1 : bits 1,3,5,7,9,11

r_2 : bits 2,3,6,7,10,11

r_3 : bits 4,5,6,7

r_4 : bits 8,9,10,11

Redundancy bit calculation



Example of redundancy bit calculation

Data: 1 0 0 1 1 0 1



Data	1	0	0		1	1	0		1		
------	---	---	---	--	---	---	---	--	---	--	--

Adding r_1	1	0	0		1	1	0		1		1
--------------	---	---	---	--	---	---	---	--	---	--	---

Adding r_2	1	0	0		1	1	0		1	0	1
--------------	---	---	---	--	---	---	---	--	---	---	---

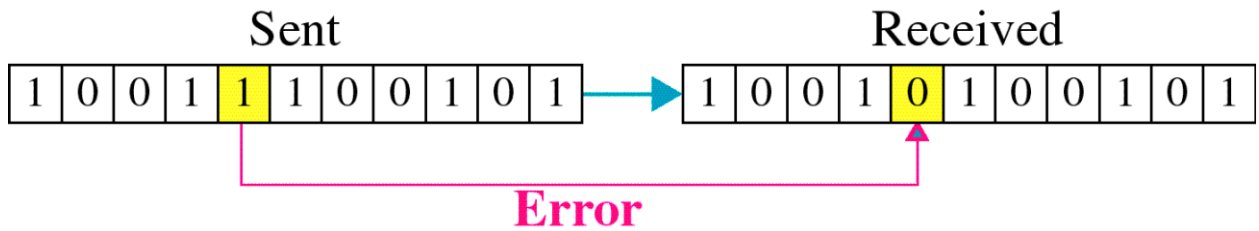
Adding r_4	1	0	0		1	1	0	0	1	0	1
--------------	---	---	---	--	---	---	---	---	---	---	---

Adding r_8	1	0	0	1	1	1	0	0	1	0	1
--------------	---	---	---	---	---	---	---	---	---	---	---

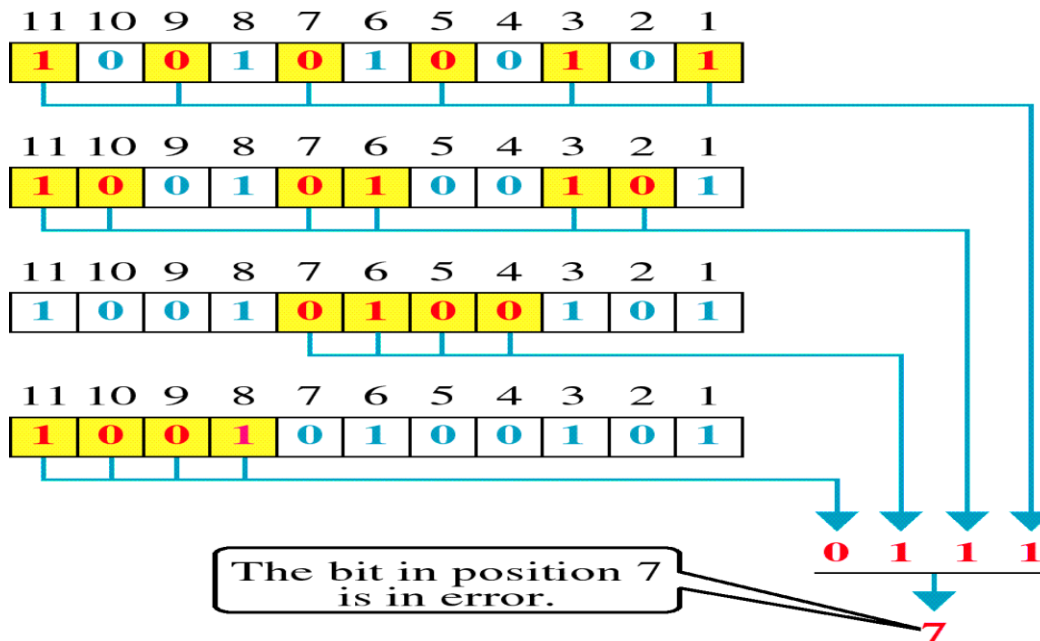


Code: 1 0 0 1 1 1 0 0 1 0 1

Single-bit error

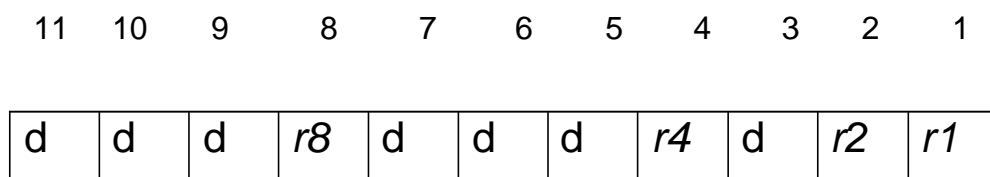


Burst Error Detection



Hamming Code:

The Hamming code can be applied to data units of any length and uses the relationship between data and redundancy bits discussed above. For example, a 7-bit ASCII code requires 4 redundancy bits that can be added to the end of the data unit or interspersed with the original data bits. In following Figure, these bits are placed in positions 1, 2, 4, and 8 (the positions in an 11-bit sequence that are powers of 2). For clarity in the examples below, we refer to these bits as r_1 , r_2 , r_4 , and r_8 .



In the Hamming code, each r bit is the parity bit for one combination of data bits, is shown below:

r1 : bits 1,3,5,7,9,11
 r2 : bits 2,3,6,7,10,11
 r3 : bits 4,5,6,7
 r4 : bits 8,9,10,11

r1 will be assigned to these bits position:

11 9 7 5 3

d	d	d	r8	d	d	d	r4	d	r2	r1
---	---	---	----	---	---	---	----	---	----	----

r2 will be assigned to these bits position:

11 10 7 6 3 2

d	d	d	r8	d	d	d	r4	d	r2	r1
---	---	---	----	---	---	---	----	---	----	----

r4 will be assigned to these bits position:

7 6 5 4

d	d	d	r8	d	d	d	r4	d	r2	r1
---	---	---	----	---	---	---	----	---	----	----

r8 will be assigned to these bits position:

11 10 9 8

d	d	d	r8	d	d	d	r4	d	r2	r1
---	---	---	----	---	---	---	----	---	----	----

Now suppose we have 1001101 data to be sent, then the redundant bits are calculated by the following method:

Data is: 1 0 0 1 1 0 1

11 10 9 8 7 6 5 4 3 2 1

1	0	0		1	1	0		1		
---	---	---	--	---	---	---	--	---	--	--

Adding r1:

11 10 9 8 7 6 5 4 3 2 1

1	0	0		1	1	0		1		1

Adding r2:

11 10 9 8 7 6 5 4 3 2 1

1	0	0		1	1	0		1	0	1
---	---	---	--	---	---	---	--	---	---	---

Adding r4:

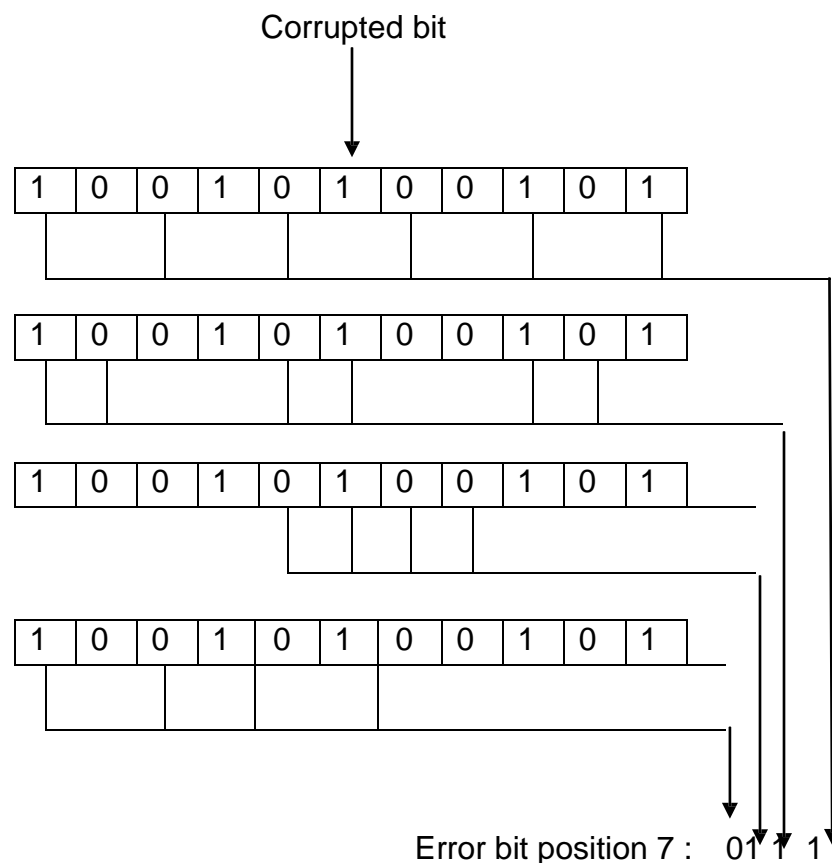
11	10	9		8	7	6	5	4	3	2	1
1	0	0		1	1	0	0	1	0	1	

Adding r8:

11	10	9		8	7	6	5	4	3	2	1
1	0	0	1	1	1	0	0	1	0	1	

Code: 10011100101

Now imagine that by the time the above transmission is received, the number 7 bit has been changed from 1 to 0. The receiver takes the transmission and recalculates 4 new parity bits, using the same sets of bits used by the sender plus the relevant parity r bit for each set (see following Fig.). Then it assembles the new parity values into a binary number in order of r position (r8 r4, r2, r1). In our example, this step gives us the binary number 0111 (7 in decimal), which is the precise location of the bit in error.

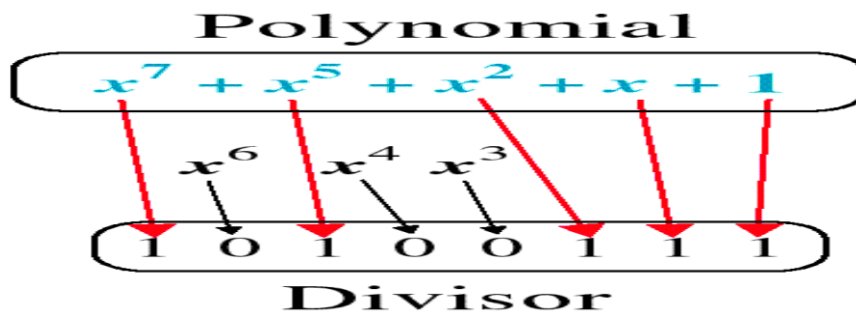


Once the bit is identified, the receiver can reverse its value and correct the error. The beauty of the technique is that it can easily be implemented in hardware and the code is corrected before the receiver knows about it.

Polynomial

$$x^7 + x^5 + x^2 + x + 1$$

Polynomial and Divisor



Standard Polynomials

CRC-12

$$x^{12} + x^{11} + x^3 + x + 1$$

CRC-16

$$x^{16} + x^{15} + x^2 + 1$$

CRC-ITU

$$x^{16} + x^{12} + x^5 + 1$$

CRC-32

$$x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x + 1$$

TRANSMISSION MODES

Data is transmitted between two digital devices on the network in the form of bits.

Transmission mode refers to the mode used for transmitting the data. The transmission medium may be capable of sending only a single bit in unit time or multiple bits in unit time. When a single bit is transmitted in unit time the transmission mode used is Serial Transmission and when multiple bits are sent in unit time the transmission mode used is called Parallel transmission.

Types of Transmission Modes:

There are two basic types of transmission modes Serial and Parallel as shown in the figure below.

Serial transmission is further categorized into Synchronous and Asynchronous Serial transmission.

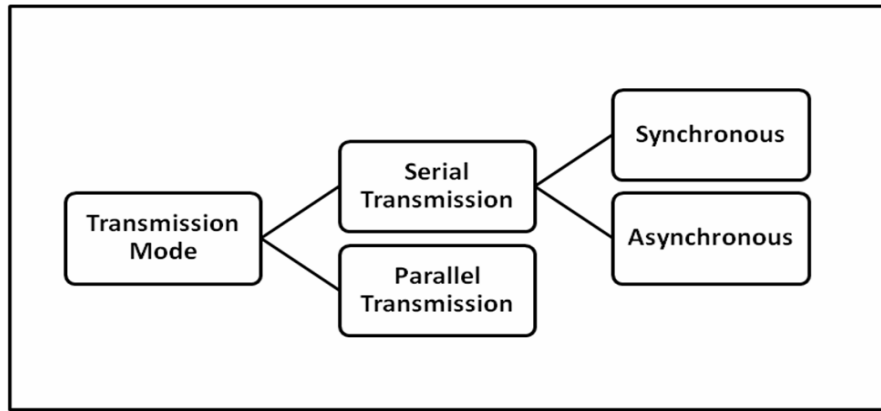


Fig. Types of Transmission Modes

Parallel Transmission

It involves simultaneous transmission of N bits over N different channels. Parallel Transmission increases transmission speed by a factor of N over serial transmission. Disadvantage of parallel transmission is the cost involved, N channels have to be used, hence, it can be used for short distance communication only.

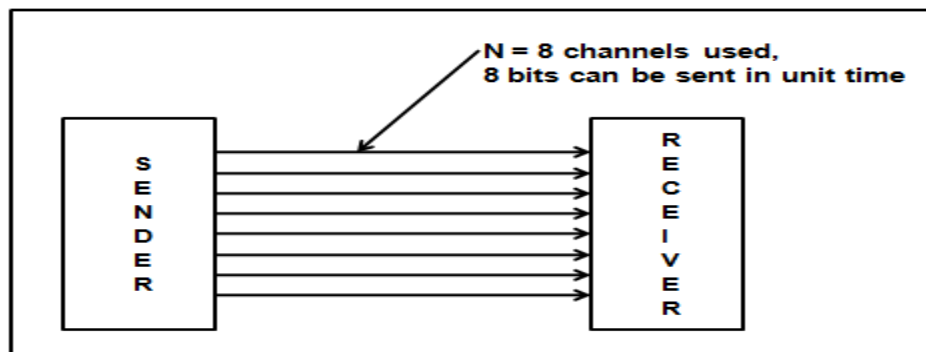


Fig. Parallel Transmission of Data over $N = 8$ channels

Example of Parallel Transmission is the communication between CPU and the Projector.

Serial Transmission

In Serial Transmission, as the name suggests data is transmitted serially, i.e. bit by bit, one bit at a time. Since only one bit has to be sent in unit time only a single channel is required.

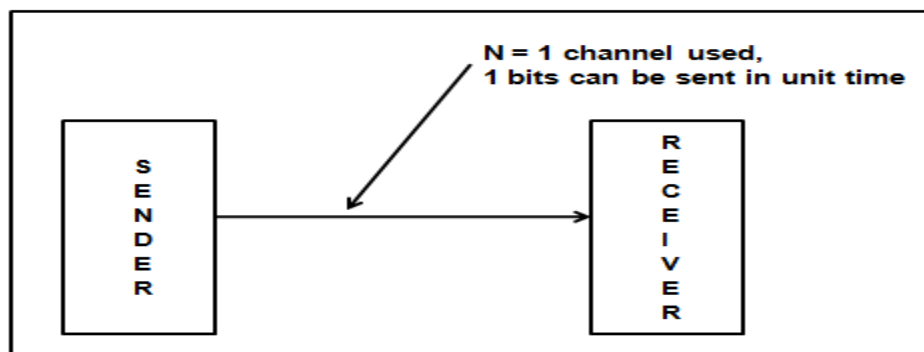


Fig. Serial Transmission of Data over N = 8 channels

Types of Serial Transmission:

Depending upon the timing of transmission of data there are two types of serial transmission as described below

ASynchronous Transmission

In asynchronous serial transmission the sender and receiver are not synchronized. The data is sent in group of 8 bits i.e. in bytes. The sender can start data transmission at any time instant without informing the receiver. To avoid confusing the receiver while receiving the data, —start and —stop bits are inserted before and after every

group of 8 bits as shown below

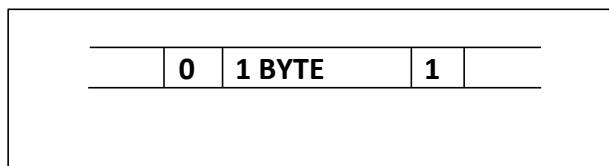


Fig: Start and Bit before and after every data byte

The start bit is indicated by 0 and stop bit is indicated by 1. The sender and receiver may not be synchronized as seen above but at the bit level they have to be synchronized i.e. the duration of one bit needs to be same for both sender and receiver for accurate data transmission. There may be gaps in between the data transmission indication that there is no data being transmitted from sender. Ex. Assume a user typing at uneven speeds, at times there is no data being transmitted from Keyboard to the CPU. Following is the Diagram for Asynchronous Serial

Transmission.

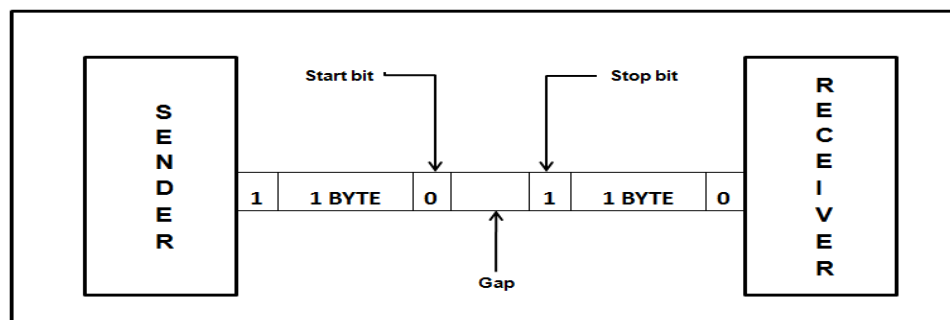


Fig: Asynchronous Serial Transmission

Advantages

1. Cheap and Effective implementation
2. Can be used for low speed communication

Disadvantages

Insertion of start bits, stop bits and gaps make asynchronous transmission slow.

Application

Keyboard

Synchronous Transmission

In Synchronous Serial Transmission, the sender and receiver are highly synchronized. No start, stop bits are used. Instead a common master clock is used for reference. The sender simply send stream of data bits in group of 8 bits to the receiver without any start or stop bit. It is the responsibility of the receiver to regroup the bits into units of 8 bits once they are received. When no data is being transmitted a sequence of 0's and 1's indicating IDLE is put on the transmission medium by the sender.

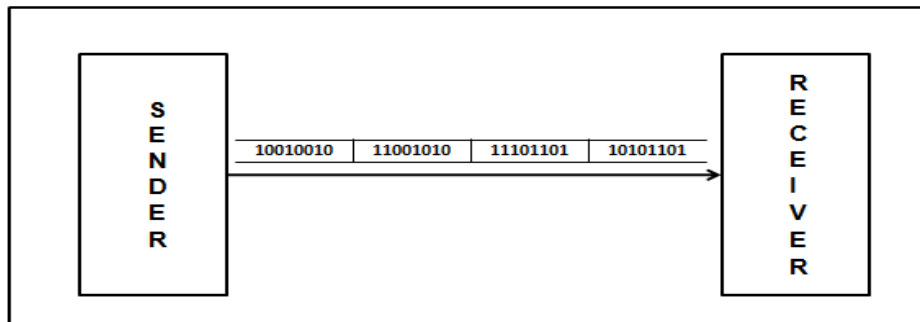


Fig: Asynchronous Serial Transmission

Advantage

1. There are no start bits, stop bits or gaps between data units
2. Since the above are absent data transmission is faster.
3. Due to synchronization there are no timing errors.

9.2.2.3 Comparison of serial and parallel transmission

Sr.no	Parameter	Parallel transmission	Serial transmission
1	Number of wire required to transmit N bits	N wire	1 wire
2	Number of bits transmitted simultaneously	N bits	1 bit
3	Speed of data transfer	False	Slow
4	Cost	Higher due to more number of conductor	Low, since only one wire is used
5	Application	Short distance communication such as computer to printer communication	Long distance computer to computer communication.

Data-Link Protocols

Data-Link Protocol Functions

Line discipline – coordinates hop-to-hop data delivery where a hop is a computer, a network controller, or some type of network-connecting device, such as router

It determines which device is transmitting and which is receiving at any point in time

Flow control – the rate at which data is transported over a link

--provides an acknowledgement mechanism that data is received at the destination

--regulate flow of data from sender to receiver

Error control – detects and corrects transmission errors

Framing – recognizing beginning and end of frames (blocks, packets)

Communications requires at least two devices, one to send and one to receive. If both devices are ready to send some information and put their signals on the link then the two signals collide each other and become nothing. To avoid such a situation the data link layer uses a mechanism called line discipline.

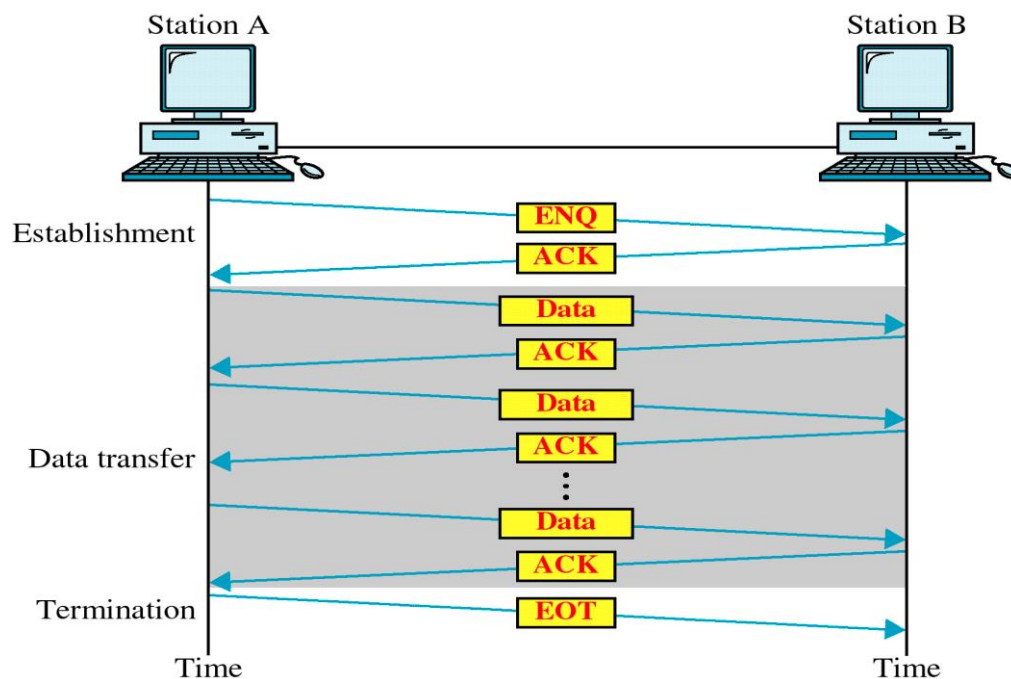
Line discipline coordinates the link system. It determines which device can send and when it can send. It answers the question, who should send now?

Line discipline can serve in two ways:

1. enquiry / acknowledgement (ENQ / ACK)
2. poll / select (POLL / SELECT)

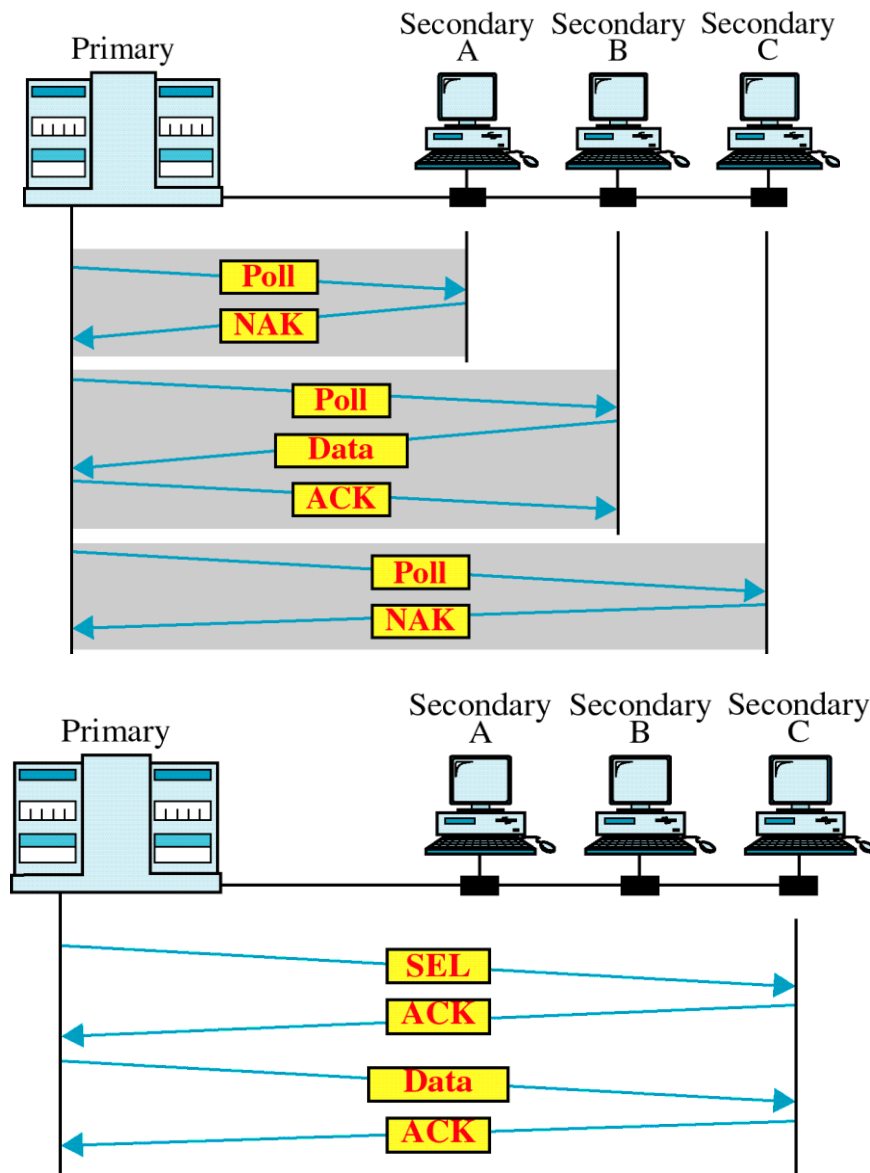
ENQ / ACK:

This method is used in peer-to-peer communications. That is where there is a dedicated link between two devices. The initiator first transmits a frame called an enquiry (ENQ) asking if the receiver is available to receive data. The receiver must answer either with an acknowledgement (ACK) frame if it is ready to accept or with a negative acknowledgement (NAK) frame if it is not ready. If the response is positive, the initiator is free to send its data. Otherwise it waits, and tries again. Once all its data have been transmitted, the sending system finishes with an end of transmission (EOT) frame. Line discipline



Example of ENQ/ACK line discipline

POLL/SELECT:

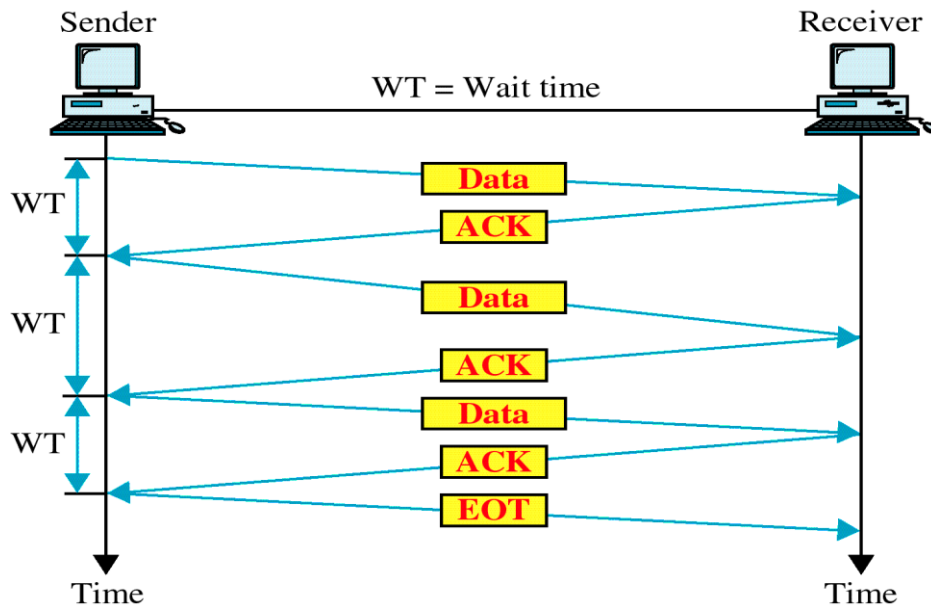


Example of poll/select line discipline

Flow control

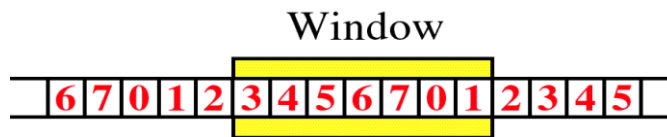
Stop-and-Wait flow control

- Source transmits frame
- Destination receives frame and replies with acknowledgement
- Source waits for ACK before sending next frame
- Destination can stop flow by not send ACK
- Works well for a few large frames



Example of Stop-and-Wait flow control

Sliding Window flow control



Error Control

Detection and correction of errors

Lost frames

Damaged frames

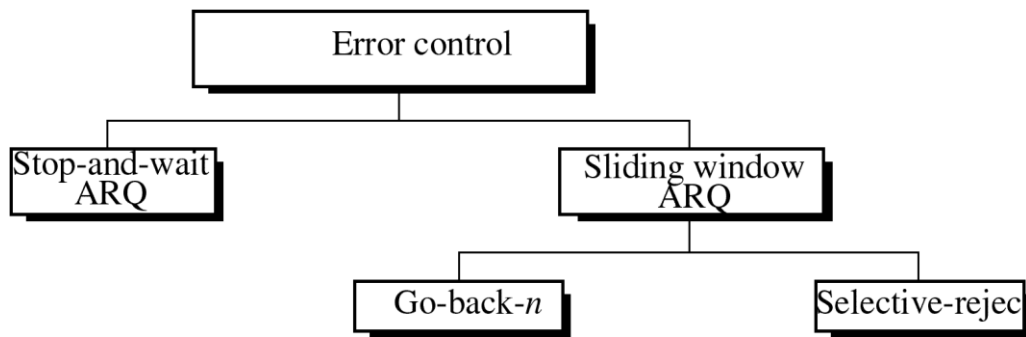
Techniques for error control (Automatic repeat request)

--Error detection

--Positive acknowledgment

--Retransmission after timeout

--Negative acknowledgement and retransmission



FLOW CONTROL AND ERROR CONTROL

FLOW CONTROL

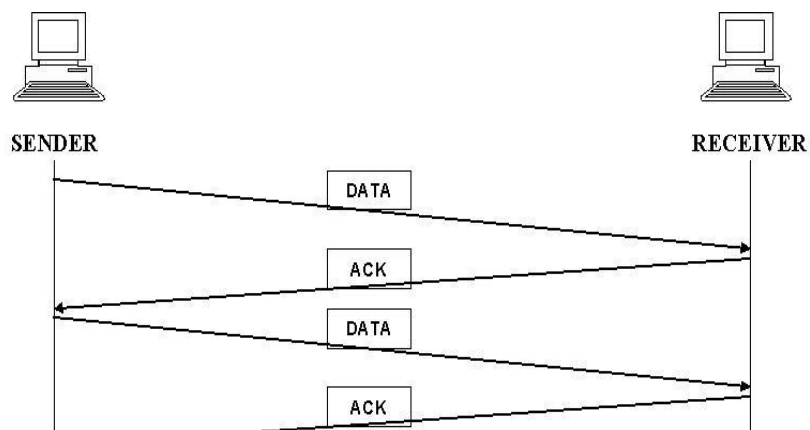
It refers to a set of procedures used to restrict the amount of data flow between sending and receiving stations. It tells the sender how much data it can transmit before it must wait for an acknowledgement from the receiver.

There are two methods are used. They are,

1. stop and wait
2. sliding window

STOP AND WAIT:

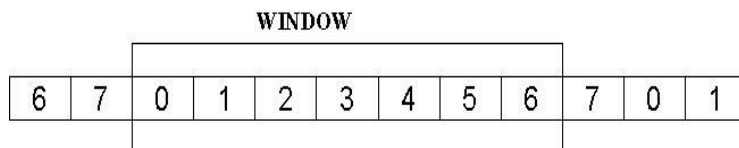
In this method the sender waits for acknowledgment after every frame it sends. Only after an acknowledgment has been received, then the sender sends the next frame.



The advantage is simplicity. The disadvantage is inefficiency
SLIDING WINDOW:

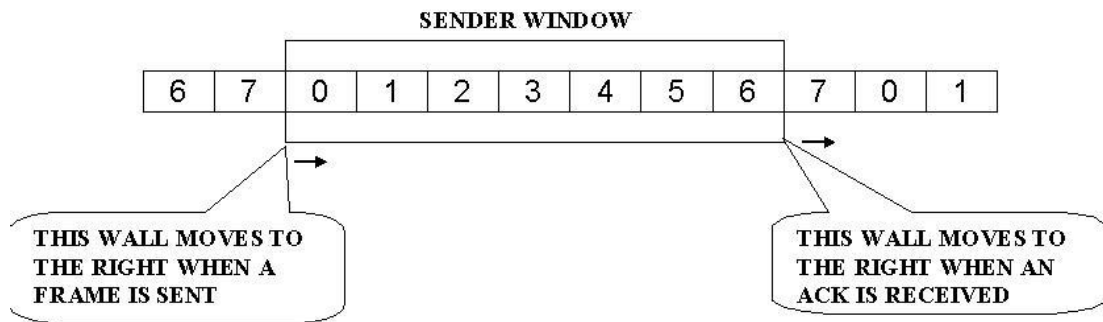
In this method, the sender can transmit several frames before needing an acknowledgment. The receiver acknowledges only some of the frames, using a single ACK to confirm the receipt of multiple data frames.

The sliding window refers to imaginary boxes at both the sender and receiver. This window provides the upper limit on the number of frames that can be transmitted before requiring an acknowledgement. To identify each frame the sliding window scheme introduces the sequence number. The frames are numbered as 0 to n-1. And the size of the window is n-1. Here the size of the window is 7 and the frames are numbered as 0,1,2,3,4,5,6,7.

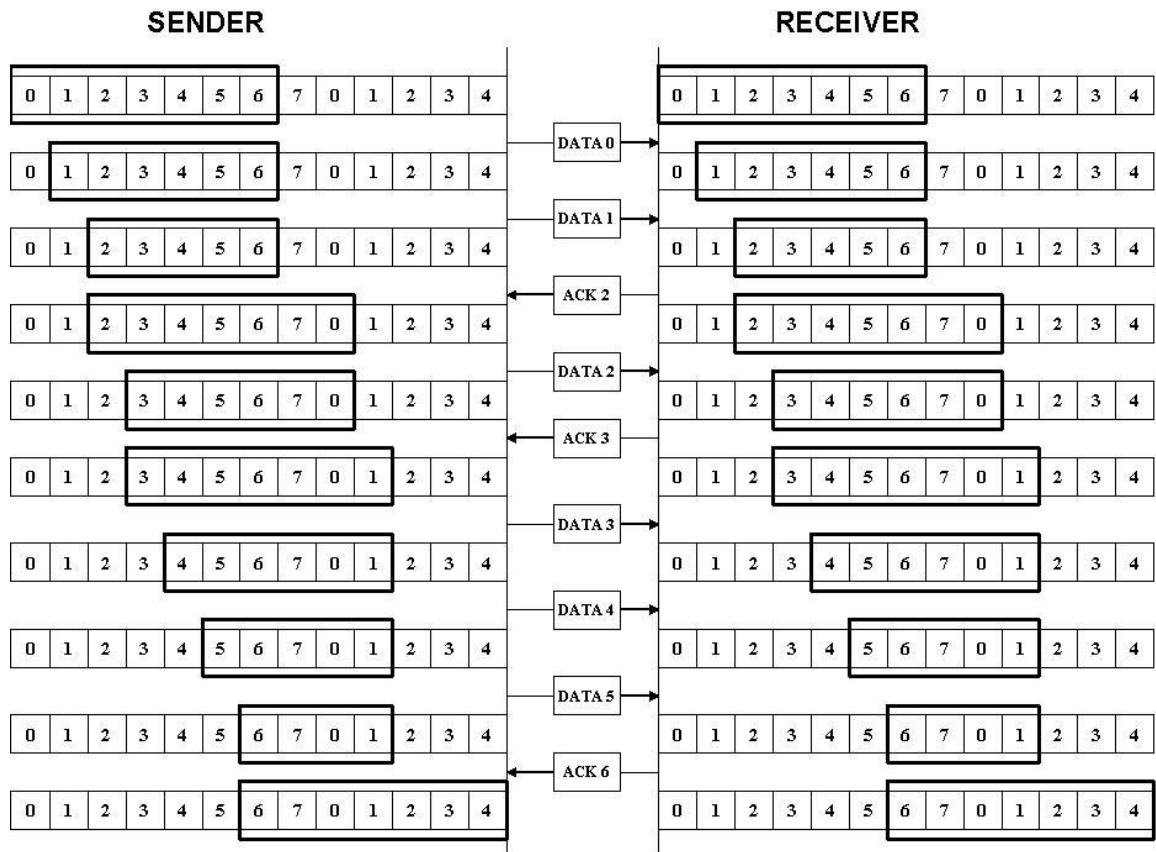


SENDER WINDOW:

At the beginning the sender's window contains n-1 frames. As frames are sent out the left boundary of the window moves inward, shrinking the size of the window. Once an ACK receives the window expands at the right side boundary to allow in a number of new frames equal to number of frames acknowledged by that ACK.



EXAMPLE:



ERROR CONTROL

Error control is implemented in such a way that every time an error is detected, a negative acknowledgement is returned and the specified frame is retransmitted. This process is called **automatic repeat request (ARQ)**.

The error control is implemented with the flow control mechanism. So there are

two types in error control. They are,

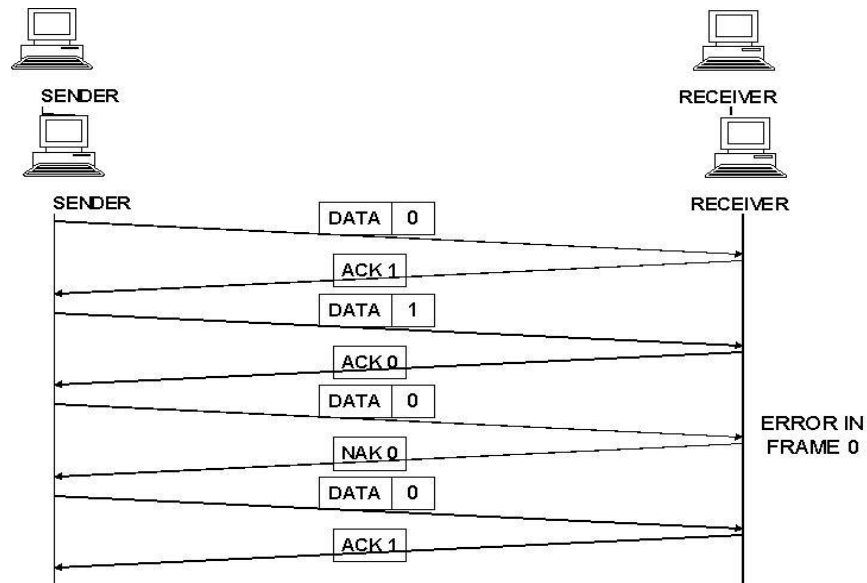
1. stop and wait ARQ
2. sliding window ARQ

STOP AND WAIT ARQ:

It is a form of stop and wait flow control, extended to include retransmission of data in case of lost or damaged frames.

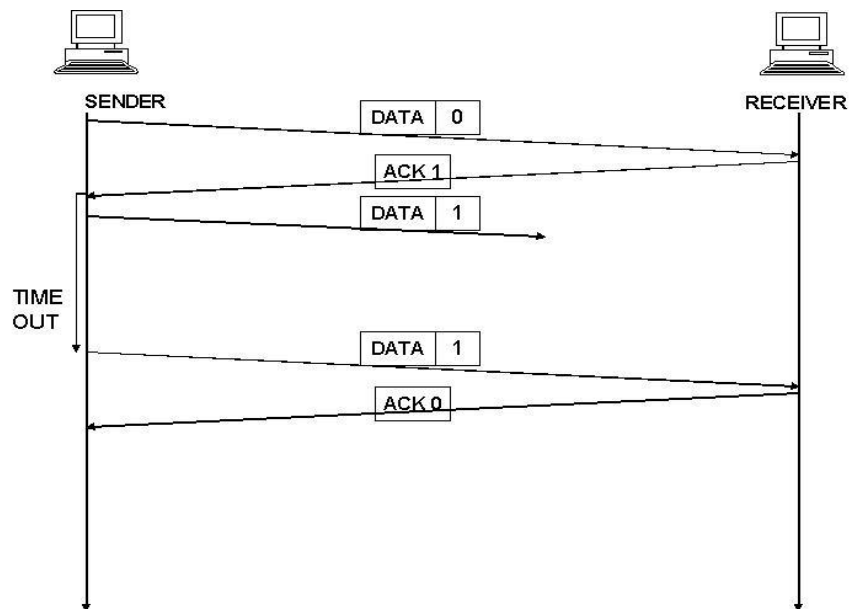
DAMAGED FRAME:

When a frame is discovered by the receiver to contain an error, it returns a NAK frame and the sender retransmits the last frame.



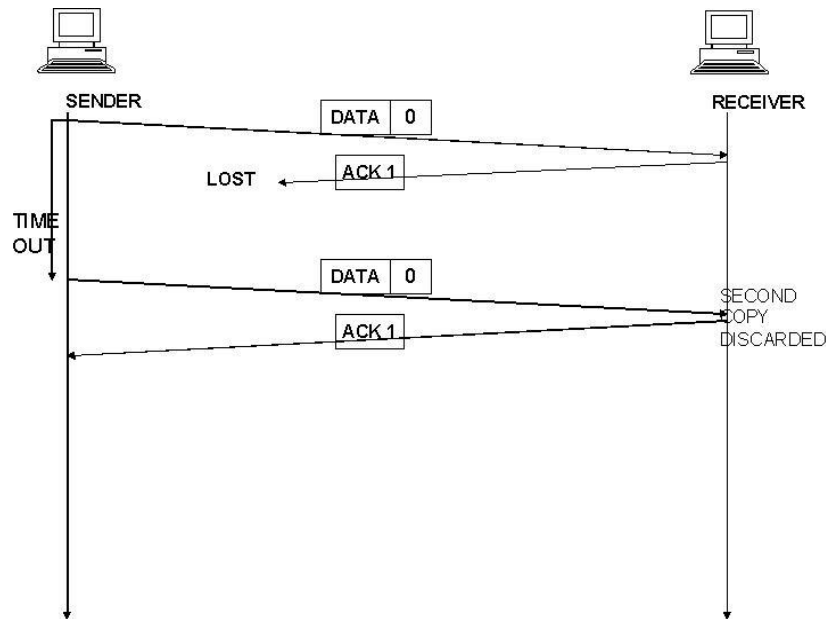
LOST DATA FRAME:

The sender is equipped with a timer that starts every time a data frame is transmitted. If the frame is lost in transmission the receiver can never acknowledge it. The sending device waits for an ACK or NAK frame until its timer goes off, then it tries again. It retransmits the last data frame.



LOST ACKNOWLEDGEMENT:

The data frame was received by the receiver but the acknowledgement was lost in transmission. The sender waits until the timer goes off, then it retransmits the data frame. The receiver gets a duplicated copy of the data frame. So it knows the acknowledgement was lost so it discards the second copy.



SLIDING WINDOW ARQ

It is used to send multiple frames per time. The number of frame is according to the window size. The sliding window is an imaginary box which is reside on both sender and receiver side.

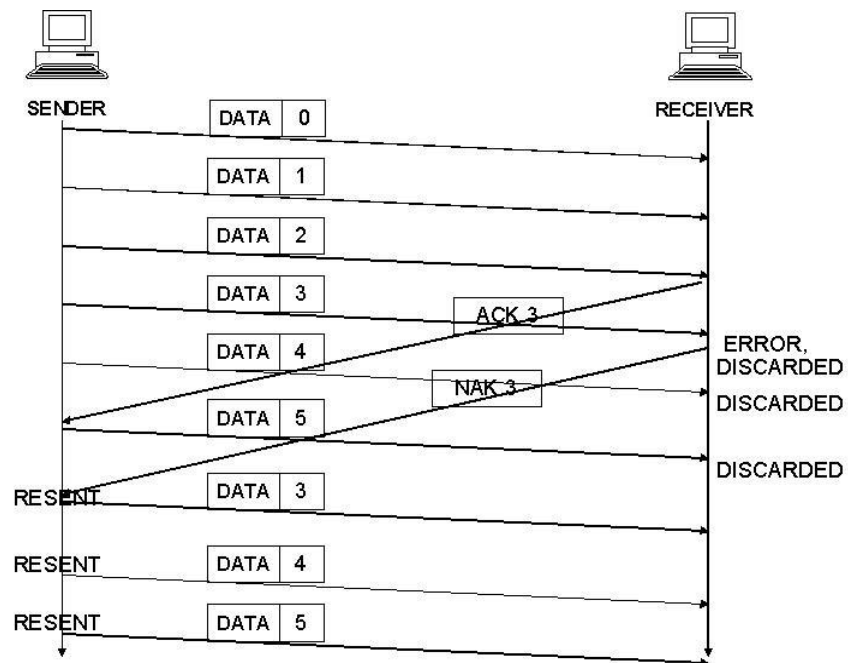
It has two types. They are,

1. go-back-n ARQ
2. selective reject ARQ

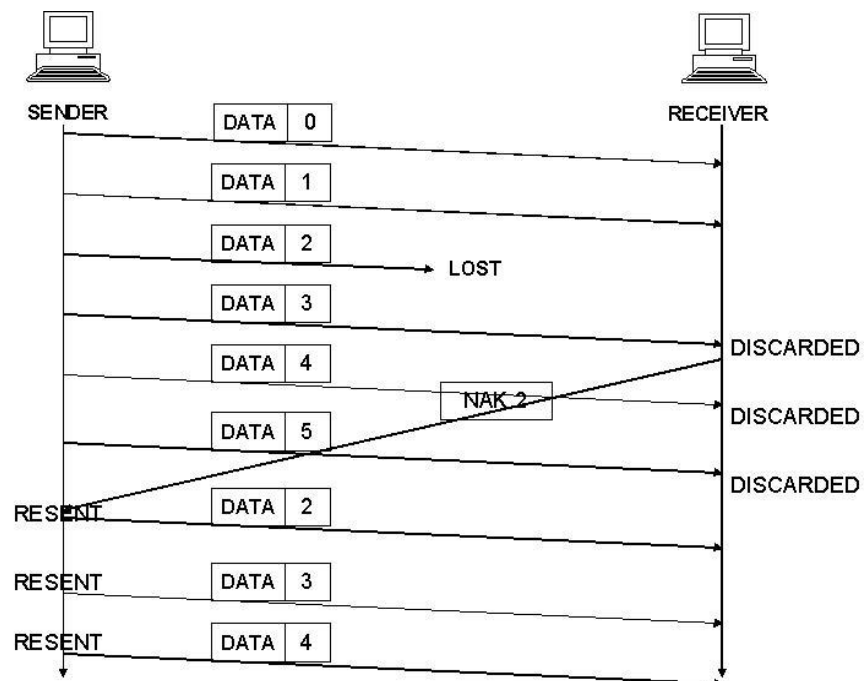
GO-BACK-N ARQ:

In this method, if one frame is lost or damaged, all frames sent since the last frame acknowledged or retransmitted.

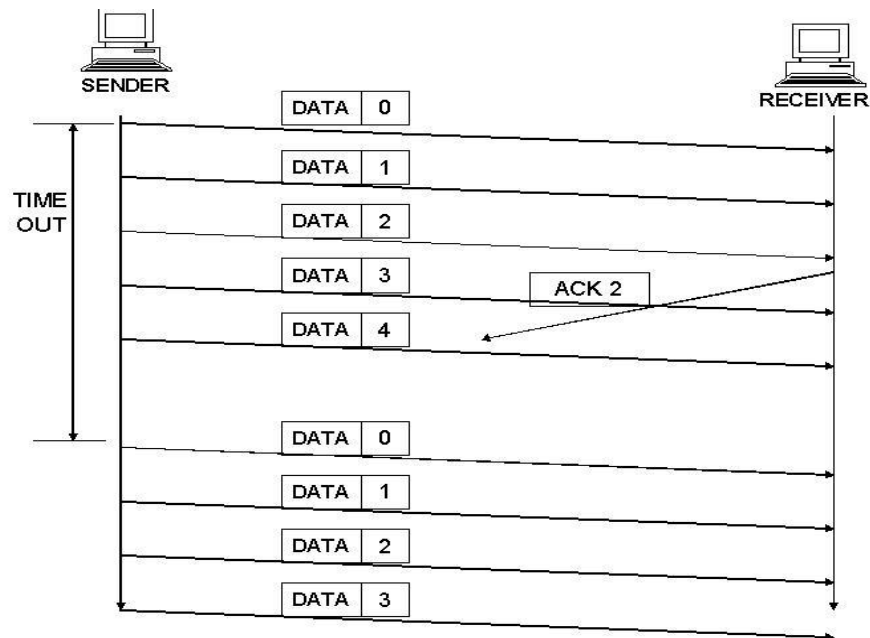
DAMAGED FRAME:



LOST FRAME:



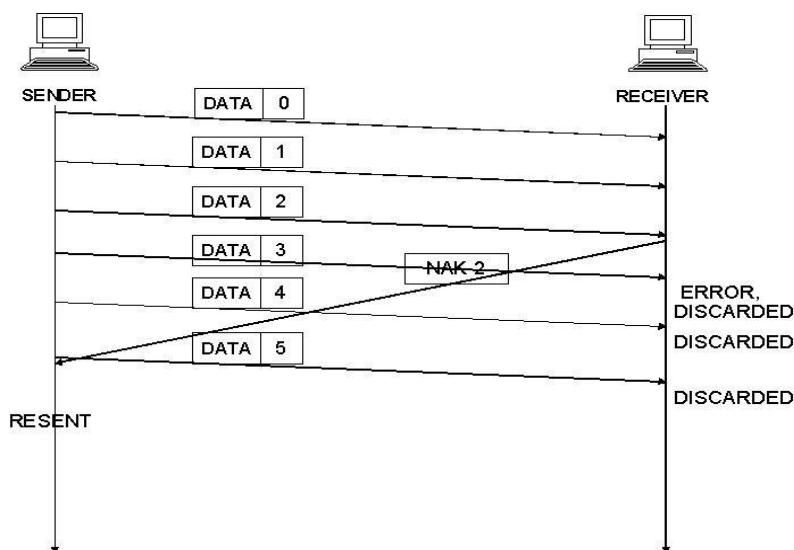
LOST ACK:



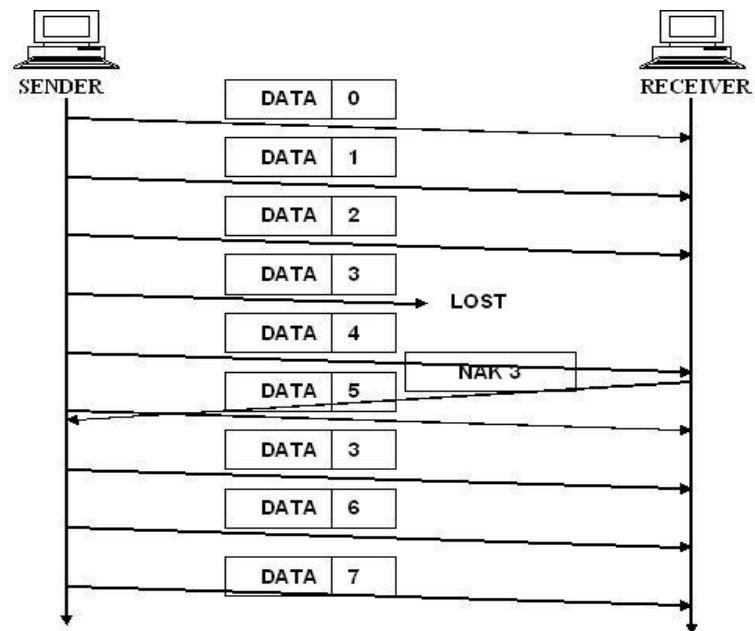
SELECTIVE REPEAT ARQ

Selective repeat ARQ retransmits only the damaged or lost frames instead of sending multiple frames. The selective transmission increases the efficiency of transmission and is more suitable for noisy link. The receiver should have sorting mechanism.

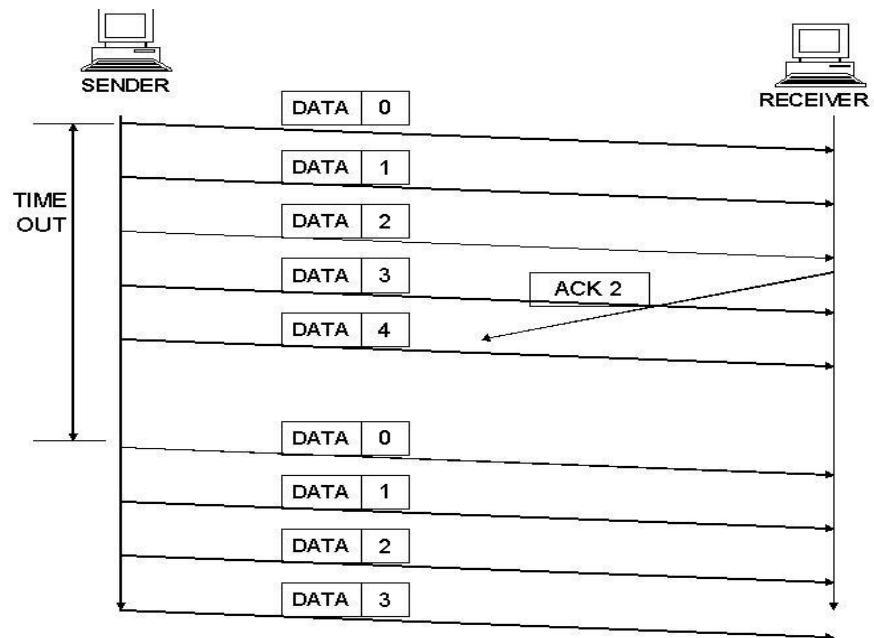
DAMAGED FRAME:



LOST FRAME



LOST ACK



1. What do you mean by Automatic Repeat Request (ARQ)?

ARQ means retransmission of data in three cases:

- Damaged Frame
- Lost Frame
- Lost Acknowledge

2. What are the responsibilities of Data Link Layer?

The Data Link Layer transforms the physical layer, a raw transmission facility, to a reliable link and is responsible for node-node delivery.

- Framing
- Physical Addressing
- Flow Control
- Error Control
- Access Control

3. What are the three protocols used for noisy channels?

The three protocols used for noisy channels

- Stop – and – Wait ARQ
- Go – back – N ARQ
- Selective Repeat ARQ

4. What is CSMA/CD?

Carrier Sense Multiple Access with Collision Detection is a protocol used to sense whether a medium is busy before transmission and it also has the ability to detect whether the packets has collided with another

5. What are the various types of connecting devices?

There are five types of connecting devices

- Repeaters
- Hubs
- Bridges
- Routers
- Switches.

6. Define Flow control

It refers to a set of procedures used to restrict the amount of data the sender can send before waiting for an acknowledgement

7. What are the categories of Flow control?

The categories of Flow control are

- Stop& wait
- Sliding Window

8. Mention the disadvantages of stop& wait.

- Inefficiency
- Slow process

9. What are the functions of data link layer?

The functions of data link layer are

- Flow control
- Error control

10. Define Link Discipline

It coordinates the link system. It determines which device can send and when it can send.

11. What do you mean by polling?

When the primary device is ready to receive data, it asks the secondary to send data. This is called polling.

12.What are the various controlled access methods?

The various controlled access methods are

- Reservation
- Token passing
- Polling

13 What are the various Random access methods?

The various Random access methods are

- Slotted ALOHA
- CSMA
- CSMA/CD,CSMA/CA

14. Define Piconet

A Bluetooth network is called Piconet .It can have up to eight stations one of which is called the master and the rest are called slaves,

15. What is the frequency range of Bluetooth devices?

The frequency range of Bluetooth device is 2.4 GHZ

16. What is the need of connecting devices?

To connect LANs or segments of LAN we use connecting devices. These devices can operate in different layers of internet model.

17. What type of address a data link layer is using?

The data link layer is using a physical address

18. What do you mean by Backbone networks?

It allows several LANs to be connected. The architecture used are Star and Bus

19. What is the need of frame relay?

It is a Virtual circuit wide area network that was designed to respond to demands for a new type of WAN.

20. What is the maximum length of a datagram?

The maximum length of a datagram is 65,535 bytes.

21. What are the key functions of error control techniques?

Ans: There are basically two types of errors, namely, (a) Damaged Frame (b) Lost Frame. The key functions for error control techniques are as follows:

- Error detection

- Sending of positive acknowledgement (ACK) by the receiver for no error

- Sending of negative acknowledgement (NAK) by the receiver for error

- Setting of timer for lost frame

- Numbering of frames

22. Why is flow control needed?

Ans: In case of data communication between a sender and a receiver, it may so happen that the rate at which data is transmitted by a fast sender is not acceptable by a slow receiver. IN such a situation, there is a need of flow control so that a fast transmitter does not overwhelm a slow receiver.

23. Mention key advantages and disadvantages of stop-and-wait ARQ technique?

Ans: Advantages of stop-and-wait ARQ are:

- a. Simple to implement
- b. Frame numbering is modulo-2, i.e. only 1 bit is required.

The main disadvantage of stop-and-wait ARQ is that when the propagation delay is long, it is extremely inefficient.

24. Consider the use of 10 K-bit size frames on a 10 Mbps satellite channel with 270 ms delay. What is the link utilization for stop-and-wait ARQ technique assuming $P = 10^{-3}$?

Ans: Link utilization = $(1-P) / (1+2a)$

Where $a = (\text{Propagation Time}) / (\text{Transmission Time})$

Propagation time = 270 msec

Transmission time = $(\text{frame length}) / (\text{data rate})$

= $(10 \text{ K-bit}) / (10 \text{ Mbps})$

= 1 msec

Hence, $a = 270/1 = 270$

Link utilization = $0.999/(1+2*270) \approx 0.0018 = 0.18\%$

25. What is the channel utilization for the go-back-N protocol with window size of 7 for the problem 3?

Ans: Channel utilization for go-back-N

= $N(1 - P) / (1 + 2a)(1-P+NP)$

P = probability of single frame error $\approx 10^{-3}$

Channel utilization $\approx 0.01285 = 1.285\%$

26. In what way selective-repeat is better than go-back-N ARQ technique?

Ans : In selective-repeat scheme only the frame in error is retransmitted rather than transmitting all the subsequent frames. Hence it is more efficient than go-back-N ARQ technique.

27. In what situation Stop-and-Wait protocol works efficiently?

Ans: In case of Stop-and-Wait protocol, the transmitter after sending a frame waits for the acknowledgement from the receiver before sending the next frame. This protocol works efficiently for long frames, where propagation time is small compared to the transmission time of the frame.

28. How the inefficiency of Stop-and-Wait protocol is overcome in sliding window protocol?

Ans: The Stop-and-Wait protocol is inefficient when large numbers of small packets are sent by the transmitter since the transmitter has to wait for the acknowledgement of each individual packet before sending the next one. This problem can be overcome by sliding window protocol. In sliding window protocol multiple frames (up to a fixed number of frames) are sent before receiving an acknowledgement from the receiver.

30. What is piggybacking? What is its advantage?

Ans: In practice, the link between receiver and transmitter is full duplex and usually both transmitter and receiver stations send data to each other. So, instead of sending separate acknowledgement packets, a portion (few bits) of the data frames can be used for acknowledgement. This phenomenon is known as piggybacking.

The piggybacking helps in better channel utilization. Further, multi-frame acknowledgement can be done.

31. For a k-bit numbering scheme, what is the range of sequence numbers used in sliding window protocol?

Ans: For k-bit numbering scheme, the total number of frames, N, in the sliding window can be given as follows (using modulo-k).

$$N = 2^k - 1$$

Hence the range of sequence numbers is: 0, 1, 2, and 3 ... $2^k - 1$

Version

32. Why do you need error detection?

Ans: As the signal is transmitted through a media, the signal gets corrupted because of noise and distortion. In other words, the media is not reliable. To achieve a reliable communication through this unreliable media, there is need for detecting the error in the signal so that suitable mechanism can be devised to take corrective actions.

33. How does NRZ-L differ from NRZ-I?

In the NRZ-L sequence, positive and negative voltages have specific meanings: positive for 0 and negative for 1. In the NRZ-I sequence, the voltages are meaningless.

Instead, the receiver looks for changes from one level to another as its basis for recognition of 1s.

34. What are the responsibilities of data link layer?

Specific responsibilities of data link layer include the following. a) Framing b) Physical addressing c) Flow control d) Error control e) Access control.

35. What are the ways to address the framing problem?

- Byte-Oriented Protocols(PPP)
- Bit-Oriented Protocols(HDLC)
- Clock-Based Framing(SONET)

36. What is the purpose of hamming code?

A hamming code can be designed to correct burst errors of certain lengths. So the simple strategy used by the hamming code to correct single bit errors must be redesigned to be applicable for multiple bit correction.

37.What is redundancy?

It is the error detecting mechanism, which means a shorter group of bits or extra bits may be appended at the destination of each unit.

38.Define flow control?

Flow control refers to a set of procedures used to restrict the amount of data. The sender can send before waiting for acknowledgment.

39.Mention the categories of flow control?

There are 2 methods have been developed to control flow of data across communication links. a) Stop and wait- send one from at a time. b) Sliding window- send several frames at a time.

40.What is a buffer?

Each receiving device has a block of memory called a buffer, reserved for storing incoming data until they are processed.